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15 Coordinated intensification to reconcile the 'zero hunger' and 'life on land' Sustainable

16 Development Goals

17 Abstract

18 The Sustainable Development Goals (SDGs) encourage nations to substantially increase food 19 production to achieve zero hunger (SDG 2) while preserving life on land (SDG 15). A key question is 20 how to reconcile these potentially competing goals spatially. We use integer linear programming to 21 develop an 'integrated land use planning framework' that identifies the optimal allocation of 17 22 crops under different hypothetical conservation targets while meeting agricultural demands by 23 2030. Intensifying existing cropland to maximum yield before allocating new cropland would reduce 24 land requirement by 43% versus cropland expansion without intensification. Even with yield gap 25 closure, tropical and sub-tropical crops still require expansion, primarily allocated to Venezuela, 26 eastern Brazil, Congo Basin, Myanmar and Indonesia. Enforcement of protected areas, via avoiding 27 conversion in 75% of Key Biodiversity Areas and 65% of intact areas, is vital to attain biodiversity 28 targets but bears large opportunity costs, with agricultural rents dropping from \$4.1 to \$2.8 trillion. 29 Although nationally constrained forest conservation efforts would earn 9% less agricultural rents 30 compared to globally coordinated conservation solutions, they reduced intact habitat and forest loss 31 (43 and 35% reduction). Our results demonstrate that careful choice of the allocation of future 32 cropland expansion, could dramatically reduce—but not eliminate—the tradeoffs between the SDGs 33 for food production and land biodiversity conservation.

34 Keyw

Keywords: land-use systems; agricultural intensification; telecoupling; spatial optimization.

35 Earth is undergoing a global biodiversity crisis, with one of the main causes being rampant habitat 36 loss. Over 2.3 million km² of forest has been lost since 2000 (Hansen et al., 2013), and as a result, 37 about one million species are currently threatened with extinction (Diaz et al., 2019). The 38 biodiversity crisis occurs in parallel with 795 million people suffering from food insecurity (Von 39 Grebmer et al., 2016). In response to these challenges, world leaders committed to the Sustainable 40 Development Goals (SDGs) in 2015, which aim to eradicate hunger (SDG 2 zero hunger) and poverty 41 from the planet by 2030 (United Nations, 2017). At the same time, the SDGs also aim to preserve 42 and enhance natural life on land and water (SDGs 14 and 15) (Griggs et al., 2013).

43

Eradicating global hunger and poverty, while meeting ever-increasing food demands, requires
substantially increasing food production (Godfray et al., 2010), as well as broad-scale societal
changes, including reduced food waste, reduced over-consumption, and reduced meat consumption.
Increasing food production is—through more demand for agricultural land—necessarily at odds with
enhancing and protecting biodiversity (Gao and Bryan, 2017; Phalan et al., 2011).

49

50 Strong inherent trade-offs between SDGs 2 and 15 make coordinated implementation challenging. 51 Integrated cross-sectoral analyses have identified trade-offs and operating spaces to attain 52 sustainable outcomes nationally (e.g. Collste et al., 2017; Gao and Bryan, 2017 in Tanzania and 53 Australia respectively) and globally (Obersteiner et al., 2016; Pastor et al., 2019). For instance, Obersteiner et al. (2016) revealed that policies targeting sustainable consumption and production 54 55 (SGD12) are the most effective ones to alleviate trade-offs between environmental conservation and 56 food production. Although the interconnectedness between the SDGs and the trade-offs that competing SDGs would impose on nature are increasingly recognized (McGowan et al., 2019; Nerini 57 58 et al., 2018), a key question is how social and environmental SDGs can be simultaneously achieved 59 spatially.

