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Numerical modeling of first experiments on PbLi MHD flows in a rectangular duct with foam-based SiC flow channel insert



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HIGHLIGHTS

- Numerical studies were performed as a pre-experimental analysis to the experiment on MHD PbLi flows in a rectangular duct with a flow channel insert (FCI).
- Dynamic testing of foam-based SiC foam-based CVD coated FCI has been performed using MaPLE facility at UCLA.
- Two physical models were proposed to explain the experimental results and 3D and 2D computations performed using COMSOL, HIMAG and UCLA codes.
- The obtained results suggest that more work on FCI development, fabrication and testing has to be done to assure good hermetic properties before the implementation in a fusion device.

A R T I C L E I N F O

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ABSTRACT

A flow channel insert (FCI) is the key element of the DCLL blanket concept. The FCI serves as electrical and thermal insulator to reduce the MHD pressure drop and to decouple the temperature-limited ferritic structure from the flowing hot lead-lithium (PbLi) alloy. The main focus of the paper is on numerical computations to simulate MHD flows in the first experiments on PbLi flows in a stainless steel rectangular duct with a foam-based silicon carbide (SiC) FCI. A single uninterrupted long-term (~6500 h) test has recently been performed on a CVD coated FCI sample in the flowing PbLi in a magnetic field up to 1.5 T at the PbLi temperature of 300 °C using the MaPLE loop at UCLA. An unexpectedly high MHD pressure drop measured in this experiment suggests that a PbLi ingress into the FCI occurred in the course of the experiment, resulting in degradation of electroinsulating FCI properties. The ingress through the protective CVD layer was further confirmed by the post-experimental microscopic analysis of the FCI. The numerical modeling included 2D and 3D computations using HIMAG, COMSOL and a UCLA research code to address important flow features associated with the FCI finite length, fringing magnetic field, rounded FCI corners and also to predict changes in the MHD pressure drop in the unwanted event of a PbLi ingress. Two physical/mathematical models have been proposed and 3D and 2D computations performed to explain the experimental results. Although the computations do confirm that the SiC FCI can significantly reduce the MHD pressure drop, these first testing results that yet do not match the theoretical predictions, suggest that more work on the FCI development and testing is still needed, first of all to ensure that the FCI can withstand PbLi ingress in a long run.

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1. Introduction

A Dual-Coolant Lead-Lithium (DCLL) blanket is an attractive breeding blanket concept that leads to a high-temperature (T \sim 700 °C), high thermal efficiency ($\eta > 40\%$) blanket system [1].

http://dx.doi.org/10.1016/j.fusengdes.2016.04.035 0920-3796/© 2016 Elsevier B.V. All rights reserved. A flow channel insert (FCI) is the key element in this blanket concept, which serves as an electrical insulator to reduce the magnetohydrodynamic (MHD) pressure drop in the lead-lithium (PbLi) flows and also to decouple the temperature-limited RAFM (reduced activation ferritic/martensitic steel) structure from the flowing high-temperature PbLi breeder (Fig. 1).

Historically, the first low-temperature (LT) DCLL blanket design [2] employed a "sandwich-type" FCI as an electrical insulator. This sandwich FCI consists of an insulating alumina layer embedded

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Fig. 1. Schematics of the poloidal DCLL duct with the FCI and He-cooled structure. The FCI is seated loosely inside the RAFM duct forming a thin gap with the duct walls. Both the gap and the space inside the FCI have the flowing PbLi breeder/coolant. The FCI may have a pressure equalization slot or holes.

between two protecting layers of steel. In the more advanced hightemperature (HT) DCLL blanket [3], an FCI made of low-conductivity silicon carbide (SiC) ceramics was proposed for both electrical and thermal insulation. A sandwich-type FCI was tested in the past [4]. The tests demonstrated the anticipated reduction of the MHD pressure drop in MHD flows in a long duct subject to a transverse magnetic field. However, compared to a SiC FCI, the sandwich FCI has a smaller design window, is less effective as electrical insulator, and cannot serve as a thermal insulator. Also, the impact of corrosion on the protecting layers of steel and stability of insulating oxide ceramics in nuclear environment need to be addressed. At the same time, the expected advantages of the SiC FCI, e.g. significant reduction of the MHD pressure drop, were demonstrated only in computations [5]. As a matter of fact, only one experimental study [6] has been conducted to characterize the effect of a mono-material FCI on the MHD pressure drop. However, in this experiment substitute materials were used: the FCI was made of epoxy and a room-temperature liquid metal galinstan was used as a working fluid. The results of this experiment were found to be different from the 2-D computational predictions [6], but later, a good match with the theory was demonstrated using a full 3-D computational model [7], suggesting importance of 3-D effects.

Besides computations in [5–7], there is a significant number of theoretical studies that address various aspects of MHD flows in the presence of FCIs, including effectiveness of the FCI as electrical and thermal insulator [8–11], 2-D and 3-D MHD effects [12–14], and influence of pressure equalization openings in the FCI on the MHD flow [15]. Tritium transport was considered in [16,17], while studies in Ref. [18] focused on impact of PbLi flows on corrosion of RAFM steel in the thin gap between the FCI and the RAFM structure. Pressure equalization mechanisms between the bulk PbLi flow inside the FCI box and that in the thin gap between the FCI and the RAFM wall were considered in [19]. Performance of the DCLL blanket in ITER and DEMO was analyzed in [20], using electrical and thermal conductivity of the FCI as parameters.

