

Computing the ground state and dynamics of the nonlinear Schrödinger equation with nonlocal interactions via the nonuniform FFT



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ABSTRACT

We present efficient and accurate numerical methods for computing the ground state and dynamics of the nonlinear Schrödinger equation (NLSE) with nonlocal interactions based on a fast and accurate evaluation of the long-range interactions via the nonuniform fast Fourier transform (NUFFT). We begin with a review of the fast and accurate NUFFT based method in [29] for nonlocal interactions where the singularity of the Fourier symbol of the interaction kernel at the origin can be canceled by switching to spherical or polar coordinates. We then extend the method to compute other nonlocal interactions whose Fourier symbols have stronger singularity at the origin that cannot be canceled by the coordinate transform. Many of these interactions do not decay at infinity in the physical space, which adds another layer of complexity since it is more difficult to impose the correct artificial boundary conditions for the truncated bounded computational domain. The performance of our method against other existing methods is illustrated numerically, with particular attention on the effect of the size of the computational domain in the physical space. Finally, to study the ground state and dynamics of the NLSE, we propose efficient and accurate numerical methods by combining the NUFFT method for potential evaluation with the normalized gradient flow using backward Euler Fourier pseudospectral discretization and time-splitting Fourier pseudospectral method, respectively. Extensive numerical comparisons are carried out between these methods and other existing methods for computing the ground state and dynamics of the NLSE with various nonlocal interactions. Numerical results show that our scheme performs much better than those existing methods in terms of both accuracy and efficiency.

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1. Introduction

In this paper, we present efficient and accurate numerical methods and compare them with existing numerical methods for computing the ground state and dynamics of the nonlinear Schrödinger equation (NLSE). In dimensionless form, the NLSE with a nonlocal (long-range) interaction in d dimensions ($d = 3, 2, 1$) is

$$i\partial_t\psi(\mathbf{x}, t) = \left[-\frac{1}{2}\Delta + V(\mathbf{x}) + \beta\varphi(\mathbf{x}, t) \right] \psi(\mathbf{x}, t), \quad \mathbf{x} \in \mathbb{R}^d, \quad t > 0, \tag{1.1}$$

$$\varphi(\mathbf{x}, t) = \left(U * |\psi|^2 \right) (\mathbf{x}, t), \quad \mathbf{x} \in \mathbb{R}^d, \quad t \geq 0; \tag{1.2}$$

with the initial data

$$\psi(\mathbf{x}, t = 0) = \psi_0(\mathbf{x}), \quad \mathbf{x} \in \mathbb{R}^d. \tag{1.3}$$

Here, t is time, \mathbf{x} is the spatial coordinates, $\psi(\mathbf{x}, t)$ is the complex-valued wave-function, $V(\mathbf{x})$ is a given real-valued external potential, β is a dimensionless interaction constant (positive for repulsive interaction and negative for attractive interaction), and $\varphi(\mathbf{x}, t)$ is a real-valued nonlocal (long-range) interaction which is defined as the convolution of an interaction kernel $U(\mathbf{x})$ and the density function $\rho(\mathbf{x}, t) = |\psi(\mathbf{x}, t)|^2$. The NLSE with the nonlocal interaction (1.1)–(1.2) has been widely used in modeling a variety of problems arising from quantum physics and chemistry to materials science and biology. It is nonlinear, dispersive and time transverse invariant, i.e., if $V(\mathbf{x}) \rightarrow V(\mathbf{x}) + \alpha$ and $\varphi(\mathbf{x}, t) \rightarrow \varphi(\mathbf{x}, t) + \delta$, then $\psi(\mathbf{x}, t) \rightarrow \psi(\mathbf{x}, t)e^{-i(\alpha+\beta\delta)t}$, which immediately implies that the physical observables such as the density $\rho(\mathbf{x}, t)$ are kept unchanged. In addition, it conserves the mass and energy defined as follows:

$$N(\psi(\cdot, t)) := \int_{\mathbb{R}^d} |\psi(\mathbf{x}, t)|^2 d\mathbf{x} \equiv \int_{\mathbb{R}^d} |\psi(\mathbf{x}, 0)|^2 d\mathbf{x} = \int_{\mathbb{R}^d} |\psi_0(\mathbf{x})|^2 d\mathbf{x} = N(\psi_0), \quad t \geq 0, \tag{1.4}$$

$$E(\psi(\cdot, t)) := \int_{\mathbb{R}^d} \left[\frac{1}{2} |\nabla\psi(\mathbf{x}, t)|^2 + V(\mathbf{x})|\psi(\mathbf{x}, t)|^2 + \frac{1}{2} \beta \varphi(\mathbf{x}, t)|\psi(\mathbf{x}, t)|^2 \right] d\mathbf{x} \equiv E(\psi_0). \tag{1.5}$$

One of the most important nonlocal interactions in applications is the Coulomb interaction whose interaction kernel in 3D/2D is given as

$$U_{\text{Coul}}(\mathbf{x}) = \begin{cases} \frac{1}{4\pi|\mathbf{x}|}, \\ \frac{1}{2\pi|\mathbf{x}|}, \end{cases} \iff \widehat{U}_{\text{Coul}}(\mathbf{k}) = \begin{cases} \frac{1}{|\mathbf{k}|^2}, & d = 3, \\ \frac{1}{|\mathbf{k}|}, & d = 2, \end{cases} \quad \mathbf{x}, \mathbf{k} \in \mathbb{R}^d, \tag{1.6}$$

where $\widehat{f}(\mathbf{k}) = \int_{\mathbb{R}^d} f(\mathbf{x}) e^{-i\mathbf{k}\cdot\mathbf{x}} d\mathbf{x}$ is the Fourier transform of $f(\mathbf{x})$ for $\mathbf{x}, \mathbf{k} \in \mathbb{R}^d$. In 3D, the Coulomb interaction kernel $U_{\text{Coul}}(\mathbf{x})$ is exactly the Green’s function of the Laplace operator and thus the nonlocal Coulomb interaction φ in (1.2) also satisfies the Poisson equation in 3D

$$-\Delta\varphi(\mathbf{x}, t) = |\psi(\mathbf{x}, t)|^2, \quad \mathbf{x} \in \mathbb{R}^3, \quad \lim_{|\mathbf{x}| \rightarrow \infty} \varphi(\mathbf{x}, t) = 0, \quad t \geq 0. \tag{1.7}$$

In this case, (1.1)–(1.2) is also referred to as the 3D Schrödinger–Poisson system (SPS) which was derived from the linear Schrödinger equation for a many-body (e.g., N electrons) quantum system with binary Coulomb interaction between different electrons via the “mean field limit” [12,13,23]. It has important applications in modeling semiconductor devices and calculating electronic structures in materials simulation and design. On the other hand, the Coulomb interaction kernel $U(\mathbf{x})$ in 2D is the Green’s function of the square-root-Laplace operator instead of the Laplace operator and thus the nonlocal Coulomb interaction φ in (1.2) also satisfies the fractional Poisson equation in 2D

$$\sqrt{-\Delta}\varphi(\mathbf{x}, t) = |\psi(\mathbf{x}, t)|^2, \quad \mathbf{x} \in \mathbb{R}^2, \quad \lim_{|\mathbf{x}| \rightarrow \infty} \varphi(\mathbf{x}, t) = 0, \quad t \geq 0. \tag{1.8}$$

In this case, (1.1)–(1.2) could be obtained from the 3D SPS under an infinitely strong external confinement in the z -direction [9,14]. This model could be used for modeling 2D materials such as graphene and “electron sheets” [20].

Another type of interaction from applications is that the interaction kernel $U(\mathbf{x})$ is taken as the Green’s function of the Laplace operator in 3D/2D/1D [41]

$$U_{\text{Lap}}(\mathbf{x}) = \begin{cases} \frac{1}{4\pi|\mathbf{x}|}, & d = 3, \\ -\frac{1}{2\pi} \ln|\mathbf{x}|, & d = 2, \\ -\frac{1}{2}|\mathbf{x}|, & d = 1, \end{cases} \iff \widehat{U}_{\text{Lap}}(\mathbf{k}) = \frac{1}{|\mathbf{k}|^2}, \quad \mathbf{x}, \mathbf{k} \in \mathbb{R}^d. \tag{1.9}$$

When $d = 3$, $U_{\text{Lap}}(\mathbf{x}) = U_{\text{Coul}}(\mathbf{x})$ for $\mathbf{x} \in \mathbb{R}^3$. When $d = 2$, the nonlocal interaction φ in (1.2) with (1.9) satisfies the Poisson equation in 2D with the far-field condition

$$-\Delta\varphi(\mathbf{x}, t) = |\psi(\mathbf{x}, t)|^2, \quad \mathbf{x} \in \mathbb{R}^2, \quad \lim_{|\mathbf{x}| \rightarrow \infty} \left[\varphi(\mathbf{x}, t) + \frac{C_0}{2\pi} \ln|\mathbf{x}| \right] = 0, \quad t \geq 0; \tag{1.10}$$

and when $d = 1$ with $\mathbf{x} = x$, it satisfies the Poisson equation in 1D with the far-field condition

$$-\partial_{xx}\varphi(x, t) = |\psi(x, t)|^2, \quad x \in \mathbb{R}, \quad \lim_{x \rightarrow \pm\infty} \left[\varphi(x, t) + \frac{1}{2} (C_0|x| \mp C_1) \right] = 0, \quad t \geq 0, \quad (1.11)$$

where $C_0 = \int_{\mathbb{R}^d} |\psi(\mathbf{x}, t)|^2 d\mathbf{x} = \widehat{|\psi|^2}(\mathbf{0}, t) \equiv \int_{\mathbb{R}^d} |\psi_0(\mathbf{x})|^2 d\mathbf{x} = |\widehat{\psi_0}|^2(\mathbf{0}) = N(\psi_0)$ and $C_1 = \int_{\mathbb{R}} x |\psi(x, t)|^2 dx = \widehat{(x|\psi|^2)}(\mathbf{0}, t)$, which indicate that the nonlocal interaction $\varphi(\mathbf{x}, t) \rightarrow -\infty$ as $|\mathbf{x}| \rightarrow \infty$ in 2D/1D. In fact, when $d = 2$ or $d = 1$, (1.1)–(1.2) with (1.9) is also referred to as the 2D or 1D SPS. They could be obtained from the 3D SPS by integrating the 3D Coulomb interaction kernel $U_{\text{Coul}}(\mathbf{x})$ along the z -line or (y, z) -plane under the assumption that the electrons are uniformly distributed in one or two spatial dimensions, respectively. The 2D/1D SPS is usually used for modeling 2D “electron sheets” and 1D “quantum wires”, respectively, as well as lower dimensions semiconductor devices [32].

Recently, the following nonlocal interaction kernels in 2D/1D were obtained from the 3D SPS under strongly confining external potentials in the z -direction and (y, z) -plane, respectively

$$U_{\text{Con}}^\varepsilon(\mathbf{x}) = \begin{cases} \frac{2}{(2\pi)^{3/2}} \int_0^\infty \frac{e^{-\frac{u^2}{2}}}{\sqrt{|\mathbf{x}|^2 + \varepsilon^2 u^2}} du, & \mathbf{x} \in \mathbb{R}^2 \\ \frac{1}{4} \int_0^\infty \frac{e^{-\frac{u}{2}}}{\sqrt{|\mathbf{x}|^2 + \varepsilon^2 u}} du, & \mathbf{x} \in \mathbb{R} \end{cases} \iff \widehat{U}_{\text{Con}}^\varepsilon(\mathbf{k}) = \begin{cases} \frac{2}{\pi} \int_0^\infty \frac{e^{-\frac{\varepsilon^2 s^2}{2}}}{|\mathbf{k}|^2 + s^2} ds, & \mathbf{k} \in \mathbb{R}^2, \\ \frac{1}{2} \int_0^\infty \frac{e^{-\varepsilon^2 s/2}}{|\mathbf{k}|^2 + s} ds, & \mathbf{k} \in \mathbb{R}, \end{cases} \quad (1.12)$$

where $0 < \varepsilon \ll 1$ is a dimensionless constant describing the ratio of the anisotropic confinement in different directions in the original 3D SPS [9]. In this case, the convolution (1.2) for the nonlocal interaction φ can no longer be re-formulated into a partial differential equation. For other nonlocal interactions considered in quantum chemistry and dipole Bose–Einstein condensation, e.g., the dipole–dipole interaction, we refer to [4,5,17,29] and references therein.