61	Conservation planning may reconcile competing objectives through spatial optimization that either
62	minimizes conservation costs while achieving biodiversity targets, or maximizing biodiversity gains
63	given a limited conservation budget (Delavenne et al., 2012; Hermoso et al., 2010; Levin et al., 2013;
64	Nhancale and Smith, 2011). Here we expand conservation planning into 'integrated land use
65	planning' by integrating biodiversity (SDG 15 life on land) and food provision targets (SDG 2 Zero
66	Hunger) within the same spatial optimization framework. As closing yield gaps is likely insufficient to
67	meet future food demands (Tilman et al., 2011), it is necessary to study where to put new cropland
68	while preserving biodiversity once yield gaps are closed.
69	
70	We use this integrated land use planning framework to: (i) identify which crops, after yield gap
71	closure, still require cropland expansion; (ii) identify where future crop expansion should occur to
72	reconcile conservation and food production; (iii) explore the trade-offs between agricultural rents of
73	food production and conservation targets; and (iv) compare the outcomes between nationally
74	constrained and globally coordinated strategies for limited deforestation.
75	
76	Our optimization used integer linear programming combined with geographic information systems
77	to movimize agricultural rante globally from 17 erons that are the greatest in terms of area and value
//	to maximize agricultural rents globally from 17 crops that are the greatest in terms of area and value
78	(banana, beans, cassava, cocoa, coconut, coffee, cotton, cowpea, groundnut, maize, millet, oil palm,
79	rice, sorghum, soybean, sugarcane, and wheat). We assumed that yield gaps would first be closed in
80	existing cropland for the 17 crops prior to further habitat conversion to agriculture (see <i>Methods</i>).
81	The maximization was subject to meeting global demands for each crop by the 2030 target for the
82	SDGs under four hypothetical scenarios: (Table 1, see Methods): i) cropland expansion is possible in
83	any available land after existing yield gaps are closed (baseline scenario I); ii) similar to the baseline

84 scenario I but cropland is not intensified to close yield gaps before cropland expansion (baseline 85 scenario II); iii) forests cannot be reduced by more than 5% at the global (forest conservation 86 scenario I) or vi) at the national (forest conservation scenario II) levels. We evaluate each optimal 87 spatial solution of where to allocate new cropland under each scenario in terms of area converted 88 (in different habitat types and conservation protection status), agricultural rents generated, and 89 projected number of birds and mammals to become extinct globally due to conversion using species-90 area relationship models. Results here are not predictions of what will happen in the future, but are 91 projected social and environmental outcomes under different hypothetical scenarios.

92

93 Results

94 Which crops need expansion and where should they go?

95 Closing yield gaps across existing crop distributions under baseline scenario I would be able to meet

96 2030 demand of most crops except for the tropical and sub-tropical crops of banana, cassava,

97 coconut, cotton, oil palm and sugarcane, thus requiring further cropland expansion. The deficit in

98 demand would be highest for sugarcane, cassava and oil palm (433, 80, and 48 million tons,

99 respectively, Table S1). Cotton and sugarcane were the crops that required the most land to meet

100 their future demands (collectively around 53% of total new cropland area, Fig. 1).



Fig. 1. New cropland allocation maps according to the optimization model showing where cropland
cultivating each crop should be allocated to maximize rent subject to environmental and human
food demand constraints in the a) baseline scenario I; b) baseline scenario II; c) forest conservation
scenario I; and d) forest conservation scenario II. Only regions with new cropland allocation are
shown on the map.

109	To meet the deficit in demand, across the four different scenarios, the spatial patterns of new
110	cropland allocation collectively exhibited some similarities. Locations selected for cropland
111	expansion were mainly along the tropical belt including the Guiana Shield (mainly Venezuela), the
112	Brazilian Shield, the Western African coast, Eastern African plateaus and valleys, and South-east Asia
113	(SEA) (Fig. 1). Across continents, South America had most cropland allocation while Europe and
114	Oceania had the least (Fig. 2). Conversely, in the baseline scenario II with no intensification before
115	cropland allocation, there were much larger-scale land allocation in Africa and SEA. In the forest
116	conservation scenario I that required global coordination, new cropland shifted away from
117	Venezuela to SEA (Myanmar, Laos, and Indonesia) and Africa (Democratic Republic of Congo,
118	Ethiopia, Zimbabwe, Mozambique, and Madagascar, Fig. 1). These are areas with high potential
119	agricultural rents (high potential yields and low production costs; Fig. S1) for the crops requiring
120	further production. In addition, when forest conservation was set as national targets in forest
121	conservation scenario II, new cropland allocation was scattered across more countries instead of
122	being concentrated in a just a few countries.