The requirements on SiC electrical and thermal conductivities were formulated in [20] and [21] based on the computational analysis of the velocity, pressure and temperature distributions for a 5-mm FCI. As shown for the inboard DCLL blanket [21], the goal is low electrical conductivity of about 1 S/m. Higher electrical conductivities of about 50 S/m are allowed for lower magnetic field outboard blankets [20]. When using such materials, MHD pressure drop reduction in poloidal flows by a factor of 50–100 is expected compared to bare ducts [5]. Good thermoinsulating properties of the SiC FCI have been predicted as well providing the thermal conductivity is 1–2 W/m-K [20].

Two different approaches are currently considered to develop and manufacture SiC FCIs of required thermomechanical properties, shapes and dimensions. In the first approach, a SiC FCI is reinforced with 2D fiber (SiC_f/SiC composite) resulting in a relatively thin FCI wall of about 5 mm. Such composites (see e.g. Ref. [22]) can be produced by either chemical vapor infiltration (CVI) or using nano-infiltrated and the transient eutectic-phase (NITE) method. Another possible candidate for blanket applications is a foam-based SiC FCI [23], which is a potential low-cost alternative to continuous fiber composite FCI. The idea is to utilize a core of low-density SiC foam, sealed at all surfaces with a layer of CVD (chemical vapor deposition) SiC. A potential advantage of this coated foam-based SiC is low thermal and electrical conductivity. Using foam materials may, however, result in significantly thicker FCIs, displacing PbLi from the breeder region, and thus reducing the tritium breeding ratio (TBR). Also, such an FCI will likely have lower toughness and lower thermal shock resistance compared to what composites can offer. At present, SiC foam-based FCI segments with a \sim 8 mm core and \sim 1 mm thick CVD layers resulting in the overall FCI thickness of 1 cm have been successfully manufactured by Ultramet, USA (Fig. 2).

Thinner foam-based FCIs approaching 5-mm thickness seem to be possible in the future as the fabrication technology matures. As measured in [23] at room temperature in non-irradiation conditions, the electrical conductivity of foam-based SiC is 0.1–10 S/m and thermal conductivity is 4–7 W/m-K depending on fabrication technique and surface pre-conditioning. A main concern about the use of SiC materials is, however, the potential for ingress of PbLi into the FCI through the cracks or other imperfections in the FCI that may appear in the manufacturing process or could develop when the FCI is exposed to hot PbLi and neutron irradiation.

Most of material testing performed earlier on SiC materials in isothermal conditions demonstrated that almost no physical/chemical interaction occurs between the SiC samples and PbLi, providing a special care was taken on purity of PbLi, and providing no dissimilar materials were used in the experiment. For example, specimens of high purity SiC made by CVD showed very low mass change in the temperature range up to 1200 °C using a CVD SiC capsule to prevent dissimilar material interactions [24]. When using a commercial PbLi eutectic alloy with a high oxygen content, no corrosion was observed either, instead a non-uniform oxide layer formed on the SiC surface resulting in the mass gain [25]. Similar conclusions about stable behavior of SiC material in hightemperature PbLi were made more recently based on static testing of samples made of CVD coated SiC_f/SiC composite at 700 °C [26]. In the case of dissimilar materials, e.g. the PbLi containing capsule is made of steel, a few experimental studies (unpublished) in a static pool of PbLi suggest that corrosion does occur. Quantitative data are however scarce and need further verification. To our knowledge, no data exist on corrosion of SiC materials in dynamic conditions when the PbLi is flowing.

In this study, we perform numerical studies of liquid metal MHD flows in a conducting rectangular stainless steel ducts with an FCI as a pre-experimental analysis. This includes computations for finite-length FCI segments exposed to MHD flows of PbLi in experimental-like conditions, where strong MHD effects and high MHD pressure drop can be present in the flow due to formation of 3D electric current loops associated with the FCI edges and a fringing (non-uniform) magnetic field. Additional numerical analysis addresses the effect of rounded FCI corners compared to the right-angle corners. These computations were performed using three numerical codes: HIMAG [28] developed jointly by HyPerComp, USA and UCLA, the commercial finite-element software COMSOL Multiphysics [29] and a UCLA multi-material research code for fully developed MHD flows [30]. The experimental part of the study included dynamic FCI testing in the MaPLE loop at UCLA [27]. In



Fig. 2. Foam-based SiC FCI manufactured by Ultramet, USA: (a) a 30-cm FCI segment and (b) overall FCI segment dimensions.

these dynamic tests, the MHD pressure drop was measured over the flow section with the FCI and then compared with the pressure drop measured over the bare duct section to evaluate the pressure drop reduction factor. Surprisingly, the experimental data demonstrated higher MHD pressure drops compared to the theoretical predictions, suggesting that significant PbLi ingress in the FCI occurred in the course of the experiment. This ingress was further confirmed with the microscopic analysis. To better interpret the experimental data, in particular to understand what might cause the PbLi ingress, the experimental data were compared against the postexperimental numerical analysis, where two possible scenarios of the PbLi ingress were considered.