The ground state ϕ_g of the NLSE is defined as follows:

$$\phi_g = \underset{\phi \in S}{\operatorname{argmin}} E(\phi), \quad \text{where } S := \{\phi(\mathbf{x}) \mid \|\phi\|^2 := \int_{\mathbb{R}^d} |\phi(\mathbf{x})|^2 d\mathbf{x} = 1, E(\phi) < \infty\}. \quad (1.13)$$

For the existence, uniqueness and properties of the ground state as well as the well-posedness and dynamical properties of the NLSE, we refer to [36,18,15,4,14,19,33,34] and references therein.

In order to numerically compute the ground state of (1.13) and the dynamics of (1.1)–(1.2), one of the key difficulties is to efficiently and accurately evaluate the nonlocal interaction (1.2) for a given density $\rho = |\psi|^2$. Note that

$$\varphi(\mathbf{x}, t) = \int_{\mathbb{R}^d} U(\mathbf{x} - \mathbf{y}) \rho(\mathbf{y}, t) d\mathbf{y} = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \widehat{U}(\mathbf{k}) \widehat{\rho}(\mathbf{k}, t) e^{i\mathbf{k}\cdot\mathbf{x}} d\mathbf{k}, \quad \mathbf{x} \in \mathbb{R}^d, \quad t \geq 0, \quad (1.14)$$

it is natural to evaluate $\varphi(\mathbf{x}, t)$ via the standard fast Fourier transform (FFT) using a uniform grid on a bounded computational domain Ω [11]. However, the accuracy of this approach is hampered due to the singularity of $\widehat{U}(\mathbf{k})$ at the origin. Indeed, for the 3D Coulomb interaction, this method is equivalent to solving the Poisson equation (1.7) on Ω with periodic boundary condition via the Fourier spectral method. It is easy to see that this approach is inconsistent due to the inappropriate periodic boundary condition:

$$0 < \int_{\Omega} |\psi(\mathbf{x}, t)|^2 d\mathbf{x} = - \int_{\Omega} \Delta \varphi(\mathbf{x}, t) d\mathbf{x} = - \int_{\partial\Omega} \frac{\partial \varphi}{\partial \mathbf{n}} ds = 0. \quad (1.15)$$

Thus, this approach suffers from no convergence in terms of the mesh size of partitioning any fixed Ω (a phenomenon known as “numerical locking” in the literature); and its convergence is very slow, e.g., linearly convergent for the 3D/2D Coulomb interaction, in terms of the size of Ω because φ decays like $\frac{1}{|\mathbf{x}|}$. To overcome this “numerical locking”, a numerical method was proposed by imposing the homogeneous Dirichlet boundary condition on $\partial\Omega$, and then solving the truncated problem via the discrete sine transform (DST) [6,17,41]. This method avoids numerically the singularity of $\widehat{U}(\mathbf{k})$ at the origin and thus significantly improves the accuracy in the evaluation of the Coulomb interaction potential. However, the truncation error of this method still decays only linearly in terms of the size of Ω due to the slow decaying property of the Coulomb potential. Thus when high accuracy is required, the bounded computational domain Ω must be chosen very large, which increases significantly the computational cost in both memory and CPU time for evaluating the nonlocal interaction potential (1.2) and solving the NLSE (1.1). Moreover, for the purpose of solving the NLSE, a much smaller computational domain actually suffices since the wave-function ψ decays exponentially fast when $|\mathbf{x}| \rightarrow \infty$ in most applications. We would also like to point out that this method could not be extended to the cases where the potential in (1.1) either does not decay at infinity (for example, 1D/2D cases of (1.9)) or cannot be converted to a PDE problem (as in (1.12)).

Recently, a fast and accurate NUFFT based method [29] was proposed to compute the Coulomb interaction (1.6) in 3D/2D. The key observation there is that the singularity in the Fourier transform of the interaction kernel $\widehat{U}(\mathbf{k})$ at the origin can be canceled out with the Jacobian in spherical or polar coordinates, thus making the integrand in (1.14) smooth. The integral is then approximated via a high-order quadrature and the resulting discrete summation is evaluated via the

NUFFT. The algorithm has $O(N \log N)$ complexity with N the total number of unknowns in the physical space and achieves very high accuracy for the evaluation of Coulomb interactions [29]. The main aims of this paper are fourfold: (i) to extend the algorithm in [29] to evaluate the nonlocal interactions whose Fourier symbols have stronger singularity at the origin which cannot be canceled by coordinate transform; (ii) to compare numerically the newly developed NUFFT based method with those existing methods for nonlocal interaction evaluation; (iii) to propose efficient and accurate numerical methods for computing the ground state and dynamics of the NLSE (1.1)–(1.2) by incorporating the NUFFT based algorithm into the normalized gradient flow method and the time-splitting Fourier pseudospectral method, respectively, and (iv) to compare these two new schemes with those existing ones for computing the ground state and dynamics of the NLSE.

The paper is organized as follows. In Section 2, the NUFFT based algorithm in [29] for the evaluation of Coulomb interaction is reviewed and then extended for the case of general nonlocal interaction (1.2) whose kernel is taken as either (1.9) or (1.12). Then, efficient and accurate numerical methods are proposed respectively in Section 3 and Section 4 to compute the ground state and dynamics of the NLSE (1.1)–(1.2). Finally, some concluding remarks are drawn in Section 5.

2. An algorithm for the evaluation of the nonlocal interaction via the NUFFT

In this section, we will propose a fast and accurate evaluation of the nonlocal interaction

$$u(\mathbf{x}) = (U * \rho)(\mathbf{x}) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \widehat{U}(\mathbf{k}) \widehat{\rho}(\mathbf{k}) e^{i\mathbf{k}\cdot\mathbf{x}} d\mathbf{k}, \quad \mathbf{x} \in \mathbb{R}^d, \quad d = 3, 2, 1, \quad (2.1)$$

where $\rho(\mathbf{x})$ satisfying $\widehat{\rho}(\mathbf{0}) = \int_{\mathbb{R}^d} \rho(\mathbf{x}) d\mathbf{x} > 0$ is a given nonnegative smooth density function that decays rapidly at far field. We will first briefly review the algorithm in [29] for fast and accurate evaluation of the Coulomb interactions, and then extend it to the cases where $U(\mathbf{x})$ in (2.1) is taken as either (1.9) or (1.12).

2.1. Coulomb interactions in 3D/2D

When $U(\mathbf{x})$ reads as (1.6), by truncating the integration domain in (2.1) into a bounded domain and adopting the spherical/polar coordinates in 3D/2D in the Fourier (or phase) space, we have [29]

$$\begin{aligned} u(\mathbf{x}) &= \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} e^{i\mathbf{k}\cdot\mathbf{x}} \widehat{U}_{\text{Coul}}(\mathbf{k}) \widehat{\rho}(\mathbf{k}) d\mathbf{k} = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \frac{1}{|\mathbf{k}|^{d-1}} e^{i\mathbf{k}\cdot\mathbf{x}} \widehat{\rho}(\mathbf{k}) d\mathbf{k} \\ &\approx \frac{1}{(2\pi)^d} \int_{|\mathbf{k}| \leq P} \frac{1}{|\mathbf{k}|^{d-1}} e^{i\mathbf{k}\cdot\mathbf{x}} \widehat{\rho}(\mathbf{k}) d\mathbf{k} \\ &= \frac{1}{(2\pi)^d} \begin{cases} \int_0^P \int_0^\pi \int_0^{2\pi} e^{i\mathbf{k}\cdot\mathbf{x}} \widehat{\rho}(\mathbf{k}) \sin\theta d|\mathbf{k}| d\theta d\phi, & d = 3, \\ \int_0^P \int_0^{2\pi} e^{i\mathbf{k}\cdot\mathbf{x}} \widehat{\rho}(\mathbf{k}) d|\mathbf{k}| d\phi, & d = 2, \end{cases} \quad \mathbf{x} \in \Omega \subset \mathbb{R}^d. \end{aligned} \quad (2.2)$$

Here, $P = O(1/\varepsilon_0)^{1/n}$, $\varepsilon_0 > 0$ is the prescribed precision (e.g., $\varepsilon_0 = 10^{-10}$), and n is the decaying rate of $\widehat{\rho}(\mathbf{k})$ at infinity (i.e., $\widehat{\rho}(\mathbf{k}) = O(|\mathbf{k}|^{-n})$ as $|\mathbf{k}| \rightarrow \infty$). Correspondingly, we choose a bounded domain Ω large enough such that the truncation error of $\rho(\mathbf{x})$ is negligible. It is easy to see that the singularity of the integrand at the origin in phase space is removed in spherical or polar coordinates. Thus, the above integral can be discretized using high order quadratures and the resulting summation can be evaluated efficiently via the NUFFT. This leads to an $O(N \log N) + O(M)$ algorithm where N is the total number of equispaced points in the physical space and M is the number of nonequispaced points in the Fourier space. However, although M is roughly the same order as N , the constant in front of $O(M)$ (e.g., 24^d for 12-digit accuracy) is much greater than the constant in front of $O(N \log N)$. This makes the algorithm considerably slower than the regular FFT, especially for three dimensional problems.

An improved algorithm is developed to reduce the computational cost in [29]. First, the integral in (2.2) is further split into two parts via a simple partition of unity:

$$\begin{aligned} u(\mathbf{x}) &\approx \frac{1}{(2\pi)^d} \int_{|\mathbf{k}| \leq P} \frac{1}{|\mathbf{k}|^{d-1}} e^{i\mathbf{k}\cdot\mathbf{x}} \widehat{\rho}(\mathbf{k}) d\mathbf{k} \\ &= \frac{1}{(2\pi)^d} \int_{|\mathbf{k}| \leq P} e^{i\mathbf{k}\cdot\mathbf{x}} \frac{1 - p_d(\mathbf{k})}{|\mathbf{k}|^{d-1}} \widehat{\rho}(\mathbf{k}) d\mathbf{k} + \frac{1}{(2\pi)^d} \int_{|\mathbf{k}| \leq P} e^{i\mathbf{k}\cdot\mathbf{x}} \frac{p_d(\mathbf{k})}{|\mathbf{k}|^{d-1}} \widehat{\rho}(\mathbf{k}) d\mathbf{k} \\ &\approx \frac{1}{(2\pi)^d} \int_{\mathcal{D}} e^{i\mathbf{k}\cdot\mathbf{x}} w_d(\mathbf{k}) \widehat{\rho}(\mathbf{k}) d\mathbf{k} + \frac{1}{(2\pi)^d} \int_{|\mathbf{k}| \leq P} e^{i\mathbf{k}\cdot\mathbf{x}} \frac{p_d(\mathbf{k})}{|\mathbf{k}|^{d-1}} \widehat{\rho}(\mathbf{k}) d\mathbf{k} := I_1 + I_2, \quad \mathbf{x} \in \Omega. \end{aligned} \quad (2.3)$$

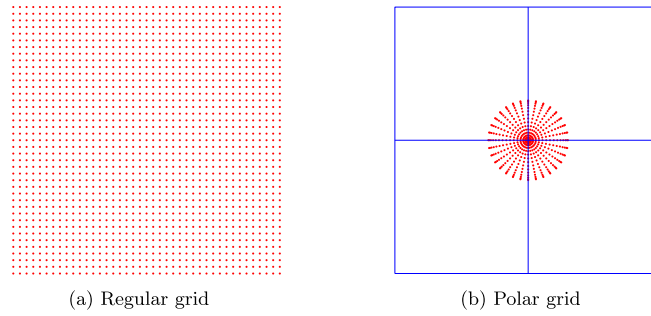


Fig. 1. Two grids used in the Fourier domain in the improved algorithm in [29]: the regular grid on the left panel is used to compute I_1 in (2.3) via the regular FFT; while the polar grid (confined in a small region centered at the origin) on the right panel is used to compute I_2 in (2.3) via the NUFFT. Note that the number of points in the polar grid is $O(1)$, thus keeping the interpolation cost in NUFFT minimal.