Fig. 2. Area lost due to new cropland allocation in each continent in each scenario. Forest I=Forest conservation scenario I (global coordination); and Forest II=Forest conservation scenario II (national constrained). No allocation in the Antarctic and the Oceania. Allocation in Europe was not shown in the graph since it has new cropland only in the baseline scenario II (0.04 million hectare).

132

133 Trade-offs between different conservation targets

134 Comparison between the baseline scenario I and baseline scenario II revealed the effectiveness of

135 intensification in terms of reducing habitat loss (from 211 Mha to 121 Mha) and species loss (from

136 54.93 to 23.67 bird species and from 4.77 to 1.97 mammal species extinctions) (Table 2 & Fig. 3).

- 137 Although less PAs and intact habitats were converted after yield gap closure in baseline scenario I
- due to less new cropland required, their increased proportional contribution to total converted area
- 139 (from 57% to 67%, and from 23% to 32%, respectively) indicated that these areas are prioritized
- 140 during the new cropland allocation process. This suggested that PAs and intact habitats might have

- 141 high potential to generate large agricultural rents the tropics (see SI for additional conservation
- 142 scenarios that also reflected this pattern).

	Baseline	Baseline II	Forest	Forest
Scenario	I		conservation I	conservation II
Total area (×10 ⁸ ha)	1.21	2.11	1.13	1.01
Rent (×10 ¹²)	4.09	12.75	2.57	2.34
Area of intact habitat (×10 ⁷ ha)	3.91	4.75	1.01	0.58
Area of forest (×10 ⁷ ha)	8.19	14.31	7.75	5.08
Area of grassland (×10 ⁷ ha)	1.58	2.75	1.32	2.16
Area of shrubland (×10 ⁷ ha)	1.76	2.96	1.85	2.34
Area of wetland (×10 ⁶ ha)	1.92	2.66	1.83	2.38
Area of PAs (×10 ⁷ ha)	8.1	12.03	0	0
Area of KBAs (×10 ⁷ ha)	2.74	4.26	0	0
Number of bird species extinct	23.67	54.93	10.12	13.45
Number of mammal species extinct	1.97	4.77	1.98	1.58

143 Table 2. Characteristics of portfolios selected with different conservation strategies to maximize

agricultural rent, considering human food demand and environmental constraints. Rent is in 2016

145 USD.



Fig. 3. Percentage of species loss (bird and mammal combined) in each ecoregion due to new
cropland allocation in the a) baseline scenario I; b) baseline scenario II; c) forest conservation
scenario I; and d) forest conservation scenario II. Only regions with new cropland allocation are
shown on the map.

154	When forest conservation is globally coordinated (forest conservation scenario I), via forest
155	avoidance and PA exclusion, conversion shifted mainly to shrubland habitats. While total area
156	converted was reduced slightly compared to the baseline scenario I (from 121Mha to 113 Mha), the
157	drop in agricultural rent was more dramatic (from \$4.09 to \$2.57 trillion), suggesting the higher rent
158	generation potential of forests compared to shrubland in general. Forest conservation and PA
159	exclusion also showed high capacity to protect intact habitat and reduce species loss (Table 2). The
160	additional PA exclusion scenarios presented in SI illustrated that exclusion of PAs alone from
161	conversion also reduced Key Biodiversity Area (KBAs) conversion (Tables S2 & Table S3) from 27 to 7
162	million hectares of converted KBAs with respect to baseline scenario I under with yield gap closure.
163	
164	Globally coordinated versus nationally constrained conservation
165	In the forest conservation scenario I (where globally forest loss should be less than 5%), there were
166	19 countries with more than 5% loss of forests within their territories. They were mainly African
167	countries and Republic of Congo had the largest gap between the actual and 5% threshold loss (Fig.
168	4). Compared to the forest conservation scenario II (no nation could lose more than 5% of its
169	forests), global forest conservation had higher agricultural rents generated (from \$2.34 to \$2.57
170	trillion) and better bird species conservation performance, with bird species extinction numbers
171	lowered from 13.45 to 10.12 (Table 2 & Fig. 3).