2. Theoretical background of MHD flows with FCI

Depending on the length of the insert with respect to the host duct, there can be two different approaches to attacking the MHD problem of PbLi flows in a rectangular duct with FCIs in a magnetic field. The first approach assumes a long duct with an FCI extended over the whole duct length, all in a uniform magnetic field. In such conditions, 3-D effects associated with the developing flows at the duct inlet/outlet or those due to a fringing magnetic field can be neglected, such that the problem can be treated as an entirely 2-D problem, using a fully-developed flow model. In fact, such a flow model is a close approximation to the real DCLL blanket conditions where the FCI segments are placed continuously inside the long poloidal ducts (not counting for overlap regions between two FCI segments). If so, the dominating electrical currents are those closing in the cross-sectional plane (cross-sectional currents) as shown in Fig. 3.

In this figure, the MHD PbLi flow was computed with the numerical code described in [30] for a duct made of RAFM steel at the Hartmann number Ha = 15,900 and the electrical conductivity of the FCI σ_{FCI} of 100 S/m, assuming no pressure equalization openings in the FCI. The Hartmann number is defined as $Ha = B_0 b \sqrt{\sigma/v\rho}$, where B_0 is the applied magnetic field, *b* is the half of the distance between the two FCI walls perpendicular to the magnetic field, and σ , ν and ρ are the electrical conductivity, kinematic viscosity and the density of PbLi correspondingly. The associated reduction in the MHD pressure drop in such a fully developed flow compared to a bare duct could be up to 100 times as shown in [5] for low-conductivity FCIs.

The second approach is more related to experimental conditions (e.g. Ref. [6]), where a purely 2-D flow can hardly be established because of the limited workspace inside the magnet and other experimental constraints. In such conditions, axial electrical currents are induced at some locations along with the cross-sectional currents, such that the MHD pressure drop associated with the 3-D effects is not negligible any more. Typically, this 3-D MHD pressure drop is comparable with or even considerably higher than the 2-D MHD pressure drop in a fully-developed flow. A computed pressure distribution in the PbLi flow with a finite-length FCI is shown in Fig. 4. In this computation, the FCI is 60-cm long, while the length of the host duct is 2 m. The FCI and the host duct form a small 2mm gap between them, which is also filled with PbLi. In the original DCLL concept, the gap was proposed in order to accommodate possible FCI thermal expansion and to avoid mechanical stresses in the FCI by allowing it to freely float in the liquid. This PbLi flow in the duct with the FCI is subjected to a spatially-varying magnetic field analogous to that in the MaPLE loop at UCLA [27], which is equipped with an air-gap magnet that produces maximum magnetic field of 1.8 T over the 80-cm length. There are two fringing field regions at the edges of the magnet as also shown in the figure. The computation is performed at the flow velocity U_0 of 5 cm/s, which is close to that in a DCLL blanket (see, e.g. Ref. [1]) and the magnetic field of 1.5 T. The corresponding dimensionless Reynolds number $(Re = U_0 b/v)$ is 11,000 and the Hartmann number is 1350.

The pressure in Fig. 4 is plotted as a function of the axial distance at three locations: one is at the duct center and the other two are in the 2-mm gap at the center of the Hartmann wall and at the center of the side wall. As indicated in the figure, the pressure distribution has nine characteristic zones with respect to the axial distance. In zones I, III, V, VII and IX the flow is fully



Fig. 3. Fully developed MHD flow in a rectangular duct with insulating FCI with no pressure equalization openings computed at Ha = 15,900 and $\sigma_{FCI} = 100$ S/m: (a) velocity profile, (b) induced electric current.



Fig. 4. 3D MHD PbLi flow in a rectangular duct with FCI at Ha=1350 (B_0 =1.5 T), Re=11,000 (U_0 =5 cm/s), σ_{FCI} = 1S/m: (top) axial pressure distribution at three locations, (bottom) location of the host steel duct with the FCI with respect to the magnetic field.

developed (or almost fully developed) as seen from the linear pressure dependency of the axial distance and also due to the fact that the pressure at three different locations within the same crosssection is the same. The only exception is zone V, associated with the flow over the duct section with the FCI. Here, the pressure is also linearly varying with the axial coordinate but there is some difference in the pressure between the bulk and the gap. This difference is because the two flows are completely decoupled as the FCI in this particular example is almost ideally insulating. The pressure drop in the gap is significantly higher than that in the bulk flow inside the FCI box. In zones II, IV, VI and VI, the pressure demonstrates significant variations over the cross-section. This, and also the non-linear pressure dependency of the axial coordinate suggest that the flow in these zones is 3D. The 3D effects in zones II and VIII are related to the fringing magnetic field, whereas in zones IV and VI, the 3D effects are associated with the entry/exit flow effects at the FCI edges.

To quantitatively describe differences in the pressure drop between the MHD flows with and without the FCI it is useful to introduce a pressure drop reduction factor *R* (R-factor). Following [5], the R-factor is defined as the ratio of the MHD pressure drop in a bare duct without an FCI relative to that with the FCI. It is also reasonable to distinguish between the pressure drop reduction factor in a fully developed flow R_{2D} and that for a flow with a finite-length FCI R_{3D} . As mentioned earlier in the paper, providing the FCI electrical conductivity is low enough, R_{2D} could be as high as ~100 in blanket flows, while R_{3D} is sufficiently lower due to the contribution of 3-D effects as shown in Section 4.