Here, $\mathcal{D} = \{\mathbf{k} = (k_1, \dots, k_d)^T \mid -P \leq k_j \leq P, j = 1, \dots, d\}$ is a rectangular domain containing the ball B , the function $p_d(\mathbf{k})$ is chosen such that it is a C^∞ function that decays exponentially fast as $|\mathbf{k}| \rightarrow \infty$ and the function $w_d(\mathbf{k}) := \frac{1-p_d(\mathbf{k})}{|\mathbf{k}|^{d-1}}$ is smooth for $\mathbf{k} \in \mathbb{R}^d$. We remark here that similar ideas by partition of unity to remove the singularity were also used for surface integral [16,22,24–27].

With this $p_d(\mathbf{k})$, I_1 can be computed via the regular FFT and I_2 can be evaluated via the NUFFT with a fixed (much fewer) number of irregular points in the Fourier space (see Fig. 1). Thus the interpolation cost in the NUFFT is reduced to $O(1)$ and the cost of the overall algorithm is comparable to that of the regular FFT, with an oversampling factor (2^3 for 3D problems and 2^2-3^2 for 2D problems) in front of $O(N \log N)$.

2.2. Poisson potentials in 2D/1D

When $U(\mathbf{x})$ is taken as (1.9) in 2D/1D, the algorithm discussed in the previous section cannot be applied directly to evaluate the Poisson potential $u(\mathbf{x})$ due to the stronger singularity of $\widehat{U}_{\text{Lap}}(\mathbf{k})$ at the origin. Obviously, the Poisson potential $u(\mathbf{x})$ satisfies the Poisson equation $-\Delta u(\mathbf{x}) = \rho(\mathbf{x})$ with the far field condition

$$\lim_{|\mathbf{x}| \rightarrow \infty} \left[u(\mathbf{x}) + \frac{\widehat{\rho}(\mathbf{0})}{2\pi} \ln |\mathbf{x}| \right] = 0 \quad (2.4)$$

for 2D problems and

$$\lim_{x \rightarrow \pm\infty} \left[u(x) + \frac{1}{2} \left(\widehat{\rho}(0)|x| \mp \widehat{(x\rho)}(0) \right) \right] = 0 \quad (2.5)$$

for 1D problems, respectively.

Let us first consider the evaluation of the 2D Poisson potential. To overcome the above mentioned difficulties, we introduce the auxiliary functions

$$G(\mathbf{x}) = \frac{1}{2\pi\sigma^2} e^{-\frac{|\mathbf{x}|^2}{2\sigma^2}}, \quad G_1(\mathbf{x}) = \widehat{\rho}(\mathbf{0}) G(\mathbf{x}) - \widehat{(x\rho)}(\mathbf{0}) \cdot \nabla_{\mathbf{x}} G(\mathbf{x}), \quad \mathbf{x} \in \mathbb{R}^2, \quad (2.6)$$

and the function $u_1(\mathbf{x})$ which satisfies the Poisson equation with the far-field condition:

$$-\Delta u_1(\mathbf{x}) = G_1(\mathbf{x}), \quad \mathbf{x} \in \mathbb{R}^2, \quad \lim_{|\mathbf{x}| \rightarrow \infty} \left[u_1(\mathbf{x}) + \frac{\widehat{\rho}(\mathbf{0})}{2\pi} \ln |\mathbf{x}| \right] = 0. \quad (2.7)$$

Here, $\sigma > 0$ is a parameter to be chosen later. Solving (2.7) via the convolution, we have

$$u_1(\mathbf{x}) = (U_{\text{Lap}} * G_1)(\mathbf{x}) = \widehat{\rho}(\mathbf{0}) u_{1,1}(\mathbf{x}) - \widehat{(x\rho)}(\mathbf{0}) \cdot \mathbf{u}_{1,2}(\mathbf{x}), \quad \mathbf{x} \in \mathbb{R}^2, \quad (2.8)$$

where

$$u_{1,1}(\mathbf{x}) = (U_{\text{Lap}} * G)(\mathbf{x}), \quad \mathbf{u}_{1,2}(\mathbf{x}) = \nabla_{\mathbf{x}} u_{1,1}(\mathbf{x}), \quad \mathbf{x} \in \mathbb{R}^2. \quad (2.9)$$

Note that $G(\mathbf{x})$ is radially symmetric, i.e., $G(\mathbf{x}) = G(|\mathbf{x}|) = G(r)$ with $r = |\mathbf{x}| \geq 0$ and $u_{1,1}(\mathbf{x})$ satisfies the Poisson equation

$$-\Delta u_{1,1}(\mathbf{x}) = G(\mathbf{x}), \quad \mathbf{x} \in \mathbb{R}^2, \quad \lim_{|\mathbf{x}| \rightarrow \infty} \left[u_{1,1}(\mathbf{x}) + \frac{1}{2\pi} \ln |\mathbf{x}| \right] = 0. \quad (2.10)$$

It is clear that $u_{1,1}(\mathbf{x})$ is also radially symmetric, i.e., $u_{1,1}(\mathbf{x}) = u_{1,1}(r)$. Thus, the Poisson equation (2.10) can be re-formulated as the following second order ODE:

$$-\frac{1}{r} \partial_r (r \partial_r u_{1,1}(r)) = G(r), \quad 0 < r < \infty, \quad \lim_{r \rightarrow \infty} \left[u_{1,1}(r) + \frac{1}{2\pi} \ln r \right] = 0. \tag{2.11}$$

Integrating the above ODE twice with the far-field boundary condition, we obtain

$$u_{1,1}(\mathbf{x}) = \begin{cases} -\frac{1}{4\pi} \left[E_1\left(\frac{|\mathbf{x}|^2}{2\sigma^2}\right) + 2 \ln(|\mathbf{x}|) \right], & \mathbf{x} \neq \mathbf{0}, \\ \frac{1}{4\pi} (\gamma_e - \ln(2\sigma^2)), & \mathbf{x} = \mathbf{0}, \end{cases} \quad \mathbf{x} \in \mathbb{R}^2, \tag{2.12}$$

where $E_1(r) := \int_r^\infty t^{-1} e^{-t} dt$ for $r > 0$ is the exponential integral function [1] and $\gamma_e \approx 0.5772156649015328606$ is the Euler–Mascheroni constant. Differentiating (2.12) leads to

$$\mathbf{u}_{1,2}(\mathbf{x}) = \begin{cases} -\frac{1}{2\pi} \frac{\mathbf{x}}{|\mathbf{x}|^2} \left(1 - e^{-\frac{|\mathbf{x}|^2}{2\sigma^2}} \right), & \mathbf{x} \neq \mathbf{0}, \\ 0, & \mathbf{x} = \mathbf{0}, \end{cases} \quad \mathbf{x} \in \mathbb{R}^2. \tag{2.13}$$

Denote

$$u_2(\mathbf{x}) = u(\mathbf{x}) - u_1(\mathbf{x}) \iff u(\mathbf{x}) = u_1(\mathbf{x}) + u_2(\mathbf{x}), \quad \mathbf{x} \in \mathbb{R}^2. \tag{2.14}$$

We have

$$-\Delta u_2(\mathbf{x}) = \rho(\mathbf{x}) - G_1(\mathbf{x}), \quad \mathbf{x} \in \mathbb{R}^2, \quad \lim_{|\mathbf{x}| \rightarrow \infty} u_2(\mathbf{x}) = 0. \tag{2.15}$$

Solving the above problem via the Fourier integral, noticing (2.6) and using the fact that

$$\nabla_{\mathbf{k}} \widehat{\rho}(\mathbf{0}) = -i \widehat{(\mathbf{x}\rho)}(\mathbf{0}) = -i \int_{\mathbb{R}^2} \mathbf{x}\rho(\mathbf{x}) d\mathbf{x},$$

we obtain

$$\begin{aligned} u_2(\mathbf{x}) &= (U_{\text{Lap}} * (\rho - G_1))(\mathbf{x}) = \frac{1}{(2\pi)^2} \int_{\mathbb{R}^2} \frac{\widehat{\rho}(\mathbf{k}) - \widehat{G_1}(\mathbf{k})}{|\mathbf{k}|^2} e^{i\mathbf{k}\cdot\mathbf{x}} d\mathbf{k} \\ &= \frac{1}{(2\pi)^2} \int_{\mathbb{R}^2} \frac{W(\mathbf{k})}{|\mathbf{k}|} e^{i\mathbf{k}\cdot\mathbf{x}} d\mathbf{k} \approx \frac{1}{(2\pi)^2} \int_0^P \int_0^{2\pi} W(\mathbf{k}) e^{i\mathbf{k}\cdot\mathbf{x}} d|\mathbf{k}| d\theta, \quad \mathbf{x} \in \Omega \subset \mathbb{R}^2, \end{aligned} \tag{2.16}$$

where

$$W(\mathbf{k}) = \begin{cases} \frac{\widehat{\rho}(\mathbf{k}) - \widehat{G_1}(\mathbf{k})}{|\mathbf{k}|} = \frac{\widehat{\rho}(\mathbf{k}) - (\widehat{\rho}(\mathbf{0}) + \mathbf{k} \cdot \nabla_{\mathbf{k}} \widehat{\rho}(\mathbf{0})) e^{-\frac{1}{2}|\mathbf{k}|^2\sigma^2}}{|\mathbf{k}|}, & \mathbf{k} \neq \mathbf{0}, \\ 0, & \mathbf{k} = \mathbf{0}, \end{cases} \quad \mathbf{k} \in \mathbb{R}^2. \tag{2.17}$$

Note that the singularity of $W(\mathbf{k})/|\mathbf{k}|$ at the origin in (2.16) is removed by switching to polar coordinates in the Fourier space, and thus $u_2(\mathbf{x})$ can be evaluated by the algorithm in [29].

In practical computations, the parameter σ in (2.6) should be chosen appropriately such that the Gaussian $e^{-\frac{1}{2}|\mathbf{k}|^2\sigma^2}$ and $\mathbf{k} \cdot \nabla_{\mathbf{k}} \widehat{\rho}(\mathbf{0}) e^{-\frac{1}{2}|\mathbf{k}|^2\sigma^2}$ in the Fourier space decay at the same rate or faster than $\widehat{\rho}(\mathbf{k})$ when $|\mathbf{k}|$ is large. With this choice of σ , there is no need to enlarge the computational domain in the Fourier space for the evaluation of (2.16) via the NUFFT. On the other hand, there is no need to oversample the truncated Fourier domain due to the rapid decaying of the Gaussian $e^{-\frac{1}{2}|\mathbf{k}|^2\sigma^2}$ in the Fourier space. Thus, setting the Gaussian to $2 \cdot 10^{-16}$ at $|\mathbf{k}|_\infty = P$ with P being the side-length of the bounded computational box $B = \{\mathbf{k} \mid |\mathbf{k}| \leq P\}$ in the Fourier space, we can choose $\sigma = 6/P$, a constant that is independent of the density function ρ .

For the convenience of the readers, we summarize the algorithm to evaluate the Poisson potential $u(\mathbf{x})$ in 2D in Algorithm 1.

Similarly, for the 1D case, i.e., $U_{\text{Lap}}(x) = -\frac{1}{2}|x|$, we introduce the auxiliary functions

$$G(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{x^2}{2\sigma^2}}, \quad G_1(x) = \widehat{\rho}(\mathbf{0})G(x) - \widehat{(x\rho)}(\mathbf{0})G'(x), \quad x \in \mathbb{R}, \tag{2.18}$$

and function $u_1(x)$ which satisfies the 1D Poisson equation with the far-field condition

$$-u_1''(x) = G_1(x), \quad x \in \mathbb{R}, \quad \lim_{x \rightarrow \pm\infty} \left[u_1(x) + \frac{1}{2} \left(\widehat{\rho}(\mathbf{0})|x| \mp \widehat{(x\rho)}(\mathbf{0}) \right) \right] = 0. \tag{2.19}$$

Algorithm 1 Evaluation of the Poisson potential in 2D.

Compute $\widehat{\rho}(\mathbf{k})$ and $\widehat{(\mathbf{x}\rho)}(\mathbf{0})$.
 Evaluate $u_1(\mathbf{x}) = \widehat{\rho}(\mathbf{0})u_{1,1}(\mathbf{x}) - \widehat{(\mathbf{x}\rho)}(\mathbf{0}) \cdot \mathbf{u}_{1,2}(\mathbf{x})$ via (2.12) and (2.13).
 Evaluate $u_2(\mathbf{x})$ through (2.16) via the NUFFT [29].
 Compute $u(\mathbf{x}) = u_1(\mathbf{x}) + u_2(\mathbf{x})$.