Fig. 4. Countries with more than 5% forest loss in the forest conservation scenario I when the less
than 5% forest loss is set as a global target without national constraints. The 'threshold' column
shows the maximum amount of forest could be lost in each country according to a less than 5%
forest loss criteria, the 'actual' column shows actual forest loss in each country due to allocation of
new cropland.



189 Discussion

Our results show that new cropland would need to be located mainly along the tropical belt, where most of the unused, suitable land for agriculture resides (Gibbs et al., 2010). Needing to place future cropland in hyper diverse tropical regions implies a direct confrontation between food production (SDG 2) and life on land (SDG 15). But despite the tradeoff between SDGs 2 and 15 in the tropics, our results suggest that careful planning of the locations where new cropland is allocated can substantially reduce impacts on biodiversity.

196

197 The first fundamental step to reduce the tradeoff is enhanced protected area management in the 198 tropics. Our results demonstrate that, relative to the baseline, agricultural demands could be met 199 with about one third of intact habitat area loss, one quarter of KBAs area loss and two thirds of 200 projected bird extinctions if protected areas are excluded from conversion (comparing baseline 201 scenario I against PA exclusion scenario). The key role of protected areas in protecting tropical 202 biodiversity and constraining agricultural expansion contrasts with previous research suggesting that 203 PAs are biased towards higher altitude, steeper slopes, and further distances to roads (Joppa and 204 Pfaff, 2009). This shows that the tropical fraction of the PA network does focus on halting declines of 205 biodiversity under imminent threats and that tropical PAs are facing a tremendous pressure for 206 agricultural conversion. This would explain pervasive encroachment within protected areas 207 (Spracklen et al., 2015) and of protected area downgrading, downsizing, and degazettement 208 (PADDD) due to agricultural conversion (Kroner et al., 2019; Symes et al., 2016). Therefore, tropical 209 protected area management—protection from direct conversion and protection from 210 degazettement and then conversion—should be a top priority if tradeoffs between SDGs 2 and 15 211 are to be mitigated. For example, a global convention on no PADDD or effective PAs enforcement for 212 at least 30 years would be fundamental for reconciliation of SDGs 2 and 15.

214 Despite improved outcomes for biodiversity and habitat protection associated with enhanced 215 protected area management scenario (PA exclusion scenario in SI), the scenario carries a substantial 216 economic cost. Agricultural rents could be reduced by half owing to higher production costs because 217 less accessible areas are converted. This suggests food would be costlier, which could undermine 218 zero hunger (SDG 2), increase inequality (SDG 10, costlier food would be harder to afford by lower 219 income communities), and restrict economic growth (SDG 8). Studying these ramifications would 220 require further research with multi-sectoral economic models (Obersteiner et al., 2016; Pastor et al., 221 2019). For example, a recent study has suggested optimization frameworks to consider the trade-222 offs among conservation (SDG 15), equity (SDG 10), and climate change (SDG 13) (Palomo et al., 223 2019).