3. Pre-experimental numerical analysis using HIMAG

Prior to dynamic testing where an FCI sample was exposed to the flowing PbLi in a magnetic field, static tests were performed on several coated and uncoated FCI samples in a pool of stagnant PbLi. The important details and main conclusions of this study are presented in Ref. [1]. In these static tests, several 12-cm FCI samples were exposed to a stagnant (not counting possible natural-convection flows) PbLi at the temperature of 700 °C for 100 h at different Ar gas overpressures from 0.1 to 1 MPa. About half of these tests demonstrated no PbLi ingress, others had some ingress from small to significant. More ingress was observed in the uncoated samples.

As a pre-experimental analysis of the dynamic experiments, full 3D computations were performed using the HIMAG code [28] to estimate typical values of the pressure drop reduction factor R_{3D} under the experimental conditions. The second goal of the preexperimental analysis was to define optimal locations of the two pressure taps, which are used in the experiment to measure the pressure drop over the FCI segment. Ideally, these two pressure taps should be located within the fully developed flow section, i.e. within zone V as shown in Fig. 4. In practice, placing the pressure taps within the fully developed flow region would require two orifices in the FCI. This is definitely prohibited because of a high risk of PbLi ingress at these two locations. Because of this reason, it was decided to have the pressure taps located at some distance from the fore and rear edges of the FCI as shown in Fig. 4 at the bottom. Putting the pressure taps too far from the FCI would increase the measured MHD pressure drop and thus complicate the analysis of the experimental data. Contrary, putting them too close to the FCI edges would result in uncertainties in measurements of the pressure drop since the pressure distribution near the FCI edges is not uniform, i.e. the pressure is different between the Hartmann and the side layers and both are different from that in the bulk flow. As a compromise, based on the pre-experimental analysis, the distance of 4 cm was found to be optimal for almost all parameters from the experimental matrix.

Table 1

Pre-experimental analysis. Pressure drop reduction factor computed with HIMAG versus Hartmann number, Reynolds number and interaction parameter for σ_{FCI} =5 S/m.

U ₀ (cm/s)/Re	$\Delta P_{\rm bare}$ (Pa)	$\Delta P_{\rm FCI}$ (Pa)	R _{3D}	N = Ha²/Re	
B=0.5T (Ha=448)					
5/11350	305.9	259.2	1.18	17.7	
10/22700	614.9	587.1	1.05	8.84	
15/34050	922.4	895.5	1.03	5.89	
B=1.0T (Ha=895)					
5/11350	1190.8	815.3	1.46	70.6	
10/22700	2381.6	1743.9	1.37	35.3	
15/34050	3594.4	2758.5	1.30	23.5	
B = 1.5 T (Ha = 1342)					
5/11350	2677.1	1620.0	1.65	158	
10/22700	5302.6	3486.9	1.52	79	
15/34050	8014.1	5387.6	1.49	52.7	
B=1.8 T (Ha=1611)					
5/11350	3856.0	2227.9	1.73	229	
10/22700	7684.3	4763.2	1.61	114	
15/34050	11530.5	7420.0	1.55	76.3	

The experimental matrix includes three magnetic field strengths (0.5, 1.0 and 1.5 T) and three velocities (5, 10 and 15 cm/s). In addition, computations were performed for 1.8 T. The FCI and the host duct parameters are given in Section 5. Computational results from this pre-experimental analysis have been summarized in Table 1 for all the velocities and magnetic field strengths. As seen from this table, the R-factor increases with the magnetic field and slightly decreases with the velocity. Based on the computed R-factor, the reduction of the MHD pressure drop by the FCI in the experiments was expected to be around 1.5 compared to a bare duct flow of the same length. Surprisingly, the experimental results were found to be significantly different from the theoretical predictions (much lower R-factor) as explained in detail in Section 5. It has to be mentioned that in the pre-experimental computations, rounded FCI corners (see Fig. 2c) were not included. Rather than that, the computational model used approximated right-angled corners. The rounded FCI corners were added in the post-processing computations (see Section 6), but the obtained results were not very different from the results of the pre-experimental analysis and thus the discrepancy between the experimental data and the theoretical predictions of the pre-experimental analysis cannot be explained with the simplified FCI geometry used in the pre-experimental computations.

In the table, U_0 is the mean bulk velocity in the bare duct and the Hartmann and Reynolds numbers are defined earlier in Section 2. As seen from the table, all flows in the simulations (and also in the experiment) are high Hartmann number, high interaction parameter flows, meaning that electromagnetic forces are much stronger compared to viscous and inertia forces. Also, the ratio Re/Ha, which is the Reynolds number based on the thickness of the Hartmann layer is below its critical magnitude of about 200-400. Another relevant ratio Re/\sqrt{Ha} (Reynolds number based on the thickness of the side layer) that can be used to predict instabilities in the side layers is above its critical value of about 65 (see, e.g. Ref. [32]) in almost all experiments. These suggest that the flow in the Hartmann layers in the experiments is laminar but the side-wall jets, which are formed at the duct walls parallel to the applied magnetic field, are most likely unstable such that quasi-two-dimensional turbulence [32] is likely to occur.

