Fast Algorithms for $(\Delta + 1)$ -Edge-Coloring

Joint work with Anton Bernshteyn

Abhishek Dhawan

School of Mathematics Georgia Institute of Technology

34th Midwestern Conference on Combinatorics and Combinatorial Computing October 21, 2022

- 1 Background and Results
- 2 The Multi-Step Vizing Algorithm
- Proof of the Bounded Augmenting Subgraph



1 Background and Results

2 The Multi-Step Vizing Algorithm

Proof of the Bounded Augmenting Subgraph



Recall a proper k-edge-coloring is a function $\varphi : E(G) \to [k]$ such that $\varphi(e) \neq \varphi(f)$ when e and f share an endpoint. The chromatic index of a graph (denoted $\chi'(G)$) is the minimum value k such that G admits a proper k-edge-coloring.

Gr 4 / 16 Recall a proper *k*-edge-coloring is a function $\varphi : E(G) \rightarrow [k]$ such that $\varphi(e) \neq \varphi(f)$ when *e* and *f* share an endpoint.

The **chromatic index** of a graph (denoted $\chi'(G)$) is the minimum value k such that G admits a proper k-edge-coloring.

The following renowned result of Vizing provides a general bound on $\chi'(G)$.

Theorem (Vizing 1964)

For any simple graph G, $\chi'(G) \in \{\Delta(G), \Delta(G) + 1\}.$

Vizing's Theorem

Theorem (Vizing 1964)

For any simple graph G, $\chi'(G) \in \{\Delta(G), \Delta(G) + 1\}$.



 There is a deterministic (Δ + 1)-edge-coloring algorithm that runs in O(mn) time (Bollobás 1984; Rao, Dijkstra 1992; Misra, Gries 1992).

- There is a deterministic (Δ + 1)-edge-coloring algorithm that runs in O(mn) time (Bollobás 1984; Rao, Dijkstra 1992; Misra, Gries 1992).
- There is a deterministic $(\Delta + 1)$ -edge-coloring algorithm that runs in $O(m\sqrt{n \log n})$ time (Gabow, Nishizeki, Kariv, Leven, Terada 1985).

- There is a deterministic (Δ + 1)-edge-coloring algorithm that runs in O(mn) time (Bollobás 1984; Rao, Dijkstra 1992; Misra, Gries 1992).
- There is a deterministic $(\Delta + 1)$ -edge-coloring algorithm that runs in $O(m\sqrt{n \log n})$ time (Gabow, Nishizeki, Kariv, Leven, Terada 1985).
- There is a randomized $(\Delta + 1)$ -edge-coloring algorithm that runs in $O(m\sqrt{n})$ time with probability at least $1 e^{-\sqrt{m}}$ (Sinnamon 2019).

- There is a deterministic (Δ + 1)-edge-coloring algorithm that runs in O(mn) time (Bollobás 1984; Rao, Dijkstra 1992; Misra, Gries 1992).
- There is a deterministic $(\Delta + 1)$ -edge-coloring algorithm that runs in $O(m\sqrt{n \log n})$ time (Gabow, Nishizeki, Kariv, Leven, Terada 1985).
- There is a randomized $(\Delta + 1)$ -edge-coloring algorithm that runs in $O(m\sqrt{n})$ time with probability at least $1 e^{-\sqrt{m}}$ (Sinnamon 2019).
- There is a deterministic $(\Delta + 1)$ -edge-coloring algorithm that runs in $O(m\sqrt{n})$ time (Sinnamon 2019).