224

225 The results show that, while the nationally constrained solutions (forest conservation scenario II) 226 greatly reduced forest (35% less) and intact habitat (43% less) conversion, they have relatively less 227 deviation from the globally coordinated efforts (forest conservation scenario I) in terms of 228 agricultural rent losses (12% lower) and biodiversity losses (32% greater bird species extinction but 229 20% less mammal species extinction). This is in contrast to a previous study on land use planning for 230 sustainable intensification, which found that globally coordinated plans could reduce much more 231 projected biodiversity loss (Egli et al., 2018). The globally coordinated biodiversity conservation plans 232 depicted could be unrealistic because they require agreement across multiple nations. National-233 constrained solutions compared with globally coordinated optimal solutions allows evaluating the 234 feasibility of the interventions while respecting national sovereignties in terms of biodiversity 235 conservation (Runting et al., 2015). Our results also show that reconciling SDGs 2 and 15 could 236 largely depend on a few tropical nations for additional food production (e.g. Venezuela, Brazil, DRC, 237 Mozambique, Myanmar, Laos, Indonesia). While this would undoubtedly make coordination easier

than a global response, coordination among these countries still face challenges (Mason et al.,
2020). In addition, complimentary strategies are required to make sure that habitats spared from
cropland expansion in other countries are to be conserved instead of being lost to other activities
(Phalan et al., 2016). Payment for Ecosystem Services schemes, including Reducing Emissions from
Deforestation and Forest Degradation (REDD+), could play a key role (Phelps et al., 2013).

243

244 Future cropland expansion that minimizes tradeoffs between SDG 2 and 15 could concentrate in a 245 few tropical nations, suggesting these nations would receive the majority of the agricultural rents at 246 the expense of their natural capital. This allocation may neither be an equitable solution in terms of 247 employment or income generation. It may also be at odds with the national food security policies of 248 other nations, leading to more scattered food production and less-than-optimal biodiversity 249 outcomes (Agarwal, 2014). For example, Senegal is investing heavily in the rice sector to gain self-250 sufficiency (Diagne et al., 2013) although it is not the best location to produce rice according to our 251 integrated land use planning results. In addition, factors such as lack of political stability might 252 influence the ability of a region to close yield gaps by creating barriers to investment, infrastructure, 253 new technology or new crop varieties (Erb et al., 2012; Kimenyi et al., 2014).

254

255 Our models presented the potential trade-offs and synergies between SDG2 and SDG15 and compared 256 different hypothetical conservation strategies. However, there are several fundamental limitations. 257 Firstly, besides the scenarios presented here, conservation agriculture (Kassam et al., 2019) and 258 shared landscapes (Ellis and Mehrabi, 2019) are other potential strategies to reconcile these two goals 259 and worth further research. In addition, although our model has the ability to generate polyculture 260 results if planning units are tiny enough, this requires extremely high computational power and high-261 resolution data sources. Therefore, current cropland allocation patterns have to remain to be 262 monoculture if considering individual planning unit. Moreover, model outputs are likely to vary if 263 parameter estimates used in the models were different or assumptions were violated. For example, 264 crop yield closure could be a long time effort, climate change might affect potential yield, and other 265 measures such as mixed cropping could also increase crop production. Crop demand is likely to vary if 266 future demand does not follow past trends. Fuel cost and driver cost would also change when crops 267 are transported to international markets instead of nearest large cities. Economies of scale might 268 affect crop price and productions costs. We therefore conducted a sensitivity analysis through 269 increasing and decreasing individual parameter values by 10% under the baseline scenario I condition 270 (see Supplementary Information Figure S6 for the results). The sensitivity analysis, in comparison with 271 baseline scenario I results, showed that model outputs are most sensitive to the uncertainty of future 272 crop demand, crop price, and crop yield. Variation could be as high as around 40% of original values if 273 demand diverged by 10%. This means that when the assumption that demand would follow its 274 historical trend is violated, it could change the results the most, possibly because varying demand 275 means converting much more/less lower-fertility land. This is a plausible scenario considering new 276 demand of crops are emerging, but demand is less likely to diverge too much within only 10 years. 277 Uncertainty of estimates on the other parameter values has very limited influences, mostly below 3%. 278 In particular, the influence of capital, fuel and driver cost value uncertainties on model outputs are 279 almost negligible. This sensitivity analysis indicate that it is most critical to better estimate values of 280 crop demand, price, and future yield to improve projection accuracy. Future research on data 281 collection should give these parameters high priority.