4. MaPLE loop

The MaPLE loop (Fig. 5), which was used for dynamic testing, includes a pipe system, electromagnetic (EM) pump, EM flow meter, electromagnet and a glove box. The flow circuit that consists of the melting tank (also serves as a supply/drain tank) and



Fig. 5. Panoramic picture of the MaPLE loop at UCLA used for dynamic testing of the FCI sample in the flowing PbLi in a magnetic field.

pipelines, are made of stainless steel SUS304. The maximum inventory of PbLi in the loop is about 250 kg. The style V EM conduction pump by Creative Engineers, Inc., USA is used for pumping the alloy through the circuit. The pump tube is made of stainless steel SUS316. The loop is currently operated at maximum temperature of $350 \,^{\circ}$ C as required by the temperature limit of the pump. The magnetic field is created by a water-cooled air-gap electromagnet with the maximum magnetic field of 1.8 T. The magnetic field is uniform within the space of 80 cm (axial) × 15 cm (horizontal) × 15 cm (vertical).

The whole loop, except for the magnet, sits on a steel catch pan, which in turn is put on a four-wheel carrier, which can be moved forward or backward. This allows for all the maintenance work on the loop components to be done outside the magnet. To keep the alloy above its melting point (234 °C), the melting tank is heated by band-heaters and the piping and test section by rope-heaters. There are eight independent, individually controlled heater sections. The tubing part inside the EM pump is heated by its built-in heater and also due to parasitic Joule heating when the conduction pump is on. All loop components are thermally insulated and heated. The glove box that sits on the top of the melting tank is designed to allow for a connection of a vacuum pump and/or a purification unit for circulation of high-purity argon gas through the loop in the initial loop operation stages to remove air and moisture. Fig. 5 shows a panoramic picture of the loop taken at the time of writing this paper.

5. Dynamic testing

A 90 mm \times 90 mm \times 1848 mm host stainless steel (SUS304) duct with 3-mm walls (Fig. 6a) was fabricated at UCLA and the FCI was placed inside the duct as shown in Fig. 6b. The position of the SiC insert inside the host duct is fixed with several adjustable pin holders. There are pin holders to center the FCI inside the host duct and also to restrict vertical and horizontal FCI displacements (centering pins) and those to restrict axial displacements in the flow direction (restrain pins) as shown in Fig. 7. The minimal gap between the FCI and the wall of the host duct is 2 mm with bigger gap spacing at the corners because of the rounded FCI shape. Three pressure taps are welded to the duct to connect the indirect pressure measurement system already used in [28]. This system measures a differential pressure between two argon-filled pressure cans, each connected to its pressure tap with a thin tube as described in [28]. The location of the pressure taps is shown schematically in Fig. 8. Before placing the FCI inside the host duct, the FCI was weighed at 780 ± 1 g.

After melting PbLi ingots from Atlantic metals, USA in the melting tank and filling the loop with the liquid metal, the test section was moved in the gap space of the magnet and experiments on measuring the pressure drop over the FCI and bare duct sections started. When preparing the melt, special care was taken of removing oxygen, which is originally present in the ingots. This was done by continuous pumping of high-purity argon gas through the melting chamber for many hours. This cleaning procedure results in a very small content of oxygen of only ~5 ppm in the cover argon gas. However, no oxygen monitoring was performed during the experiments. Completing the measurements took unexpectedly long time about 9 months (~6500 h) because of some faults in the pressure measurement system, caused by clogging the connection tubes between the duct and the argon-filled pressure cans, such that the pressure measurements were taken only in the last month of the 9-month experimental period after fixing all faults in the pressure system. In the early stage of the experiment (<800 h), the pressure drop over the FCI segment was evaluated indirectly by calculating pressure drops for all loop components (except for that over the FCI section) and then subtracting them from the overall pressure drop in the loop. This approximate approach to determining the pressure drop over the FCI segment suggested magnitudes of R_{3D} close to computed ones, i.e. around 1.5.

The direct pressure measurements were taken first without the magnetic field and then at three magnetic field strengths: 0.5, 1.0 and 1.5 T. The flow velocity was also widely varied by changing the pump voltage from 20 to 240 V. The maximum flow-rate in the experiments was 38 LPM. This corresponds to the velocity of 0.09 m/s in the host duct, and 1.6 m/s in the one-inch connecting circular pipes. The PbLi temperature in the experiments was held at ~300 °C. The maximum pressure in the loop did not exceed 0.25 MPa.

The main goal of this series of experiments was to confirm the estimated reduction of the MHD pressure drop by the FCI. The theoretical predictions for the pressure drop reduction factor R_{2D} based on the fully developed flow model as mentioned earlier is up to 100 and that using the full 3D model for the finite-length FCI is around 1.5. Fig. 9 shows the pressure drop measurements over the 30-cm section of the bare duct (without the FCI) collected at three magnetic fields and various velocities. These pressure drop measurements are in a good agreement with numerical compu-



Fig. 6. Experimental test section: (a) host stainless steel duct and (b) location of the FCI inside the host duct.

Fig. 7. Location of centering and restrain pins to fix the position of the FCI segment inside the host duct.