Gr

5/16

- There is a deterministic (Δ + 1)-edge-coloring algorithm that runs in poly(Δ) n² time (Bollobás 1984; Rao, Dijkstra 1992; Misra, Gries 1992).
- There is a deterministic $(\Delta + 1)$ -edge-coloring algorithm that runs in $\operatorname{poly}(\Delta) n^{3/2} \sqrt{\log n}$ time (Gabow, Nishizeki, Kariv, Leven, Terada 1985).
- There is a randomized $(\Delta + 1)$ -edge-coloring algorithm that runs in poly $(\Delta) n^{3/2}$ time with probability at least $1 e^{-\sqrt{n}}$ (Sinnamon 2019).
- There is a deterministic $(\Delta + 1)$ -edge-coloring algorithm that runs in poly $(\Delta) n^{3/2}$ time (Sinnamon 2019).

- There is a deterministic (Δ + 1)-edge-coloring algorithm that runs in poly(Δ) n² time (Bollobás 1984; Rao, Dijkstra 1992; Misra, Gries 1992).
- There is a deterministic $(\Delta + 1)$ -edge-coloring algorithm that runs in $\operatorname{poly}(\Delta) n^{3/2} \sqrt{\log n}$ time (Gabow, Nishizeki, Kariv, Leven, Terada 1985).
- There is a randomized (Δ + 1)-edge-coloring algorithm that runs in poly(Δ) n log n time with probability at least 1 1/poly(n) (Bernshteyn, D. 2022+).
- There is a deterministic $(\Delta + 1)$ -edge-coloring algorithm that runs in poly $(\Delta) n^{3/2}$ time (Sinnamon 2019).

Given a partial coloring φ , we say a subgraph $H \subseteq G$ is **augmenting** if there is at least one uncolored edge in H and there is a proper coloring ψ that can be obtained by modifying φ on the edges in H such that every edge in H is now colored.

Given a partial coloring φ , we say a subgraph $H \subseteq G$ is **augmenting** if there is at least one uncolored edge in H and there is a proper coloring ψ that can be obtained by modifying φ on the edges in H such that every edge in H is now colored.

For an arbitrary *n*-vertex graph *G* of maximum degree Δ and partial $(\Delta + 1)$ -edge-coloring φ , how small can *H* be?

Given a partial coloring φ , we say a subgraph $H \subseteq G$ is **augmenting** if there is at least one uncolored edge in H and there is a proper coloring ψ that can be obtained by modifying φ on the edges in H such that every edge in H is now colored.

For an arbitrary *n*-vertex graph G of maximum degree Δ and partial $(\Delta + 1)$ -edge-coloring φ , how small can H be?

Theorem

• There exists G, φ such that $e(H) = \Omega(\Delta \log n)$ for every augmenting subgraph H (Chang, He, Li, Pettie, Uitto 2018).

Given a partial coloring φ , we say a subgraph $H \subseteq G$ is **augmenting** if there is at least one uncolored edge in H and there is a proper coloring ψ that can be obtained by modifying φ on the edges in H such that every edge in H is now colored.

For an arbitrary *n*-vertex graph G of maximum degree Δ and partial $(\Delta + 1)$ -edge-coloring φ , how small can H be?

- There exists G, φ such that e(H) = Ω(Δ log n) for every augmenting subgraph H (Chang, He, Li, Pettie, Uitto 2018).
- For every G, φ there exists an augmenting subgraph H such that $e(H) \leq poly(\Delta)(\log n)^2$ (Bernshteyn 2021).

A distributed algorithm in the LOCAL model occurs in rounds, where in each round, every vertex performs some local computation and then broadcasts its results to its neighbors in G.



 There is a randomised distributed (Δ + Õ(√Δ))-edge-coloring algorithm that runs in poly(Δ, log log n) rounds (Chang, He, Li, Pettie, and Uitto 2018).

- There is a randomised distributed $(\Delta + \tilde{O}(\sqrt{\Delta}))$ -edge-coloring algorithm that runs in poly $(\Delta, \log \log n)$ rounds (Chang, He, Li, Pettie, and Uitto 2018).
- There is a deterministic distributed [3Δ/2]-edge-coloring algorithm that runs in poly(Δ) (log n)⁸ rounds (Ghaffari, Kuhn, Maus, and Uitto 2018).