282

283 Conclusion

We developed an integrated land use planning modelling framework to reconcile agricultural
production and biodiversity conservation (SDGs 2 and 15) under different hypothetical scenarios.
Yield gap closure could save a large amount of land, and thus greatly reduce species extinction. The
five crops that would require further expansion by 2030, even if yields gaps are closed, are tropical

288	crops. Protected areas are key to attaining the biodiversity targets by resisting conversion pressure				
289	associated with large agricultural opportunity costs to ensure that intact areas and KBAs remain. We				
290	show that although globally coordinated conservation solutions attain higher agricultural rents and				
291	less bird species extinction, politically more feasible nationally constrained solutions are able to				
292	greatly reduced intact habitat and forest loss without a large reduction of agricultural rents. Our				
293	results thus demonstrate that the careful design of the future cropland allocation could dramaticall				
294	reduce the tradeoffs between the SDGs for food production and land biodiversity conservation.				
295					
296	Conflict of interest				
297	The authors declare no conflicts of interests.				
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302					
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422 Methods

423 Overview

424 We created a human-centred integrated land use planning model to plan for the distribution of new 425 cropland. In this model, we aimed to maximize the amount of agricultural rents received by farmers, 426 within constraints of both human crop demand satisfaction and conservation targets achievement. 427 Maximising agricultural rents ensures cropland occur in areas where it generates the most profit 428 (such as via lower production and transport costs). We used integer linear programming to find the 429 optimal solution and applied the model to four different hypothetical scenarios with various 430 conservation criteria to investigate their influences on new cropland allocation. We conducted data 431 extraction and all spatial analysis in ArcMap (version 10.3) and used the Gurobi package (version 8.1) 432 (Gurobi optimization LLC, 2019) in R (version 3.6.1) for optimization (R Core Team, 2019). We 433 ensured that all the maps were in the same projected coordinates system before performing any 434 spatial analysis.

435

436 Planning units

437 We created a grid with 0.25-degree resolution in ArcMap to divide the terrestrial area in the world 438 into 245,508 planning units (approximately 28×28km at the equator but size varies according to 439 coordinates). We intersected the planning units map with land cover map to get land cover data 440 within each planning units. We excluded those planning units with land cover types not suitable for 441 conversion to new cropland, including current cropland, water bodies, snow or ice, and artificial 442 areas. Global land cover was obtained from the Climate Change Initiative Land Cover (CCI_LC) year 2014 map (Climate Change Initiative Land Cover Team, 2017). After the exclusions, there were 443 444 157,231 planning units left susceptible of being converted to cropland. These planning units spanned

over 25 different types of land uses (see Supplementary Information Table S4). We then calculated
the area available for conversion within each planning unit.

447

448 Biological data

449 The analysis used four types of biological data: a key biodiversity areas (KBA) map (BirdLife

450 International, 2017) to represent biodiversity at the broader scale; a forest distribution map adapted

451 from the CCI_LC map through combining several land cover types (see Supplementary Information

452 Table S4); a protected area (PA) map (UNEP-WCMC, 2016) to show the distribution of the current

453 reserve network; and an intact habitat map derived based on human footprint maps (Venter et al.,

454 2016).

455

We intersected the KBA map with the planning units map to derive the area of KBAs that overlapped with each planning unit. We also calculated the area of forest in each planning unit through spatially intersecting the maps. Intact habitats were defined as areas without presence of any of the eight individual human pressures considered in the human footprint assessment (Allan et al., 2019) (see Supplementary Information table S5).