Fig. 8. Location of the FCI and the host duct with respect to the magnet (shown with a dotted line). The figure also shows locations of three pressure taps.

tations and the theoretical formula by Miyazaki et al. [33] (just slightly higher), demonstrating reliability of the employed pressure measurement technique. Surprisingly, the measured pressure drop in the flow with the FCI does not match the theoretical predictions as shown in Fig. 10 where the measured MHD pressure drop in the flows with and without the FCI are plotted together versus the flowrate Q. This figure suggests the pressure drop reduction factor of only about 0.75 (i.e. the pressure drop in the flow with the FCI is higher compared to the bare duct flow). These unexpected results can be related to degradation of electroinsulating properties of the FCI caused by liquid metal ingress into the porous structure through the defects in the protective CVD layer. After finishing the experiments, the loop was drained and the FCI extracted from the host duct (Fig. 11). Visual inspection of the FCI did not demonstrate any cracks in the protective CVD layer but the FCI weight was found to be 3022 ± 1 g, i.e. the mass gain was 2242 g compared to the original weight. This mass gain, which is obviously related to the PbLi ingress, corresponds to 31% of the total FCI volume. For further characterization of the PbLi ingress into the FCI, a few 1-cm slices were cut and then analyzed using an optical microscope. Three micrographs corresponding to the FCI inlet, middle section and outlet are shown in Fig. 11. All three micrographs clearly demonstrate significant PbLi ingress. However, the micrograph taken from the inlet section demonstrates higher PbLi ingress compared to two other slices. This may indicate to some relation

Fig. 9. Pressure drop in PbLi in the bare duct.

Fig. 10. Comparison for the MHD pressure drop with and without the FCI at 1 T.

Fig. 11. Picture of the FCI extracted from the duct.

between the ingress and the MHD flow development effects at the FCI inlet. It also should be mentioned that no significant differences in the micrographs were found between the Hartmann and

the side FCI walls meaning no anisotropy occurred in the transport phenomena that might be caused by the applied magnetic field. The thickness of the inner CVD layer was found to be significantly smaller compared to the outer layer. Whereas the outer layer is always about 1-mm thick, the inner layer was found to be non-uniform and several times thinner (Fig. 12b) and even almost absent at some locations. This may suggest that the ingress occurred predominantly from the bulk flow inside the FCI box through the inner CVD layer. However, based on this microscopic analysis, it is not clear if the inner CVD layer was originally thinner than the outer one due to some flaws in the manufacturing process or it degraded during the long exposure of the FCI to the flowing PbLi.

To possibly understand the cause of a small thickness of the inner CVD layer compared to the outer layer, an unused FCI segment of the same manufactured series was sliced and analyzed. Fig. 13a shows that the inner CVD layer is really thinner than the outer one. Whereas the thickness of the outer CVD layer is about 1 mm, the thickness of inner layer is between 100 and $350 \,\mu$ m. Regarding this difference between the inner and outer CVD layers, it was known prior to coating the FCI tubes that the outer layer would be somewhat thicker than the inner one because of the inherent difficulties in getting the CVD precursor gas to flow into the tube (particularly as the part length increased). A 1.0 mm SiC facesheet thickness was targeted because previous work had shown that closeout of the foam surface porosity typically occurs at a 0.35 mm thickness. However, although post-coating dimensional inspection of the fairly rough ID surface showed the inner layer thickness was near the target, cross-sections of full-length (30 cm) segments show that the desired thickness of the inner CVD layer was not achieved. This effect was not seen in the shorter (12 cm) segments used in the static tests as shown in Fig. 13b. Additional process optimization of the inner SiC layer is therefore required for 30-cm or longer segments. Investigation of alternative facesheet materials, such as thin, freestanding (non-bonded) layers of molybdenum sheet that are produced to fit snug over the inner and outer surfaces is also of interest. Use of non-bonded metal facesheets would minimize stress at the foam/facesheet interface and eliminate issues associated with vapor-deposited facesheets.

It it is obvious that the observed ingress is related to some defects or damages of the FCI segment, in particular of the protective CVD layer. In addition to the manufacturing flaws, there could be several causes that might lead to damages, such as stress concentration at the pins, vibration and/or forces exerted by the flowing PbLi, insufficient preheating of the FCI segment coming in contact with hot (300 °C) PbLi, or corrosion/erosion processes. All these observations suggest that more FCI development work and more studies have to be done. It should also be mentioned that the experimental campaign took unexpectedly long time, about 9 months, over which the PbLi was always flowing. The pressure measurements presented in this paper were taken almost at the end of this period so that it is hard to conclude confidently if the ingress occurred at the beginning of the experiments or the observed mass gain was caused by continuous PbLi ingress in the course of the entire experimental campaign.

6. Post-experimental numerical analysis

In order to better interpret the experimental results, a postexperimental numerical analysis was carried out using two computational tools: first, commercially available code COMSOL [29], and second, a UCLA research code for fully developed MHD duct flows [30]. Using these two computational tools, two possible scenarios of PbLi ingress into the FCI and associated degradation of electro-insulating properties resulting in higher MHD pressure drop were considered. The first scenario assumes that the CVD layer

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(a)

Fig. 12. FCI micrographs of the FCI sample exposed to PbLi in the dynamic experiment taken at three different locations: (a) 1 cm from the FCI inlet on the Hartmann wall, (b) in the middle of the FCI on the side wall, and (c) 1 cm from the outlet on the Hartmann wall.

has many micro cracks, which could appear as a result of a thermal shock when the FCI sample was exposed to high-temperature PbLi. In the second scenario, we assumed that the CVD layer is damaged only at a few particular locations, for example at the contact points between the FCI and the centering pins, such that the PbLi ingress occured at these locations while the most of the CVD facesheet was still functioning as a good barrier to PbLi ingress.