Solving the above problem via the convolution, we have

$$u_1(x) = (U_{\text{Lap}} * G_1)(x) = \widehat{\rho}(0) u_{1,1}(x) - \widehat{(\mathbf{x}\rho)}(0) u_{1,2}(x), \quad x \in \mathbb{R}, \tag{2.20}$$

where

$$u_{1,1}(x) = (U_{\text{Lap}} * G)(x) = -\frac{\sigma}{\sqrt{2\pi}} e^{-\frac{x^2}{2\sigma^2}} - \frac{1}{2} x \text{Erf}\left(\frac{x}{\sqrt{2}\sigma}\right), \tag{2.21}$$

$$u_{1,2}(x) = u'_{1,1}(x) = -\frac{1}{2} \text{Erf}\left(\frac{x}{\sqrt{2}\sigma}\right), \quad x \in \mathbb{R}. \tag{2.22}$$

Here, $\text{Erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt$ for $x \in \mathbb{R}$ is the error function. Combining (2.1) and (2.19), we solve the remaining function $u_2(x) = u(x) - u_1(x)$ via the Fourier integral:

$$u_2(x) = (U_{\text{Lap}} * (\rho - G_1))(x) = \frac{1}{2\pi} \int_{\mathbb{R}} \frac{\widehat{\rho}(k) - \widehat{G_1}(k)}{k^2} e^{ikx} dk \tag{2.23}$$

$$= \frac{1}{2\pi} \int_{\mathbb{R}} W(k) e^{ikx} dk \approx \frac{1}{2\pi} \int_{-P}^P W(k) e^{ikx} dk, \quad x \in \Omega \subset \mathbb{R}, \tag{2.24}$$

where

$$W(k) = \begin{cases} \frac{\widehat{\rho}(k) - \widehat{G_1}(k)}{k^2} = \frac{\widehat{\rho}(k) - (\widehat{\rho}(0) + k(\widehat{\rho})'(0)) e^{-\frac{1}{2}k^2\sigma^2}}{k^2}, & k \neq 0, \\ -\frac{1}{2} \widehat{(\mathbf{x}^2\rho)}(0) + \frac{\sigma^2}{2} \widehat{\rho}(0), & k = 0, \end{cases} \quad k \in \mathbb{R}. \tag{2.25}$$

Note that the integrand $W(k)$ is smooth at the origin $k = 0$ in the Fourier space, therefore $u_2(x)$ can be computed by the regular FFT method. The choice of the parameter σ is similar as the one in the 2D case.

We remark that the 1D Poisson potential has also been dealt with successfully in [41] by plugging the Fourier spectral approximation of the density obtained on a finite interval into the convolution formula (1.2). The method proposed there is an alternative good choice.

2.3. Confined Coulomb interactions

When $U(\mathbf{x})$ reads as (1.12), there is no equivalent PDE formulation for the nonlocal potential $u(\mathbf{x})$. When $d = 2$, noticing that

$$\widehat{U}_{\text{Con}}^\varepsilon(\mathbf{k}) \approx \begin{cases} \frac{1}{|\mathbf{k}|}, & |\mathbf{k}| \rightarrow 0, \\ \frac{\sqrt{2}}{\sqrt{\pi}\varepsilon|\mathbf{k}|^2}, & |\mathbf{k}| \rightarrow \infty, \end{cases} \quad \mathbf{k} \in \mathbb{R}^2, \tag{2.26}$$

we can immediately adapt the NUFFT-based solver [29] as follows:

$$\begin{aligned} u(\mathbf{x}) &= \frac{1}{(2\pi)^2} \int_{\mathbb{R}^2} e^{i\mathbf{k}\cdot\mathbf{x}} \widehat{U}_{\text{Con}}^\varepsilon(\mathbf{k}) \widehat{\rho}(\mathbf{k}) d\mathbf{k} \approx \frac{1}{(2\pi)^2} \int_{|\mathbf{k}| \leq P} e^{i\mathbf{k}\cdot\mathbf{x}} \widehat{U}_{\text{Con}}^\varepsilon(\mathbf{k}) \widehat{\rho}(\mathbf{k}) d\mathbf{k} \\ &= \frac{1}{(2\pi)^2} \int_0^P \int_0^{2\pi} e^{i\mathbf{k}\cdot\mathbf{x}} W_1(\mathbf{k}) \widehat{\rho}(\mathbf{k}) d|\mathbf{k}| d\theta, \quad \mathbf{x} \in \Omega \subset \mathbb{R}^2, \end{aligned} \tag{2.27}$$

where

$$W_1(\mathbf{k}) = |\mathbf{k}| \widehat{U}_{\text{Con}}^\varepsilon(\mathbf{k}) = \frac{2}{\pi} \int_0^\infty \frac{|\mathbf{k}| e^{-\frac{\varepsilon^2 s^2}{2}}}{|\mathbf{k}|^2 + s^2} ds = \begin{cases} \frac{2}{\pi} \int_0^\infty \frac{e^{-\varepsilon^2 |\mathbf{k}|^2 s^2 / 2}}{1 + s^2} ds, & \mathbf{k} \neq \mathbf{0}, \\ 1, & \mathbf{k} = \mathbf{0}, \end{cases} \quad \mathbf{k} \in \mathbb{R}^2. \tag{2.28}$$

The integral in (2.28) can be evaluated very accurately via the standard quadrature, such as the Gauss–Kronrod quadrature. Similarly, when $d = 1$ we have

$$\widehat{U}_{\text{Con}}^\varepsilon(k) \approx \begin{cases} \frac{1}{2} [\ln 2 - \gamma_e - 2 \ln(\varepsilon|k|)], & |k| \rightarrow 0, \\ \frac{1}{\varepsilon^2|k|^2}, & |k| \rightarrow \infty, \end{cases} \quad k \in \mathbb{R}. \tag{2.29}$$

Thus

$$\begin{aligned} u(x) &= \frac{1}{2\pi} \int_{\mathbb{R}} e^{ikx} \widehat{U}_{\text{Con}}^\varepsilon(k) \widehat{\rho}(k) dk = -\frac{1}{2\pi} \int_{\mathbb{R}} e^{ikx} k [\partial_k (\widehat{U}_{\text{Con}}^\varepsilon(k) \widehat{\rho}(k)) + ix \widehat{U}_{\text{Con}}^\varepsilon(k) \widehat{\rho}(k)] dk \\ &= -\frac{1}{2\pi} \int_{\mathbb{R}} e^{ikx} [k \partial_k \widehat{U}_{\text{Con}}^\varepsilon(k) \widehat{\rho}(k) - ik \widehat{U}_{\text{Con}}^\varepsilon(k) \widehat{(x\rho)}(k) + ixk \widehat{U}_{\text{Con}}^\varepsilon(k) \widehat{\rho}(k)] dk \\ &= \frac{1}{2\pi} \int_{\mathbb{R}} e^{ikx} [W_2(k) \widehat{\rho}(k) + i W_3(k) \widehat{(x\rho)}(k)] dk - \frac{ix}{2\pi} \int_{\mathbb{R}} e^{ikx} W_3(k) \widehat{\rho}(k) dk \\ &\approx \frac{1}{2\pi} \int_{-P}^P e^{ikx} [W_2(k) \widehat{\rho}(k) + i W_3(k) \widehat{(x\rho)}(k)] dk - \frac{ix}{2\pi} \int_{-P}^P e^{ikx} W_3(k) \widehat{\rho}(k) dk, \quad x \in [-L, L]. \end{aligned} \tag{2.30}$$

Here

$$W_2(k) = -k \partial_k \widehat{U}_{\text{Con}}^\varepsilon(k) = \int_0^\infty \frac{k^2 e^{-\varepsilon^2 s/2}}{(k^2 + s)^2} ds = \begin{cases} \int_0^\infty \frac{e^{-\varepsilon^2 k^2 s/2}}{(1+s)^2} ds, & k \neq 0, \\ 1, & k = 0, \end{cases} \quad k \in \mathbb{R}, \tag{2.31}$$

$$W_3(k) = k \widehat{U}_{\text{Con}}^\varepsilon(k) = \int_0^\infty \frac{k e^{-\varepsilon^2 s/2}}{2(k^2 + s)} ds = \begin{cases} \int_0^\infty \frac{k e^{-\varepsilon^2 k^2 s/2}}{2(1+s)} ds, & k \neq 0, \\ 0, & k = 0, \end{cases} \quad k \in \mathbb{R}. \tag{2.32}$$

The integrals in (2.31)–(2.32) can be discretized very accurately via the standard quadrature, and the integrals in (2.30) can be evaluated via the regular FFT.

Remark 2.1. If $\rho(\mathbf{x})$ is spherically/radially symmetric and $U(\mathbf{x})$ reads as (1.9) in 3D/2D, then the corresponding nonlocal interaction $u(\mathbf{x})$ in (2.1) is also spherically/radially symmetric. In addition, it satisfies the following second-order ODE

$$-\frac{1}{r^{d-1}} \partial_r (r^{d-1} \partial_r u(r)) = \rho(r), \quad 0 < r < \infty, \quad d = 3, 2, \tag{2.33}$$

$$\partial_r u(0) = 0, \quad u(r) \rightarrow \begin{cases} 0, & d = 3, \\ -C_0 \ln r, & d = 2, \end{cases} \quad r \rightarrow \infty, \tag{2.34}$$

where $r = |\mathbf{x}|$ and $C_0 = \int_0^\infty \rho(r) r dr$. Moreover, if $\rho(r)$ has a compact support or decays exponentially fast when $r \rightarrow \infty$, the above problem can be further re-formulated or approximated by [28,35]

$$-\frac{1}{r^{d-1}} \partial_r (r^{d-1} \partial_r u(r)) = \rho(r), \quad 0 < r < L, \quad d = 3, 2, \tag{2.35}$$

$$\partial_r u(0) = 0, \quad \partial_r u(L) = \begin{cases} -\frac{u(L)}{L}, & d = 3, \\ \frac{u(L)}{L \ln L}, & d = 2, \end{cases} \tag{2.36}$$

where $L > 0$ is large enough such that $\text{supp}(\rho) \subset [0, L]$ or the truncation error in ρ outside $[0, L]$ is negligible. This two-point boundary value problem can be solved by the finite difference (FDM) or finite element (FEM) or spectral method. Comparing to computing the original convolution or solving the corresponding Poisson equation in 3D/2D, the memory and/or computational cost are significantly reduced.

2.4. Numerical comparisons

In this subsection, we will demonstrate the efficiency and accuracy of the NUFFT based method for nonlocal interaction evaluation and compare it with other existing methods such as the FFT based algorithm [11], the DST based one [17,41] and the finite difference method via (2.35)–(2.36) [35]. To this end, we denote Ω as the computational domain and choose $h_x = h_y = h_z = h$ in 3D or $h_x = h_y = h$ in 2D unless stated otherwise. We denote Ω_h as the partition of Ω with mesh size h

Table 1
Errors for the evaluation of the 3D Coulomb interaction by different methods for different h and L .