461

462 Anthropogenic data

We selected three anthropogenic variables to describe human needs on nature: human crop
demand, crop production, and agricultural rents. We considered the 17 globally most important
crops based on their economic importance and area of production (banana, beans, cassava, cocoa,
coconut, coffee, cotton, cowpea, groundnut, maize, millet, oil palm, rice, sorghum, soybean,
sugarcane, and wheat) (Leff et al., 2004; Phalan et al., 2013). In total, these crops accounted for
around 65% of total global crop production in year 2016 (FAO, 2017). We obtained projected human

demand for each of the 17 crops by the year 2030 (the timeline for the SDGs) under business-asusual scenario from the Food and Agriculture Organization of the United Nations (FAO) projections
(FAO, 2018). Maximum crop production in each planning unit of each crop was based on crop
potential yield (International Institute for Applied Systems Analysis, 2015). The potential production
in each planning unit, if converted to cropland, was then obtained by multiplying the potential yield
with the area available for conversion within each planning unit.

475

476 We calculated net annual agricultural rents (*AR*) for each crop *j* in each planning unit *i* as follows:

477
$$AR_{ij} = (p_j y_{ij} - w_i l_{ij} - r_i u_i k_i - trans_{ij}) \times a_i$$
(1)

478 where p is the crop price ($\frac{1}{y}$ is the crop potential yield (ton/ha·year), w is the labor wage 479 $(\frac{1}{2})$, *i* is the person-days to produce the crop (days/ha·year), *r* is the price of the tractor at the 480 time of purchase ($\frac{1}{2}$ tractor), u is the proportion of the tractor life span in one year of use, k is the 481 quantity of capital input required (tractor/ha·year), trans is the transportation cost to transport the 482 crop from farm to the market (\$/ha·year), and a is the conversion available area of each planning 483 unit (in ha). Tractor cost is used as a proxy of capital cost for agricultural production, for which we 484 assumed life span of 10 years with costs annualized to get the annual depreciation in capital asset 485 value. Details of agricultural rent calculation were presented in the Supplementary Information.

486

487 Systematic sustainability planning model

We used the Gurobi package in R to identify the best allocation patterns for new cropland spatially.
Gurobi uses several algorithms, including simplex and branch and bound, to solve integer linear
programming problems and is guaranteed to find the optimal solution if enough time is given.
Therefore, it always produces the same spatial solution for a given set of inputs to meet the
specified targets in our formulation. In this study, we used it to find an optimal new cropland

allocation by maximizing an objective function where both conservation needs and human fooddemands were considered as constraints.

495

496 The optimization problem maximized the amount of agricultural rent (AR) earned from all *N*

497 planning units. This optimization was subject to ensuring the loss of each of K conservation features

498 below certain thresholds (*T_k*) (i.e. a certain amount of each conservation feature was retained). In

499 addition, it required enough crop production to satisfy future agricultural demand (d) for each of J

500 crops:

501 maximize
$$\sum_{i}^{N} \sum_{j}^{J} AR_{ij} x_{ij}$$

502 subject to
$$\sum_{i}^{N} \sum_{j}^{J} r_{ik} x_{ij} \leq T_{k}$$
, $\forall k \in K$,

503
$$0.9d_j \le \sum_i^N s_{ij} x_{ij} \le 1.1d_j, \qquad \forall j \in J$$

504
$$\sum_{i}^{j} x_{ij} \leq 1,$$

505 $x_{ij} \in \{0,1\}$ (2)

 $\forall i \in N$,

where x_{ij} is a binary variable and represents whether planning unit *i* is allocated to crop *j* (x_{ij} =1) or not (x_{ij} =0). AR_{ij} is the agricultural rent generated by converting a planning unit *i*)to crop *j* (see eqn. 1) and r_{ik} measures the loss of each conservation feature due to the conversion. We used s_{ij} to represent production quantity of crop *j* in planning unit *i*. We allowed a ± 10% divergence from the actual demand to facilitate finding an approximate solution. We assumed that only one crop would grow in each planning unit after the conversion, occupying the entire area available for conversion. This is enforced by the third and fourth constraints.