- There is a randomised distributed $(\Delta + \tilde{O}(\sqrt{\Delta}))$ -edge-coloring algorithm that runs in poly $(\Delta, \log \log n)$ rounds (Chang, He, Li, Pettie, and Uitto 2018).
- There is a deterministic distributed [3Δ/2]-edge-coloring algorithm that runs in poly(Δ) (log n)⁸ rounds (Ghaffari, Kuhn, Maus, and Uitto 2018).
- There is a randomised distributed (Δ + 2)-edge-coloring algorithm that runs in poly(Δ) (log n)³ rounds (Su, Vu 2019).

- There is a randomised distributed $(\Delta + \tilde{O}(\sqrt{\Delta}))$ -edge-coloring algorithm that runs in poly $(\Delta, \log \log n)$ rounds (Chang, He, Li, Pettie, and Uitto 2018).
- There is a deterministic distributed [3Δ/2]-edge-coloring algorithm that runs in poly(Δ) (log n)⁸ rounds (Ghaffari, Kuhn, Maus, and Uitto 2018).
- There is a randomised distributed (Δ + 2)-edge-coloring algorithm that runs in poly(Δ) (log n)³ rounds (Su, Vu 2019).
- There is a randomised distributed (Δ + 1)-edge-coloring algorithm that runs in poly(Δ) (log n)⁵ rounds (Bernshteyn 2021).

- There is a randomised distributed $(\Delta + \tilde{O}(\sqrt{\Delta}))$ -edge-coloring algorithm that runs in poly $(\Delta, \log \log n)$ rounds (Chang, He, Li, Pettie, and Uitto 2018).
- There is a deterministic distributed [3Δ/2]-edge-coloring algorithm that runs in poly(Δ) (log n)⁸ rounds (Ghaffari, Kuhn, Maus, and Uitto 2018).
- There is a randomised distributed (Δ + 2)-edge-coloring algorithm that runs in poly(Δ) (log n)³ rounds (Su, Vu 2019).
- There is a randomised distributed (Δ + 1)-edge-coloring algorithm that runs in poly(Δ) (log n)⁵ rounds (Bernshteyn 2021).
- There is a deterministic distributed (Δ + 1)-edge-coloring algorithm that runs in poly(Δ, log log n) (log n)¹¹ rounds (Bernshteyn 2021).

Theorem (Bernshteyn, D. 2022+)

Let G be an n-vertex graph of maximum degree Δ and let φ be a partial $(\Delta + 1)$ -edge-coloring. For any uncolored edge e, there is an augmenting subgraph H containing e such that $e(H) \leq poly(\Delta) \log n$.

Theorem (Bernshteyn, D. 2022+)

There exists a randomized (resp. deterministic) distributed algorithm in the LOCAL model that computes a proper $(\Delta + 1)$ -edge-coloring of an n-vertex graph of maximum degree Δ in poly $(\Delta)(\log n)^3$ rounds (resp. poly $(\Delta, \log \log n)(\log n)^6$).

Theorem (Bernshteyn, D. 2022+)

There exists a randomized sequential algorithm that computes a proper ($\Delta + 1$)-edge-coloring of an n-vertex graph of maximum degree Δ in poly(Δ) n time with probability at least $1 - 1/\Delta^n$.

Background and Results

2 The Multi-Step Vizing Algorithm

3 Proof of the Bounded Augmenting Subgraph

4 Summary

Idea (Grebík, Pikhurko 2020; Bernshteyn 2021)

• If P is too long, consider a random initial segment of P, shift and try again.



Idea (Grebík, Pikhurko 2020; Bernshteyn 2021)

- If P is too long, consider a random initial segment of P, shift and try again.
- Repeat until the final path is short.



Non-Intersecting Vizing Chains

Idea (Grebík, Pikhurko 2020; Bernshteyn 2021)

- If P is too long, consider a random initial segment of P, shift and try again.
- Repeat until the final path is short, while guaranteeing the chain is non-intersecting.