	$h = 2$	$h = 1$	$h = 1/2$	$h = 1/4$	$h = 1/8$
NUFFT					
$L = 4$	4.191E-01	2.696E-03	6.634E-07	4.599E-07	3.688E-07
$L = 8$	4.111E-01	2.817E-03	1.667E-08	2.367E-14	2.404E-14
$L = 16$	4.127E-01	2.848E-03	1.732E-08	1.420E-14	1.334E-14
DST					
$L = 4$	2.437E-01	2.437E-01	2.437E-01	2.437E-01	2.437E-01
$L = 8$	2.754E-01	1.219E-01	1.219E-01	1.219E-01	1.219E-01
$L = 16$	3.433E-01	6.093E-02	6.093E-02	6.093E-02	6.093E-02
$L = 32$	3.780E-01	3.046E-02	3.046E-02	3.046E-02	3.046E-02
$L = 64$	3.956E-01	1.523E-02	1.523E-02	1.523E-02	1.523E-02
FFT					
$L = 4$	3.032E-01	3.363E-01	3.385E-01	3.385E-01	3.385E-01
$L = 8$	1.744E-01	1.712E-01	1.720E-01	1.720E-01	1.720E-01
$L = 16$	2.958E-01	8.666E-02	8.632E-02	8.632E-02	8.632E-02
$L = 32$	3.550E-01	4.372E-02	4.320E-02	4.320E-02	4.320E-02
$L = 64$	3.843E-01	2.214E-02	2.161E-02	2.161E-02	2.161E-02

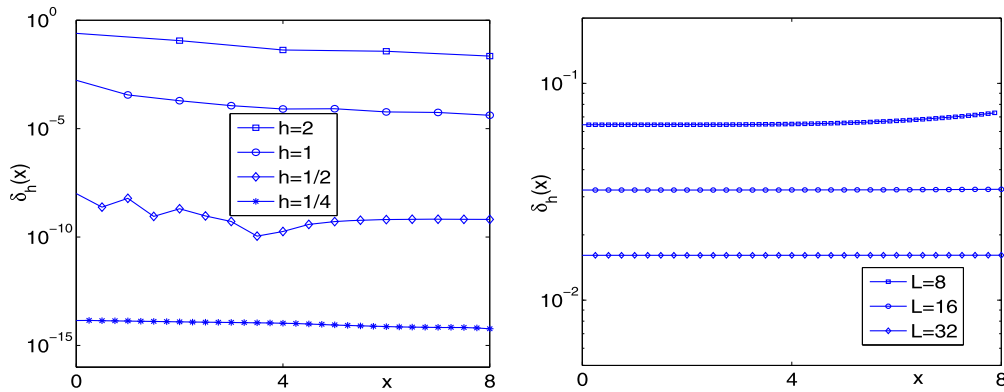


Fig. 2. Errors of $\delta_h(x) = |u(x, 0, 0) - u_h(x, 0, 0)|$ for the evaluation of the Coulomb interaction in 3D via the NUFFT method with $L = 8$ for different mesh size h (left) and via the DST method with mesh size $h = 1/4$ for different L (right).

and $u_h(\mathbf{x})$ as the numerical solution obtained by a numerical method on Ω_h . To show the comparison, we adopt the error function

$$e_h := \frac{\|u - u_h\|_{l^\infty}}{\|u\|_{l^\infty}} = \frac{\max_{\mathbf{x} \in \Omega_h} |u(\mathbf{x}) - u_h(\mathbf{x})|}{\max_{\mathbf{x} \in \Omega_h} |u(\mathbf{x})|}. \tag{2.37}$$

Example 2.1 (3D Coulomb interaction). Here $d = 3$ and $U(\mathbf{x}) = U_{\text{Coul}}(\mathbf{x})$, we take $\rho(\mathbf{x}) := e^{-(x^2+y^2+\gamma^2 z^2)/\delta^2}$ with $\delta > 0$ and $\gamma \geq 1$. The 3D Coulomb interaction can be computed analytically as

$$u(\mathbf{x}) = \begin{cases} \frac{\delta^3 \sqrt{\pi}}{4 |\mathbf{x}|} \text{Erf}\left(\frac{|\mathbf{x}|}{\delta}\right), & \gamma = 1, \\ \frac{\delta^2}{4\gamma} \int_0^\infty \frac{e^{-\frac{x^2+y^2}{\delta^2(t+1)} - \frac{z^2}{\delta^2(t+\gamma^2)}}}{(t+1)\sqrt{t+\gamma^2}} dt, & \gamma \neq 1, \end{cases} \quad \mathbf{x} \in \mathbb{R}^3. \tag{2.38}$$

The 3D Coulomb interaction $u(\mathbf{x})$ is computed numerically via the NUFFT, DST and FFT methods on a bounded computational domain $\Omega = [-L, L]^2 \times [-L/\gamma, L/\gamma]$ with mesh size h . Table 1 shows the errors e_h via the NUFFT, DST and FFT methods with $\gamma = 1$, $\delta = 1.1$ for different mesh size h and L . Fig. 2 depicts the error of the Coulomb interaction along the x -axis, which is defined as $\delta_h(x) := |u(x, 0, 0) - u_h(x, 0, 0)|$, obtained via the NUFFT and DST methods with $\gamma = 1$, $\delta = 1.1$ for different mesh size h and L . In addition, Table 2 shows the errors e_h via the NUFFT, DST and FFT methods with $\delta = 2$ and $L = 8$, $h = 1/4$ for different γ . Here h denote $h_x = h_y$ and we choose $h_z = h/\gamma$.

From Tables 1–2 and Fig. 2, we can observe clearly that: (i) The errors are saturated in the DST and FFT methods as mesh size h tends smaller and the saturated accuracies decrease linearly with respect to the box size L ; (ii) The NUFFT method is spectrally accurate and it essentially does not depend on the domain, which implies that a very large bounded computational domain is not necessary in practical computations when the NUFFT method is used; (iii) The NUFFT is

Table 2

Errors for the evaluation of the 3D Coulomb interaction by different methods with $\delta = 2$ and $L = 8$, $h = 1/4$ for different γ .

	$\gamma = 1$	$\gamma = 2$	$\gamma = 4$	$\gamma = 8$
NUFFT	2.164E-14	2.134E-14	2.044E-14	2.005E-14
DST	0.146	0.441	1.559	3.782
FFT	0.208	0.310	1.327	3.349

Table 3

Errors for the evaluation of the 2D Coulomb interaction by different methods for different h and L .

	$h = 2$	$h = 1$	$h = 1/2$	$h = 1/4$	$h = 1/8$
NUFFT					
$L = 4$	1.837	5.540E-02	4.289E-07	3.383E-07	2.937E-07
$L = 8$	4.457E-01	2.373E-03	2.714E-08	3.202E-15	3.431E-15
$L = 16$	2.084E-01	2.385E-03	2.761E-08	2.745E-15	2.859E-15
DST					
$L = 4$	1.577E-01	1.577E-01	1.577E-01	1.577E-01	1.577E-01
$L = 8$	1.348E-01	7.762E-02	7.762E-02	7.762E-02	7.762E-02
$L = 16$	1.711E-01	3.867E-02	3.867E-02	3.867E-02	3.867E-02
$L = 32$	1.897E-01	1.932E-02	1.932E-02	1.932E-02	1.932E-02
$L = 64$	1.991E-01	9.658E-03	9.658E-03	9.658E-03	9.658E-03
FFT					
$L = 4$	2.855E-01	2.961E-01	2.980E-01	2.980E-01	2.980E-01
$L = 8$	1.553E-01	1.503E-01	1.502E-01	1.502E-01	1.502E-01
$L = 16$	1.157E-01	7.596E-02	7.528E-02	7.528E-02	7.528E-02
$L = 32$	1.624E-01	3.843E-02	3.766E-02	3.766E-02	3.766E-02
$L = 64$	1.856E-01	1.961E-02	1.883E-02	1.883E-02	1.883E-02

Table 4

Errors for the evaluation of the 2D Coulomb interaction by different methods with $L = 12$, $h = 1/8$ for different γ .

	$\gamma = 1$	$\gamma = 2$	$\gamma = 4$	$\gamma = 8$
NUFFT	4.230E-14	3.102E-15	3.504E-15	4.381E-15
DST	0.373	0.386	0.412	0.446
FFT	0.426	0.425	0.405	0.344

capable of dealing with anisotropic densities, which is quite useful in numerical simulation of BEC with strong confinement, while the errors by the DST and FFT methods increase dramatically with strongly anisotropic densities (cf. Table 2).

Example 2.2 (2D Coulomb interaction). Here $d = 2$ and $U(\mathbf{x}) = U_{\text{Coul}}(\mathbf{x})$, we take $\rho(\mathbf{x}) := e^{-(x^2 + \gamma^2 y^2)/\delta^2}$ with $\delta > 0$ and $\gamma \geq 1$. The 2D Coulomb interaction can be obtained analytically as

$$u(\mathbf{x}) = \begin{cases} \frac{\sqrt{\pi} \delta}{2} I_0 \left(\frac{|\mathbf{x}|^2}{2\delta^2} \right) e^{-\frac{|\mathbf{x}|^2}{2\delta^2}}, & \gamma = 1, \\ \frac{\delta}{\gamma \sqrt{\pi}} \int_0^\infty \frac{e^{-\frac{x^2}{\delta^2(t^2+1)}} e^{-\frac{y^2}{\delta^2(t^2+\gamma^{-2})}}}{\sqrt{t^2+1} \sqrt{t^2+\gamma^{-2}}} dt, & \gamma \neq 1, \end{cases} \quad \mathbf{x} \in \mathbb{R}^2, \tag{2.39}$$

where I_0 is the modified Bessel function of order zero [1]. To numerically compute the integral in (2.39), we first split it into two integrals and reformulate the one with infinite interval into some equivalent integral with finite interval by a simple change of variable. We then apply the Gauss–Kronrod quadrature to each with fine accuracy control so as to achieve accurate reference solutions.

The 2D Coulomb interaction $u(\mathbf{x})$ is computed numerically via the NUFFT, DST and FFT methods on a bounded computational domain $\Omega = [-L, L] \times [-L/\gamma, L/\gamma]$ with mesh size h . Table 3 shows the errors e_h via the NUFFT, DST and FFT methods with $\delta = \sqrt{1.2}$ and $\gamma = 1$ under different mesh size h and L . In addition, Table 4 shows the errors e_h via the NUFFT, DST and FFT methods with $\delta = 2$, $L = 12$ and $h = 1/8$ for different γ . Here h denote h_x and we choose $h_y = h/\gamma$.

From Tables 3–4, we can conclude that: (i) The errors obtained by the DST and FFT methods reach a saturation accuracy on any fixed domain and we can observe a first order convergence in the saturated accuracy with respect to the domain size L . (ii) The NUFFT method is spectrally accurate and it essentially does not depend on the domain which makes it perfect for computing the whole space potential. (iii) The NUFFT is capable of dealing with anisotropic densities, while the results obtained by the DST and FFT methods are far from the exact solutions when the bounded computational domain is not large enough.

Table 5Errors for the evaluation of the 2D Poisson potential by different methods for different h and L .

NUFFT	$h = 2$	$h = 1$	$h = 1/2$	$h = 1/4$	$h = 1/8$
$L = 4$	5.821E-01	1.133E-02	3.011E-06	1.994E-06	1.650E-06
$L = 8$	1.685E-01	6.820E-04	1.754E-09	4.936E-14	4.857E-14
$L = 16$	1.684E-01	5.333E-04	1.391E-09	4.577E-14	4.561E-14
FDM	$h = 1/4$	$h = 1/8$	$h = 1/16$	$h = 1/32$	$h = 1/64$
$L = 4$	4.646E-03	1.155E-03	2.910E-04	7.602E-05	2.246E-05
Rate	–	2.0081	1.9889	1.9365	1.7590
$L = 8$	4.101E-03	1.019E-03	2.542E-04	6.353E-05	1.588E-05
Rate	–	2.0093	2.0024	2.0006	2.0002
$L = 16$	4.052E-03	1.007E-03	2.512E-04	6.278E-05	1.569E-05
Rate	–	2.0092	2.0023	2.0006	2.0001

Table 6CPU time (in seconds) of the NUFFT solver for the evaluation of the 2D Poisson potential. Here T_{FFT} and T_{NUFFT} are the time for the evaluation of I_1 and I_2 in (2.3) via the FFT and NUFFT methods, respectively.

	T_{FFT}	T_{NUFFT}	T_{Total}
$h = 1$	0.01	0.05	0.06
$h = 1/2$	0.02	0.08	0.10
$h = 1/4$	0.12	0.20	0.32
$h = 1/8$	0.60	0.78	1.38

Example 2.3 (2D Poisson potential). Here $d = 2$ and $U(\mathbf{x}) = U_{\text{Lap}}(\mathbf{x})$, we take $\rho(\mathbf{x}) := e^{-|\mathbf{x}|^2/\delta^2} = e^{-r^2/\delta^2}$ with $r = |\mathbf{x}|$ and $\delta > 0$. The 2D Poisson potential can be obtained analytically as

$$u(\mathbf{x}) = -\frac{\delta^2}{4} \left[E_1 \left(\frac{|\mathbf{x}|^2}{\delta^2} \right) + 2 \ln(|\mathbf{x}|) \right], \quad \mathbf{x} \in \mathbb{R}^2. \quad (2.40)$$

In this case, we choose $\delta = \sqrt{1.3}$. The 2D Poisson potential $u(\mathbf{x})$ is computed numerically via the NUFFT method on a bounded computational domain $\Omega = [-L, L]^2$ with mesh size h and the FDM through the formulation (2.35)–(2.36) on the interval $[0, L]$ with mesh size h .