6.1. Numerical analysis using COMSOL

A commercial multi-physics package COMSOL [29] is well suited for computations of complex geometry flows. Moreover, it has been demonstrated recently that COMSOL can be effectively applied to MHD flows. The COMSOL code was validated against MHD benchmark problems endorsed by the fusion community [35]. The numerical error in COMSOL in the benchmark case A (fully developed MHD flows) and B (flows in a fringing magnetic field) proposed in [35] are less than 1% and 5% respectively. In the present 3D computations by COMSOL, a mathematical formulation based on the electric potential as the main electromagnetic variable was used to compute the induced electric currents in the conducting domain, including the liquid metal, FCI and electrically conducting host duct and then to couple these currents with the fluid flow. The COMSOL code that utilizes finite-element discretization solves the Navier-Stokes equations and the elliptic-type equation for the electric potential separately through a segregated approach and then both the outputs at each numerical time step are coupled. The basic linear system of equations is solved through the Newton-Raphson method. A similar approach was used successfully in [34] to solve a number of LM MHD problems.

For simulating the FCI cases, a full 3D geometry including FCI rounded corners was included in the computational model, but taking into account the flow symmetry only half of the host duct cross-section was employed in the computations to reduce the computational time. In all computed cases, the duct length of 0.8 m under uniform magnetic field was considered. A COMSOL built-in mesh generator was used to construct a non-uniform mesh with 5 mesh elements within the Hartmann layer and 7 elements within

Fig. 13. Micrographs of the unused FCI segments. (a) A cross-sectional cut of the 30-cm segment shows variations of the inner CVD layer (at the top) from ~0.1 to 0.3 mm compared to the outer layer of ~1 mm. (b) Cross-section of carbon aerogel-filled SiC foam tube (12 cm long) shows both inner and outer SiC CVD layers to be ~0.76 mm.

Fig. 14. Comparison between MHD computations for rounded corner and right-angled corner FCI at B = 1.0 T (Ha = 895), $U_0 = 10 \text{ cm/s}$ (Re = 22,700) and $\sigma_{\text{FCI}} = 5 \text{ S/m}$: (a) electric current streamtracers in the flow with right-angled corner FCI, (b) in the flow with rounded corner FCI, and (c) velocity profile in the flow with rounded corner FCI. The magnetic field is in Z-direction. Both Z and Y in mm.

Fig. 15. Computed MHD flow in a rectangular duct with a conducting rounded corner FCI at B = 1.0 T (Ha = 895), $U_0 = 10$ cm/s (Re = 22,700) and $\sigma_{FCI} = 64,000$ S/m: (a) electric current streamtracers and (b) velocity profile. The magnetic field is in Z-direction. Both Z and Y in mm.

Fig. 16. Comparison of the electric current streamtracers (left) and the velocity profile (right) in the fully developed flow with the FCI at the magnetic field of 1T: (a) undamaged FCI and (b) damaged FCI leading to PbLi ingress in the FCI bulk material. Magnetic field in Z-direction. Both inner and outer CVD layers are 1-mm thick.

the side layer. Outside the boundary layers, the mesh size is geometrically increased inwards. The following boundary conditions are applied: zero normal component of the electric current at all outer surfaces, flat velocity profile at the inlet, zero $\partial u/\partial x$ and zero

pressure at the outlet, no-slip condition at the liquid-wall interface, and symmetry condition at the middle of the cross-section.

One of the initial guesses to explain the two times higher computed pressure drop reduction factor compared to the experiment

Table 2

Evaluation of the effective FCI electrical conductivity in the post-experimental analysis. Pressure drop reduction factor computed in COMSOL at different experimental magnetic fields is shown.

	<i>B</i> = 0.5 T	<i>B</i> = 1.0 T	<i>B</i> = 1.5 T
σ_{FCI} (S/m)	64,000	64,000	64,000
U_0 (cm/s)	10	10	10
R _{3d} , numerical	0.64	0.75	0.81
R _{3d} , experimental	0.73	0.74	0.79
Relative error (%)	12.3	1.4	2.5

was the effect of FCI rounded corners, which was not accounted in the pre-experimental analysis. However, including the rounded corners into the computational model in the post-experimental analysis has not revealed substantially new flow features. Fig. 14 shows the induced electric current in the cross-sectional area of the duct at 21 cm downstream from the FCI inlet. Comparison is made between the case for rounded corners and that for the right-angled corner FCI. In the reference cross-section, the flow is fully developed such that the current distribution and the velocity profile are very similar between the two cases. Namely, the electric current is generated in the core flow inside the FCI box and then the current is closed through the Hartmann and side layers. Some currents are also generated in the gap region but these currents are smaller than those in the PbLi flow inside the FCI. A quantitative comparison of the MHD pressure drop between the two computations also suggests a higher than unity R-factor regardless the FCI shape: R = 1.37for the sharp corners and R = 1.39 for the FCI with rounded corners (for Ha = 895 and Re = 22,700). Therefore, the unexpectedly small magnitude of the R-factor observed in the experiment is not related to the corner shape but should be attributed to the PbLi ingress.

The next computational effort using COMSOL was taken to evaluate the effective electrical conductivity of the FCI by matching measured and computed pressure drops. The physical model behind these computations assumes that the entire FCI is uniformly soaked with PbLi through many micro cracks in the CVD layer. As a result of the PbLi ingress, both the bulk material and the CVD layer have high electrical conductivity, which is lower than the electrical conductivity of PbLi but sufficiently higher than the electrical conductivity of both the original undamaged CVD layer and that of the bulk material. Numerically, the electrical conductivity of the FCI was varied until the numerical pressure reduction factor matched the experimental value. As a first step, σ_{FCI} was set equal to σ_{PbLi} such as to get an upper extreme case of PbLi ingress inside the FCI. The σ_{FCI} = 5 S/m can be considered as the lower extreme case with no PbLi ingress. With few iterations of $\sigma_{\rm FCI}$ in the numerical model, σ_{FCI} = 64,000 S/m was found to provide good match with the experiment at maximum deviation of 12% at 0.5 T as shown in Table 2. Corresponding current and velocity distributions are shown in Fig. 15.