(c) Intersection between F_i , P_j at a vertex v. (d) Intersection between F_i , P_j at a vertex v.

(d) Intersection between F_i, F_i at a vertex v

- Input: A graph G, a partial coloring φ, an uncolored edge e = xy, a vertex x ∈ e and a parameter ℓ ∈ N.
- Output: A non-intersecting augmenting multi-step Vizing chain *C* such that Start(*C*) = *xy*.

Cr 11 / 16

- Input: A graph G, a partial coloring φ, an uncolored edge e = xy, a vertex x ∈ e and a parameter ℓ ∈ N.
- Output: A non-intersecting augmenting multi-step Vizing chain C such that Start(C) = xy.

Step 1: First Chain

Find the first Vizing Chain F + P on C.



- Input: A graph G, a partial coloring φ, an uncolored edge e = xy, a vertex x ∈ e and a parameter ℓ ∈ N.
- Output: A non-intersecting augmenting multi-step Vizing chain C such that Start(C) = xy.

Step 2: Iterate

Let C (in black) and F + P (in red) be the current chain and candidate chain at the start of the iteration.



The Multi-Step Vizing Algorithm

- Input: A graph G, a partial coloring φ, an uncolored edge e = xy, a vertex x ∈ e and a parameter ℓ ∈ N.
- Output: A non-intersecting augmenting multi-step Vizing chain C such that Start(C) = xy.

Step 2: Iterate

Let C (in black) and F + P (in red) be the current chain and candidate chain after truncation. Let $\tilde{F} + \tilde{P}$ (in blue) be the next step chain.

Case 1: Non-intersecting.



The Multi-Step Vizing Algorithm

- Input: A graph G, a partial coloring φ, an uncolored edge e = xy, a vertex x ∈ e and a parameter ℓ ∈ N.
- Output: A non-intersecting augmenting multi-step Vizing chain C such that Start(C) = xy.

Step 2: Iterate

Let C (in black) and F + P (in red) be the current chain and candidate chain after truncation. Let $\tilde{F} + \tilde{P}$ (in blue) be the next step chain.

Case 2: Intersecting.



Background and Results

2 The Multi-Step Vizing Algorithm

Proof of the Bounded Augmenting Subgraph

4 Summary

Theorem (Bernshteyn, D. 2022+)

For $\ell = \text{poly}(\Delta)$ of large enough degree, the Multi-Step Vizing Algorithm terminates in $O(\log n)$ steps with probability at least 1 - 1/poly(n).

We utilise the entropy compression argument developed by Moser and Tardos in 2010.

We utilise the entropy compression argument developed by Moser and Tardos in 2010.

Some Notable Applications

- For every n ≥ 1 and a sequence of sets L₁,..., L_n of size at least 4, there is a non-repetitive sequence chosen from L₁,..., L_n (Grytczuk, Kozik, Micek 2011).
- For every graph G of maximum degree Δ, there is a non-repetitive coloring using at most (1 + o(1))Δ² colors (Dujmović, Joret, Kozik, Wood 2014; Rosenfeld 2020).
- The list chromatic number of triangle free graphs is at most (1 + o(1))Δ/log Δ asymptotically (Molloy 2017).

Termination of the Multi-Step Vizing Algorithm

• Suppose your process runs for t steps making random choices $\omega_1, \ldots, \omega_t$.

- Suppose your process runs for t steps making random choices $\omega_1, \ldots, \omega_t$.
- Define a record for each step r_1, \ldots, r_t such that given the record and the output \mathcal{O}_t after t steps, we can recover $\omega_1, \ldots, \omega_t$ as well as the outputs \mathcal{O}_j for each $1 \leq j < t$.