Table 5 shows the errors of the 2D Poisson potential obtained by the NUFFT solver on a square domain and the errors by the FDM solver as well as its convergence rate with respect to the mesh size h . In addition, to demonstrate the efficiency of the NUFFT method, Table 6 displays the computational time (CPU time in seconds) of the NUFFT solver with $L = 16$ and $h = 1/4$, where the time is measured when the algorithm is implemented in Fortran, the code is compiled by ifort 13.1.2 using the option `-g`, and executed on 32-bit Ubuntu Linux on a 2.90 GHz Intel(R) Core(TM) i7-3520M CPU with 6 MB cache.

From Tables 5–6, we can see clearly that: (i) The NUFFT solver is spectrally accurate while the FDM solver is only second order accurate, and the NUFFT solver is much more accurate than the FDM solver. (ii) The errors obtained by both methods do not essentially depend on the domain size; (iii) The complexity of the NUFFT solver scales like $O(N \ln N)$ as expected, which is the same as those presented in [29].

3. Computing the ground state

In this section, we present an efficient and accurate numerical method for computing the ground state of (1.13) by combining NUFFT-based nonlocal interaction potential solver and the normalized gradient flow that is discretized by backward Euler Fourier pseudospectral method, and compare it with those existing numerical methods.

3.1. A numerical method via the NUFFT

We choose $\tau > 0$ as the time step and denote $t_n = n\tau$ for $n = 0, 1, 2, \dots$. Different efficient and accurate numerical methods have been proposed in the literature for computing the ground state [3,6–8,21,41]. One of the most simple and popular methods is through the following gradient flow with discretized normalization (GFDN):

$$\partial_t \phi(\mathbf{x}, t) = \left[\frac{1}{2} \Delta - V(\mathbf{x}) - \beta \phi(\mathbf{x}, t) \right] \phi(\mathbf{x}, t), \quad \mathbf{x} \in \mathbb{R}^d, \quad t_n \leq t < t_{n+1}, \quad (3.1)$$

$$\phi(\mathbf{x}, t) = \left(U * |\phi|^2 \right)(\mathbf{x}, t), \quad \mathbf{x} \in \mathbb{R}^d, \quad t_n \leq t < t_{n+1}, \quad (3.2)$$

$$\phi(\mathbf{x}, t_{n+1}) := \phi(\mathbf{x}, t_{n+1}^+) = \frac{\phi(\mathbf{x}, t_{n+1}^-)}{\|\phi(\mathbf{x}, t_{n+1}^-)\|}, \quad \mathbf{x} \in \mathbb{R}^d, \quad n = 0, 1, 2, \dots \quad (3.3)$$

with the initial data

$$\phi(\mathbf{x}, 0) = \phi_0(\mathbf{x}), \quad \mathbf{x} \in \mathbb{R}^d, \quad \text{with} \quad \|\phi_0\|^2 := \int_{\mathbb{R}^d} |\phi_0(\mathbf{x})|^2 d\mathbf{x} = 1. \quad (3.4)$$

Let $\phi^n(\mathbf{x})$ and $\varphi^n(\mathbf{x})$ be the numerical approximation of $\phi(\mathbf{x}, t_n)$ and $\varphi(\mathbf{x}, t_n)$, respectively, for $n \geq 0$. The above GFDN is usually discretized in time via the backward Euler method [6–8,21,41]

$$\frac{\phi^{(1)}(\mathbf{x}) - \phi^n(\mathbf{x})}{\tau} = \left[\frac{1}{2} \Delta - V(\mathbf{x}) - \beta \varphi^n(\mathbf{x}) \right] \phi^{(1)}(\mathbf{x}), \quad \mathbf{x} \in \mathbb{R}^d, \quad (3.5)$$

$$\varphi^n(\mathbf{x}) = \left(U * |\phi^n|^2 \right)(\mathbf{x}), \quad \mathbf{x} \in \mathbb{R}^d, \quad (3.6)$$

$$\phi^{n+1}(\mathbf{x}) = \frac{\phi^{(1)}(\mathbf{x})}{\|\phi^{(1)}(\mathbf{x})\|}, \quad \mathbf{x} \in \mathbb{R}^d, \quad n = 0, 1, 2, \dots \quad (3.7)$$

Then an efficient and accurate numerical method can be designed by: (i) truncating the above problem on a bounded computational domain Ω with periodic BC on $\partial\Omega$; (ii) discretizing in space via the Fourier pseudospectral method; and (iii) evaluating the nonlocal interaction $\varphi^n(\mathbf{x})$ in (3.6) by the algorithm via the NUFFT discussed in the previous section. When $\phi_0(\mathbf{x})$ is chosen as a positive function, the ground state can be obtained as $\phi_g(\mathbf{x}) = \lim_{n \rightarrow \infty} \phi^n(\mathbf{x})$ for $\mathbf{x} \in \Omega$. The details are omitted here for brevity and this method is referred to as the *GF-NUFFT* method. We remark here that $|\widehat{\phi^n}|^2(\mathbf{0}) = 1$ for $n \geq 0$.

For comparison, for the Coulomb interaction in 3D/2D, when the NUFFT solver is replaced by the standard FFT, we refer to the method as *GF-FFT*. In addition, when (3.6) is reformulated as its equivalent PDE formulation (1.7)–(1.8) on Ω with homogeneous Dirichlet BC on $\partial\Omega$ and solved via the sine pseudospectral method [6,9,41], we refer to it as *GF-DST*.

3.2. Numerical comparisons

In order to compare the *GF-NUFFT* method with *GF-FFT* and *GF-DST* methods for computing the ground state, we denote $\varphi_g(\mathbf{x}) = (U * |\phi_g|^2)(\mathbf{x})$ and introduce the errors

$$e_{\phi_g}^h := \frac{\max_{\mathbf{x} \in \Omega_h} |\phi_g(\mathbf{x}) - \phi_g^h(\mathbf{x})|}{\max_{\mathbf{x} \in \Omega_h} |\phi_g(\mathbf{x})|}, \quad e_{\varphi_g}^h := \frac{\max_{\mathbf{x} \in \Omega_h} |\varphi_g(\mathbf{x}) - \varphi_g^h(\mathbf{x})|}{\max_{\mathbf{x} \in \Omega_h} |\varphi_g(\mathbf{x})|},$$

where ϕ_g^h and φ_g^h are obtained numerically by a numerical method with mesh size h . Additionally, we split the energy functional into three parts

$$E(\phi) = E_{\text{kin}}(\phi) + E_{\text{pot}}(\phi) + E_{\text{int}}(\phi),$$

where the kinetic energy $E_{\text{kin}}(\phi)$, the potential energy $E_{\text{pot}}(\phi)$ and the interaction energy $E_{\text{int}}(\phi)$ are defined as

$$E_{\text{kin}}(\phi) = \frac{1}{2} \int_{\mathbb{R}^d} |\nabla \phi(\mathbf{x})|^2 d\mathbf{x}, \quad E_{\text{pot}}(\phi) = \int_{\mathbb{R}^d} V(\mathbf{x}) |\phi(\mathbf{x})|^2 d\mathbf{x}, \quad E_{\text{int}}(\phi) = \frac{\beta}{2} \int_{\mathbb{R}^d} \varphi(\mathbf{x}) |\phi(\mathbf{x})|^2 d\mathbf{x},$$

respectively. Moreover, the chemical potential can be reformulated as $\mu(\phi) = E(\phi) + E_{\text{int}}(\phi)$. Furthermore, if the external potential $V(\mathbf{x})$ in (1.1) was taken as the harmonic potential [4,9,35], the energies of the ground state satisfy the following virial identity

$$0 = I := 2E_{\text{kin}}(\phi_g) - 2E_{\text{pot}}(\phi_g) + \begin{cases} E_{\text{int}}(\phi_g), & U = U_{\text{Cou}} \text{ in 3D/2D,} \\ \frac{\beta}{4\pi}, & U = U_{\text{Lap}} \text{ in 2D.} \end{cases}$$

We denote I^h as an approximation of I when ϕ_g is replaced by ϕ_g^h in the above equality. In our computations, the ground state ϕ_g^h is reached numerically when $\max_{\mathbf{x} \in \Omega_h} \frac{|\phi^{n+1}(\mathbf{x}) - \phi^n(\mathbf{x})|}{\tau} \leq \varepsilon_0$ with ε_0 a prescribed accuracy, e.g., $\varepsilon_0 = 10^{-10}$. The initial data $\phi_0(\mathbf{x})$ is chosen as a Gaussian and the time step is taken as $\tau = 10^{-2}$. In the comparisons, the reference solution $\phi_g(\mathbf{x})$ was obtained numerically via the *GF-NUFFT* method on a large enough domain $\Omega = [-8, 8]^d$ with small enough mesh size $h = 2^{d-6}$ and time step $\tau = 10^{-2}$.

Example 3.1 (*The NLSE with the Coulomb interaction in 3D*). We take $d = 3$ and $U(\mathbf{x}) = U_{\text{Cou}}(\mathbf{x})$ in (1.1)–(1.2). The ground state is computed numerically on a bounded domain $\Omega = [-8, 8]^3$. Table 7 shows the errors $e_{\phi_g}^h$ and $e_{\varphi_g}^h$ with $V(\mathbf{x}) = \frac{1}{2}(x^2 + y^2 + z^2)$ in (1.1) for different numerical methods, β and mesh size h . In addition, Table 8 lists the energy $E_g := E(\phi_g^h)$, chemical potential $\mu_g := \mu(\phi_g^h)$, kinetic energy $E_{\text{kin}}^g := E_{\text{kin}}(\phi_g^h)$, potential energy $E_{\text{pot}}^g := E_{\text{pot}}(\phi_g^h)$, interaction energy $E_{\text{int}}^g := E_{\text{int}}(\phi_g^h)$ and I^h with $h = 1/8$ and $V(\mathbf{x}) = \frac{1}{2}(x^2 + y^2 + 4z^2)$ in (1.1) for different β .

Table 7

Errors of the ground state for the NLSE with the 3D Coulomb interaction for different methods and mesh size h .

		$h = 2$	$h = 1$	$h = 1/2$	$h = 1/4$
GF-NUFFT					
$e_{\phi_g}^h$	$\beta = -5$	5.362E-02	1.954E-04	2.201E-07	4.643E-11
	$\beta = 5$	1.512E-01	4.712E-04	4.026E-08	1.141E-10
$e_{\varphi_g}^h$	$\beta = -5$	2.532E-01	3.769E-03	8.153E-07	7.035E-11
	$\beta = 5$	2.682E-01	7.061E-04	1.225E-07	8.048E-11
GF-DST					
$e_{\phi_g}^h$	$\beta = -5$	2.319E-01	9.439E-03	1.637E-06	6.309E-07
	$\beta = 5$	1.659E-01	9.469E-04	8.306E-07	8.531E-07
$e_{\varphi_g}^h$	$\beta = -5$	7.297E-02	9.551E-02	9.945E-02	1.027E-01
	$\beta = 5$	7.809E-02	1.016E-01	1.057E-01	1.091E-01

Table 8

Different energies of the ground state and I^h for the NLSE with the 3D Coulomb interaction for different β .

β	E_g	μ_g	E_{kin}^g	E_{pot}^g	E_{int}^g	I^h
-10	1.6370	1.2630	1.0990	9.1197E-01	-3.7401E-01	-3.39E-10
-5	1.8212	1.6397	1.0467	9.5594E-01	-1.8147E-01	-3.63E-10
-1	1.9646	1.9292	1.0089	9.9118E-01	-3.5462E-02	-3.87E-10
1	2.0351	2.0702	9.9128E-01	1.0088	3.5064E-02	-3.86E-10
5	2.1739	2.3454	9.5831E-01	1.0441	1.7151E-01	-4.30E-10
10	2.3431	2.6772	9.2101E-01	1.0880	3.3408E-01	-1.16E-10

Table 9

Errors of the ground state for the NLSE with 2D Coulomb interaction on $[-L, L]^2$ with mesh size h .