514 Species extinction estimation

We estimated possible endemic bird and mammal species extinction rate due to projected new
cropland allocation according to the countryside species-area relationship (SAR) model (Chaudhary
et al., 2015; de Baan et al., 2013). It was limited to birds and mammals due to data paucity for other
taxa.

519
$$S_{lost,g,e} = S_{org,g,e} \left[1 - \left(\frac{A_{new,e} + \sum_{l=1}^{L} h_{g,l,e} \times A_{l,e}}{A_{org,e}} \right)^{z_e} \right]$$
 (3)

where $S_{lost, g, e}$ is the number of species loss of taxa g due to new cropland allocation in ecoregion e, $S_{org, g, e}$ is the original number of species that would have occurred in natural habitat area $A_{org, e}$ in the ecoregion e, $A_{new, e}$ is the remaining natural habitat area after projected cropland allocation, $A_{l, e}$ is the updated area of each land use type l in each ecoregion, z_e is a constant assigned to each ecoregion, and $h_{g, l, e}$ is the affinity of each taxa g for land use type l in ecoregion e. It was calculated based on the local land occupation characterization factor $CF_{loc, g, le}$ as,

526
$$h_{g,l,e} = (1 - CF_{loc,g,le})^{1/z_e}$$
 (4)

We obtained *CF_{loc,g,le}* and *z_e* data from previous studies by de Baan et al. (2013) and Chaudhary et al.
(2015). We mapped area of each land use type before and after new cropland allocation based on
the human land use map from Ellis and Ramankutty (Climate Change Initiative Land Cover Team,
2017). We got endemic species richness data for each ecoregion from WildFinder (World Wildlife
Fund, 2006) and World Wildlife Fund provided the ecoregion distribution data (Olson et al., 2001).

532

533 Scenarios

- 534 We considered four different scenarios with various possible conservation targets to investigate how
- they influence new cropland allocation patterns (Table 1).

Scenario	Yield gap	PA	КВА	Conserva	Scale of
	closure	conversion	conversion	tion	target
				features	application
Baselines					
I. (Close yield gap first,	Yes	Yes	Yes	NA	Global
unconstrained expansion)					
II. (Do not close yield gap	No	Yes	Yes	NA	Global
first, unconstrained					
expansion)					
Forest conservation					
I. (Globally coordinated)	Yes	No	No	Forest	Global
II. (Nationally constrained)	Yes	No	No	Forest	National

536Table 1. Description of each scenario settings. Additional conservation scenarios are included in the

537 supplementary information.

538

539 Baseline I: Existing cropland was intensified to produce the maximum yield before allocating new

540 cropland. New cropland could be allocated anywhere as long as current land cover types are suitable

541 for agricultural production.

542 Baseline II: Existing cropland was not intensified and produce at the current production levels before

allocating new cropland. The other conditions remained the same as in the baseline scenario.

- 544 Forest conservation I: We added forests as a conservation feature and required that the overall loss
- of forests to be less than 5% of the total global forest area. We also did not allow conversion of any
- 546 PAs. The other conditions remained the same as in the baseline scenario.

Forest conservation II: The conservation threshold in this scenario was set for each individual country
instead of considering the world as a whole. Therefore, every single country needed to ensure loss
of forests in their country boundary to be less than 5%. The other conditions remained the same as
in the global forest conservation scenario.

551

552 Besides the abovementioned four scenarios, under the precondition of yield gap closure, we ran four

additional conservation scenarios (PA exclusion, biodiversity conservation, intact habitat exclusion,

and ecoregion habitat conservation) to explore optimization outcomes under different contexts.

555 Moreover, under the precondition of no yield gap closure (maintaining current production level), we

ran six pairing scenarios (PA exclusion, biodiversity conservation, intact habitat exclusion, forest

557 conservation I, forest conservation II, and ecoregion habitat conservation). All of them are presented

558 in the Supplementary Information.