- Suppose your process runs for t steps making random choices $\omega_1, \ldots, \omega_t$.
- Define a record for each step r₁,..., r_t such that given the record and the output O_t after t steps, we can recover ω₁,..., ω_t as well as the outputs O_j for each 1 ≤ j < t.
- We have

 $\mathbb{P}[\mathsf{Failure in } t \text{ steps}] \leq \frac{\#(\mathsf{record},\mathsf{output})\mathsf{-pairs}}{\mathsf{Amount of randomness generated}}$

Cr 13 / 16

- Suppose your process runs for t steps making random choices $\omega_1, \ldots, \omega_t$.
- Define a record for each step r₁,..., r_t such that given the record and the output O_t after t steps, we can recover ω₁,..., ω_t as well as the outputs O_j for each 1 ≤ j < t.
- We have

$$\mathbb{P}[\mathsf{Failure in } t \text{ steps}] \leq \frac{\#(\mathsf{record},\mathsf{output})\mathsf{-pairs}}{\ell^t}$$

The Record

Each entry of our record is of the form (d_i, k_i) . Assuming the process doesn't terminate, we define the *i*-th entry as follows:

The Record

Each entry of our record is of the form (d_i, k_i) . Assuming the process doesn't terminate, we define the *i*-th entry as follows:

() If the second step chain found is non-intersecting, we let $d_i = 1$, $k_i =$ blank.



Ger

The Record

Each entry of our record is of the form (d_i, k_i) . Assuming the process doesn't terminate, we define the *i*-th entry as follows:

- **()** If the second step chain found is non-intersecting, we let $d_i = 1$, $k_i =$ blank.
- If the second step chain found intersects C, we let d_i = -k and let k_i denote the (k + 1)-step chain causing the truncation.



A subtle counting argument shows that the number of k-step chains ending at a vertex x is at most $poly(\Delta)^k$. This observation helps in bounding the number of (record, output)-pairs.

Lemma

Assuming the process doesn't terminate, there are at most $n(poly(\Delta) \ell)^{t/2}$ (record, output)-pairs after t steps of the Multi-Step Vizing Algorithm. A subtle counting argument shows that the number of k-step chains ending at a vertex x is at most $poly(\Delta)^k$. This observation helps in bounding the number of (record, output)-pairs.

Lemma

Assuming the process doesn't terminate, there are at most $n(poly(\Delta) \ell)^{t/2}$ (record, output)-pairs after t steps of the Multi-Step Vizing Algorithm.

It follows that

$$\mathbb{P}[\mathsf{Failure}] \leq rac{n(\mathsf{poly}(\Delta)\,\ell)^{t/2}}{\ell^t}.$$

For $\ell \sim \text{poly}(\Delta)$ and $t \sim \log n$, the above is at most 1/poly(n).

Cr 13 / 16

- Background and Results
- 2 The Multi-Step Vizing Algorithm
- 3 Proof of the Bounded Augmenting Subgraph



• The upper bound on the size of an augmenting subgraph matches the lower bound asymptotically.

- The upper bound on the size of an augmenting subgraph matches the lower bound asymptotically.

- The upper bound on the size of an augmenting subgraph matches the lower bound asymptotically.
- **②** Runtime of the distributed algorithms matches those for $(\Delta + 2)$ -edge-coloring.
- The sequential coloring algorithm matches the lower bound asymptotically.

- The upper bound on the size of an augmenting subgraph matches the lower bound asymptotically.
- Runtime of the distributed algorithms matches those for (Δ + 2)-edge-coloring.
- The sequential coloring algorithm matches the lower bound asymptotically.
- Moreover, the result implies that the average size of an augmenting subgraph found using the Multi-Step Vizing Algorithm is independent of *n*.

- The upper bound on the size of an augmenting subgraph matches the lower bound asymptotically.
- Runtime of the distributed algorithms matches those for (Δ + 2)-edge-coloring.
- The sequential coloring algorithm matches the lower bound asymptotically.
- Moreover, the result implies that the average size of an augmenting subgraph found using the Multi-Step Vizing Algorithm is independent of *n*.
- **O** Unconventional use of the entropy compression argument.

Thank you!