GF-NUFFT ($L = 8$)		$h = 1$	$h = 1/2$	$h = 1/4$	$h = 1/8$
$e_{\phi_g}^h$	$\beta = -5$	4.620E-02	1.058E-03	5.570E-08	3.968E-15
	$\beta = 5$	7.034E-03	2.365E-05	2.632E-10	2.074E-15
$e_{\varphi_g}^h$	$\beta = -5$	1.025E-01	1.402E-03	8.244E-08	4.445E-15
	$\beta = 5$	1.263E-02	3.239E-05	3.161E-10	1.703E-15
GF-DST ($L = 8$)		$h = 1$	$h = 1/2$	$h = 1/4$	$h = 1/8$
$e_{\phi_g}^h$	$\beta = -5$	4.823E-02	1.112E-03	3.139E-05	3.133E-05
	$\beta = 5$	8.183E-03	7.245E-05	5.317E-05	5.381E-05
$e_{\varphi_g}^h$	$\beta = -5$	6.613E-02	5.159E-02	5.159E-02	5.159E-02
	$\beta = 5$	6.840E-02	6.840E-02	6.840E-02	6.840E-02
GF-DST ($h = 1/8$)		$L = 8$	$L = 16$	$L = 32$	$L = 64$
$e_{\phi_g}^h$	$\beta = -5$	3.133E-05	3.848E-06	4.789E-07	5.980E-08
	$\beta = 5$	5.381E-05	6.212E-06	7.606E-07	9.445E-08
$e_{\varphi_g}^h$	$\beta = -5$	5.159E-02	2.572E-02	1.072E-02	5.248E-03
	$\beta = 5$	6.840E-02	3.398E-02	1.415E-02	6.928E-03

Example 3.2 (The NLSE with the Coulomb interaction in 2D). We take $d = 2$ and $U(\mathbf{x}) = U_{\text{Coul}}(\mathbf{x})$ in (1.1)–(1.2). The ground state is computed numerically on a bounded domain $\Omega = [-L, L]^2$ with different mesh size h . Table 9 shows the errors $e_{\phi_g}^h$ and $e_{\varphi_g}^h$ with $V(\mathbf{x}) = \frac{1}{2}(x^2 + 4y^2)$ for different numerical methods, β and mesh size h on $[-L, L]^2$. In addition, Table 10 lists the energy $E_g := E(\phi_g^h)$, chemical potential $\mu_g := \mu(\phi_g^h)$, kinetic energy $E_{\text{kin}}^g := E_{\text{kin}}(\phi_g^h)$, potential energy $E_{\text{pot}}^g := E_{\text{pot}}(\phi_g^h)$, interaction energy $E_{\text{int}}^g := E_{\text{int}}(\phi_g^h)$ and I^h with $h = 1/8$ and $V(\mathbf{x}) = \frac{1}{2}(x^2 + 4y^2)$ on $[-8, 8]^2$ for different β .

Example 3.3 (The NLSE with the Poisson potential in 2D). We take $d = 2$ and $U(\mathbf{x}) = U_{\text{Lap}}(\mathbf{x})$ in (1.1)–(1.2). The ground state is computed numerically on a bounded domain $\Omega = [-8, 8]^2$ with different mesh size h . Table 11 shows the errors $e_{\phi_g}^h$ and $e_{\varphi_g}^h$ with $V(\mathbf{x}) = \frac{1}{2}(x^2 + 4y^2)$ in (1.1) for different numerical methods, β and mesh size h . In addition, Table 12 lists the energy $E_g := E(\phi_g^h)$, chemical potential $\mu_g := \mu(\phi_g^h)$, kinetic energy $E_{\text{kin}}^g := E_{\text{kin}}(\phi_g^h)$, potential energy $E_{\text{pot}}^g := E_{\text{pot}}(\phi_g^h)$, interaction energy $E_{\text{int}}^g := E_{\text{int}}(\phi_g^h)$ and I^h with $h = 1/8$ and $V(\mathbf{x}) = \frac{1}{2}(x^2 + 4y^2)$ in (1.1) for different β .

Table 10
Different energies of the ground state and l^h for the NLSE with the 2D Coulomb interaction for different β .

β	E_g	μ_g	E_{kin}^g	E_{pot}^g	E_{int}^g	l^h
-10	0.1367	-1.4536	1.2611	4.6592E-01	-1.5903	1.89E-10
-5	0.8698	0.1933	9.4226E-01	6.0401E-01	-6.7651E-01	2.37E-10
-1	1.3808	1.2600	7.8098E-01	7.2058E-01	-1.2080E-01	2.60E-10
1	1.6163	1.7311	7.2201E-01	7.7942E-01	1.1483E-01	-2.61E-10
5	2.0551	2.5801	6.3379E-01	8.9629E-01	5.2501E-01	-2.65E-10
10	2.5557	3.5132	5.5977E-01	1.0385	9.5748E-01	-2.69E-10

Table 11
Errors of the ground state for the NLSE with the 2D Poisson potential with mesh size h .

GF-NUFFT		$h = 1$	$h = 1/2$	$h = 1/4$	$h = 1/8$
$e_{\phi_g}^h$	$\beta = -5$	2.465E-02	1.024E-04	4.699E-10	2.878E-15
	$\beta = 5$	1.191E-02	1.593E-05	9.793E-12	2.726E-15
$e_{\psi_g}^h$	$\beta = -5$	3.737E-02	7.634E-05	2.896E-10	6.347E-14
	$\beta = 5$	1.033E-02	3.282E-06	2.682E-12	6.247E-14

Table 12
Different energies of the ground state and l^h for the NLSE with the 2D Poisson potential for different β .

β	E_g	μ_g	E_{kin}^g	E_{pot}^g	E_{int}^g	l^h
-10	1.3533	1.1432	9.8061E-01	5.8272E-01	-2.1008E-01	2.44E-10
-5	1.4429	1.3691	8.5784E-01	6.5889E-01	-7.3819E-02	2.54E-10
-1	1.4913	1.4819	7.7024E-01	7.3045E-01	-9.3826E-03	2.59E-10
1	1.5073	1.5139	7.3046E-01	7.7025E-01	6.5762E-03	-2.62E-10
5	1.5221	1.5260	6.5959E-01	8.5854E-01	3.9516E-03	-2.70E-10
10	1.5076	1.4420	5.8770E-01	9.8559E-01	-6.5660E-02	-2.81E-10

From Tables 7–12 and additional numerical results not shown here for brevity, we can see that: (i) The *GF-NUFFT* method is spectrally accurate in space, while the *GF-DST* method has a saturation accuracy for a fixed domain; (ii) The saturation error of the *GF-DST* depends inversely on the domain size L , and it can only reach satisfactory accuracy for some large L ; (iii) High accuracy, i.e., 9-digit accurate, is achieved by *GF-NUFFT* as quite expected in the energies, which, in another way, manifest the high-accuracy advantage of our NUFFT solver.

4. For computing the dynamics

In this section, we present an efficient and accurate numerical method for computing the dynamics of the NLSE with the nonlocal interaction potential (1.1)–(1.2) and the initial data (1.3) by combining the NUFFT solver for the nonlocal interaction potential evaluation and the time-splitting Fourier pseudospectral discretization, and compare it with those existing numerical methods [2,10,30,31,37,39].

4.1. A numerical method via the NUFFT

From time $t = t_n$ to $t = t_{n+1}$, the NLSE (1.1) will be solved in two splitting steps. One solves first

$$i \partial_t \psi(\mathbf{x}, t) = -\frac{1}{2} \Delta \psi(\mathbf{x}, t), \quad \mathbf{x} \in \mathbb{R}^d, \quad t_n \leq t \leq t_{n+1}, \tag{4.1}$$

for the time step of length τ , followed by solving

$$i \partial_t \psi(\mathbf{x}, t) = [V(\mathbf{x}) + \beta \varphi(\mathbf{x}, t)] \psi(\mathbf{x}, t), \quad \varphi(\mathbf{x}, t) = (U * |\psi|^2)(\mathbf{x}, t), \quad \mathbf{x} \in \mathbb{R}^d, \quad t_n \leq t \leq t_{n+1}, \tag{4.2}$$

for the same time step. For $t \in [t_n, t_{n+1}]$, Eq. (4.2) leaves $|\psi|$ invariant in t [5,9], i.e., $|\psi(\mathbf{x}, t)| = |\psi(\mathbf{x}, t_n)|$, and thus φ is time invariant, i.e., $\varphi(\mathbf{x}, t) = \varphi(\mathbf{x}, t_n) := \varphi^n(\mathbf{x})$, therefore it becomes

$$i \partial_t \psi(\mathbf{x}, t) = [V(\mathbf{x}) + \beta \varphi^n(\mathbf{x})] \psi(\mathbf{x}, t), \quad \varphi^n(\mathbf{x}) = (U * |\psi^n|^2)(\mathbf{x}), \quad \mathbf{x} \in \mathbb{R}^d, \quad t_n \leq t \leq t_{n+1}, \tag{4.3}$$

where $\psi^n(\mathbf{x}) := \psi(\mathbf{x}, t_n)$, which immediately implies that

$$\psi(\mathbf{x}, t) = e^{-i[V(\mathbf{x}) + \beta \varphi^n(\mathbf{x})](t-t_n)} \psi(\mathbf{x}, t_n), \quad \mathbf{x} \in \mathbb{R}^d, \quad t_n \leq t \leq t_{n+1}. \tag{4.4}$$

Then an efficient and accurate numerical method can be designed by: (i) adopting a second-order Strang splitting [38] or a fourth-order time splitting method [40] to decouple the nonlinearity; (ii) truncating the problem on a bounded computational domain Ω , and imposing the periodic BC on $\partial\Omega$ for the subproblem (4.1); (iii) discretizing (4.1) in space by the

Table 13
Errors of the wave-function and the nonlocal interaction at $t = 1/8$ for the NLSE with the 3D Coulomb interaction.

		$h = 1$	$h = 1/2$	$h = 1/4$	$h = 1/8$
TS-NUFFT					
$e_{\psi}^h(1/8)$	$\beta = -5$	5.461E-03	1.011E-05	9.297E-12	1.492E-13
	$\beta = 5$	3.997E-03	7.879E-06	6.959E-12	1.348E-13
$e_{\varphi}^h(1/8)$	$\beta = -5$	7.890E-03	4.466E-06	4.745E-12	6.992E-14
	$\beta = 5$	6.563E-03	2.828E-06	1.081E-12	6.872E-14
TS-DST					
$e_{\psi}^h(1/8)$	$\beta = -5$	2.561E-02	3.024E-02	3.025E-02	3.025E-02
	$\beta = 5$	2.753E-02	3.024E-02	3.025E-02	3.025E-02
$e_{\rho}^h(1/8)$	$\beta = -5$	5.567E-03	1.444E-05	2.397E-07	2.441E-07
	$\beta = 5$	5.590E-03	1.416E-05	2.560E-07	2.568E-07
$e_{\varphi}^h(1/8)$	$\beta = -5$	1.099E-01	1.099E-01	1.099E-01	1.099E-01
	$\beta = 5$	1.117E-01	1.117E-01	1.117E-01	1.117E-01

Fourier spectral method and integrating in time *exactly*; (iv) evaluating the nonlocal interaction $\varphi^n(\mathbf{x})$ in (4.4) by the algorithm via the NUFFT discussed in previous sections, and integrating in time *exactly* for (4.4). The details are omitted here for brevity and this method is referred to as the *TS-NUFFT* method.

For comparison, for the nonlocal interaction in 3D/2D, when the NUFFT in the above method is replaced by the standard FFT, we refer to the method as *TS-FFT*. In addition, when the nonlocal interaction $\varphi^n(\mathbf{x})$ in (4.4) is reformulated as its equivalent PDE formulation (1.7)–(1.8) on Ω with homogeneous Dirichlet BC on $\partial\Omega$ and then discretized by the sine pseudospectral method with an evaluation of (4.1) via the sine spectral method and integrated in time *exactly* [6,41], we refer to it as *TS-DST*.

4.2. Numerical comparisons

Again, in order to compare the *TS-NUFFT* method with the *GF-DST* method for computing the dynamics, we denote $\rho(\mathbf{x}, t) = |\psi(\mathbf{x}, t)|^2$ and $\varphi(\mathbf{x}, t) = (U * |\psi|^2)(\mathbf{x}, t)$ and introduce the errors

$$e_{\psi}^h(t) := \frac{\max_{\mathbf{x} \in \Omega_h} |\psi(\mathbf{x}, t) - \psi_h^n(\mathbf{x})|}{\max_{\mathbf{x} \in \Omega_h} |\psi(\mathbf{x}, t)|}, \quad e_{\varphi}^h(t) := \frac{\max_{\mathbf{x} \in \Omega_h} |\varphi(\mathbf{x}, t) - \varphi_h^n(\mathbf{x})|}{\max_{\mathbf{x} \in \Omega_h} |\varphi(\mathbf{x}, t)|},$$

$$e_{\rho}^h(t) := \frac{\max_{\mathbf{x} \in \Omega_h} |\rho(\mathbf{x}, t) - \rho_h^n(\mathbf{x})|}{\max_{\mathbf{x} \in \Omega_h} |\rho(\mathbf{x}, t)|}, \quad t = t_n, \quad n \geq 0,$$

where $\psi_h^n(\mathbf{x})$, $\varphi_h^n(\mathbf{x})$ and $\rho_h^n(\mathbf{x})$ are obtained numerically by a numerical method as the approximations of $\psi(\mathbf{x}, t)$, $\varphi(\mathbf{x}, t)$ and $\rho(\mathbf{x}, t)$ at $t = t_n$, respectively with a given mesh size h and a very small time step $\tau > 0$. The external potential in (1.1) and the initial data in (1.3) are chosen as

$$V(\mathbf{x}) = \frac{|\mathbf{x}|^2}{2}, \quad \psi(\mathbf{x}, 0) = \psi_0(\mathbf{x}) = e^{-\frac{|\mathbf{x}|^2}{2}}, \quad \mathbf{x} \in \mathbb{R}^d \text{ with } d = 3 \text{ or } 2. \tag{4.5}$$

In the comparisons, the “exact” solution $\psi(\mathbf{x}, t)$ (and thus $\varphi(\mathbf{x}, t)$ and $\rho(\mathbf{x}, t)$) was obtained numerically via the *TS-NUFFT* method on a large enough domain Ω with very small enough mesh size h and time step τ . In our computations, we use the fourth-order time-splitting method for time integration [40].

Example 4.1 (*The NLSE with the 3D Coulomb interaction*). Here $d = 3$ and $U(\mathbf{x}) = U_{\text{Cou}}(\mathbf{x})$ in (1.1)–(1.2). The problem is solved numerically on a bounded computational domain $\Omega = [-8, 8]^3$ with time step $\tau = 10^{-3}$ and different mesh size h . Table 13 lists the errors of the wave-function, the density and the 3D Coulomb interaction at $t = 1/8$ obtained by the *TS-NUFFT* and *TS-DST* methods for different mesh size h and interaction constant β .

Example 4.2 (*The NLSE with the 2D Coulomb interaction*). Here $d = 2$ and $U(\mathbf{x}) = U_{\text{Cou}}(\mathbf{x})$ in (1.1)–(1.2). The problem is solved numerically on a bounded computational domain $\Omega = [-16, 16]^2$ with time step $\tau = 10^{-4}$ and different mesh size h . Table 14 shows the errors of the wave-function and the 2D Coulomb interaction at $t = 0.5$ obtained by the *TS-NUFFT* and *TS-DST* methods for different mesh size h and interaction constant β .

Example 4.3 (*The NLSE with the 2D Poisson potential*). Here $d = 2$ and $U(\mathbf{x}) = U_{\text{Lap}}(\mathbf{x})$ in (1.1)–(1.2). Again, the problem is solved numerically on a bounded computational domain $\Omega = [-16, 16]^2$ with time step $\tau = 10^{-4}$ and different mesh size h . Table 14 shows the errors of the wave-function and the 2D Coulomb interaction at $t = 0.5$ obtained by the *TS-NUFFT* method for different mesh size h and interaction constant β . We remark here that the *TS-DST* method is not applicable for this case [35,41], therefore here we only present the results for the *TS-NUFFT* method.

Table 14

Errors of the wave-function and the nonlocal interaction at $t = 0.5$ for the NLSE with the 2D Coulomb interaction.

TS-NUFFT ($L = 16$)		$h = 1$	$h = 1/2$	$h = 1/4$	$h = 1/8$
$e_{\psi}^h(0.5)$	$\beta = -5$	1.582E-01	7.468E-03	4.746E-06	2.954E-12
	$\beta = 5$	5.118E-02	7.756E-04	2.476E-10	1.268E-12
$e_{\phi}^h(0.5)$	$\beta = -5$	2.219E-02	4.242E-03	4.169E-06	3.756E-12
	$\beta = 5$	3.235E-02	2.451E-04	3.117E-11	7.586E-13
TS-DST ($L = 16$)		$h = 1$	$h = 1/2$	$h = 1/4$	$h = 1/8$
$e_{\psi}^h(0.5)$	$\beta = -5$	1.175E-01	5.576E-02	6.311E-02	6.312E-02
	$\beta = 5$	6.477E-02	6.308E-02	6.313E-02	6.313E-02
$e_{\phi}^h(0.5)$	$\beta = -5$	4.286E-02	2.449E-02	2.449E-02	2.449E-02
	$\beta = 5$	6.854E-02	4.412E-02	4.455E-02	4.478E-02
TS-DST ($h = 1/8$)		$L = 8$	$L = 16$	$L = 32$	$L = 64$
$e_{\psi}^h(0.5)$	$\beta = -5$	1.263E-01	6.312E-02	3.156E-02	1.578E-02
	$\beta = 5$	1.264E-01	6.313E-02	3.156E-02	1.578E-02
$e_{\phi}^h(0.5)$	$\beta = -5$	4.907E-02	2.449E-02	1.021E-02	4.999E-03
	$\beta = 5$	9.038E-02	4.500E-02	1.875E-02	9.181E-03

Table 15

Errors of the wave-function and the Poisson potential at $t = 0.5$ for the NLSE with the 2D Poisson potential.

TS-NUFFT		$h = 1$	$h = 1/2$	$h = 1/4$	$h = 1/8$
$e_{\psi}^h(0.5)$	$\beta = -5$	5.833E-02	2.599E-04	3.211E-09	7.524E-13
	$\beta = 5$	2.658E-02	9.083E-05	3.395E-12	1.124E-12
$e_{\phi}^h(0.5)$	$\beta = -5$	1.329E-02	8.840E-05	1.072E-09	3.974E-13
	$\beta = 5$	4.645E-03	2.805E-06	8.322E-13	5.821E-13

From Tables 13–15 and additional numerical results not shown here for brevity, we can draw the following conclusions: (i) The *TS-DST*, if applicable, cannot resolve the wave-function or the potential very accurately, while the *TS-NUFFT* achieves the spectral accuracy; (ii) The saturated accuracy by *TS-DST* decreases as the computation domain increases; (iii) As long as for the physical observables, e.g., the density ρ , are concerned, the *TS-DST* method can still capture reasonable accuracy (cf. Table 13).

4.3. Applications

To further demonstrate the efficiency and accuracy of the numerical method via the NUFFT, we simulate the long-time dynamics of the 2D NLSE with the Coulomb interaction, i.e., $d = 2$ and $U(\mathbf{x}) = U_{\text{Cou}}(\mathbf{x})$ and $\beta = 5$ in (1.1)–(1.2), and a honeycomb external potential [9,20] defined as

$$V(\mathbf{x}) = 10[\cos(\mathbf{b}_1 \cdot \mathbf{x}) + \cos(\mathbf{b}_2 \cdot \mathbf{x}) + \cos((\mathbf{b}_1 + \mathbf{b}_2) \cdot \mathbf{x})], \quad \mathbf{x} = (x, y)^T \in \mathbb{R}^2, \tag{4.6}$$

with $\mathbf{b}_1 = \frac{\pi}{4}(\sqrt{3}, 1)^T$ and $\mathbf{b}_2 = \frac{\pi}{4}(-\sqrt{3}, 1)^T$. This example can be formally used to describe the dynamics of the electrons in a graphene. The initial data in (1.3) is taken as $\psi_0(x, y) = e^{-(x^2+y^2)/2}$ for $\mathbf{x} \in \mathbb{R}^2$ and the problem is solved numerically on $\Omega = [-32, 32]^2$ by using the *TS-NUFFT* with mesh size $h = \frac{1}{16}$ and time step $\tau = 10^{-4}$. Fig. 3 shows the contour plots of the density $\rho(x, y, t)$ at different times.

5. Conclusion

An efficient and accurate numerical method via the NUFFT was proposed for the fast evaluation of different nonlocal interactions including the Coulomb interactions in 3D/2D and the interaction kernel taken as either the Green’s function of the Laplace operator in 3D/2D/1D or nonlocal interaction kernels in 2D/1D obtained from the 3D Schrödinger–Poisson system under strongly external confining potentials via dimension reduction. The method was compared extensively with those existing numerical methods and it was demonstrated that it can achieve much more accurate numerical results, especially on a smaller computational domain and/or with anisotropic interaction density. Also, efficient and accurate numerical methods were presented for computing the ground state and dynamics of the NLSE with nonlocal interactions. These methods combine the NUFFT based method for interaction evaluation with the normalized gradient flow method for ground state computation and/or time-splitting Fourier pseudospectral method for dynamics simulation, respectively. Extensive numerical comparisons with other existing methods were then carried out. Numerical results showed clearly that the NUFFT based methods outperform those existing methods in terms of accuracy and efficiency, especially when the computational domain is chosen smaller and/or the solution is anisotropic.

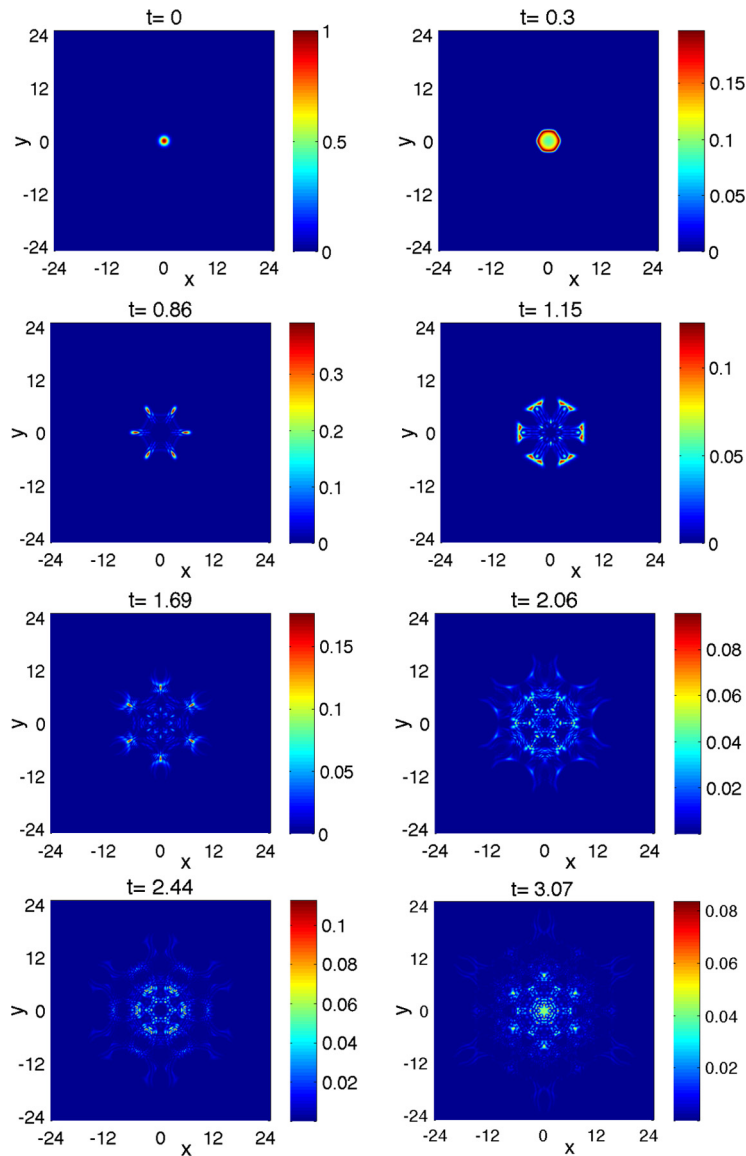


Fig. 3. Contour plots of the density $\rho(x, y, t)$ of the NLSE with the Coulomb interaction and a honeycomb potential in 2D at different times.

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