6.2. Numerical analysis using UCLA code

The home-made research UCLA code [31] is limited to fully developed MHD flows. That is why the results obtained with this code cannot be directly compared with the experimental results, which involve both 2D and 3D effects as explained earlier in Section 2. However, the code is well suited for multi-material computations and allows for very fast computations compared to COMSOL and HIMAG and thus can serve as an effective modelling tool to address certain aspects of the experimental flows. Namely, in this effort a proposed physical model assumes that the CVD layer is mostly undamaged except for a few locations where PbLi ingress occurred, for example, at the points of contact between the centering pins and the FCI.

Fig. 17. Effect of the thickness of the inner CVD layer on the dimensionless flow rate \tilde{Q} .

Taking into account a very long exposure time in the experiments, the PbLi that penetrated through these local defects in the bulk material could further diffuse and saturate the entire SiC foam-based core resulting in high electrical conductivity. In the computations, the FCI is considered as a "sandwich" structure, which includes inner and outer CVD layers and the core region. The electrical conductivity of the CVD layer in the computations is 100 S/m and that of the core is 5 S/m in the case of no ingress and 64,000 S/m in case the FCI is soaked with PbLi, similar to that in the COMSOL computations in Section 6.1. The outer FCI layer in all the computations is 1 mm thick, while the thickness of the inner layer was varied from 1 to 0.1 mm as there are some evidences that the inner layer was unintentionally manufactured thinner than the outer one as explained in Section 6. The computations are limited to fully developed flow conditions, i.e. the 3D effects associated with the FCI edges are not captured. Comparisons between the case of ideal FCI (undamaged FCI) and that with some local defects in the FCI layer (damaged FCI) are shown in Fig. 16 for the velocity profile and the induced electric current. For the undamaged FCI, all currents generated in the PbLi flow inside the FCI box remain localized to the flow domain and the velocity is uniform except for the thin MHD boundary layers. The case of a damaged FCI demonstrates a different current path where the induced electric current crosses the CVD layer at almost the right angle and then flows near tangentially inside the FCI. The associated velocity structure shows higher velocities near the FCI walls parallel to the magnetic field (known as near-wall jets) and high velocities in the two gap sections parallel to the magnetic field, while the flow is stagnant in the two other gap sections.

In the next computations, the effect of the thickness of the inner FCI layer on the MHD pressure drop was addressed in a parametric analysis. Fig. 17 shows the influence of the magnetic field (Hartmann number) and the thickness of the inner CVD layer on the dimensionless flow rate $\tilde{Q} = \int_{-1}^{1} d\tilde{y} \int_{-1}^{1} \widetilde{U} d\tilde{z}$, where $\tilde{z} = z/b$, $\tilde{y} = y/b$ and the dimensionless axial velocity is defined as $\tilde{U} = U/[b^2v^{-1}\rho^{-1}(-dP/dx)]$ using the pressure gradient in the liquid dP/dx. In this figure, the dimensionless flow rates for the damaged FCI at the thickness of the inner CVD layer of 0.1, 0.5 and 1.0 mm

are compared with the flow rate in the flow with the undamaged FCI. All damaged FCI cases show significantly lower \tilde{Q} (higher MHD pressure drop) compared to the undamaged FCI case. The maximum difference is of a factor of 5 in the case of 0.1-mm inner CVD layer. Although these computed results cannot be used in direct comparisons with the experimental results, the demonstrated tendencies suggest that the proposed model of the damaged FCI is quite realistic.

7. Concluding remarks

Theoretical predictions of the pressure drop reduction factor show that in the conditions of a DCLL blanket the FCI can reduce the MHD pressure drop up to 100 times providing that no PbLi ingress into the FCI occurred. The experimental studies that included static and dynamic tests of foam-based SiC samples in PbLi yet brought ambiguous results. In static tests, about half of the tested samples demonstrated no PbLi ingress while others, including CVD-coated and uncoated samples, showed some ingress from small to significant. Dynamic testing in the flowing PbLi was performed at different velocities (up to 9 cm/s) and magnetic fields (up to 1.5 T) and the temperature of 300 °C. The dynamic tests have not confirmed yet the anticipated reduction of the MHD pressure drop because significant PbLi ingress occurred in the course of the experiment that caused degradation of electgroinsulating properties of the FCI as confirmed by the post-experimental weight and microscopic analysis. However, since the entire testing took a very long time (\sim 6500 h) and the test was not interrupted for inspection of the FCI segment, it is not clear when the ingress occurred, at the beginning or closer to the end of the experiment. Indirect estimates of the MHD pressure drop made in the first phase of the experiment (<800 h) suggest that at the beginning of the experiment the FCI did its job as an electrical insulator such that the ingress occurred in later stages of the experiment. It needs to be stressed that no SiC FCIs were manufactured and tested before, so that these first testing results do not provide a ground to cast any doubt on the FCI concept. However, these results indicate some flaws in the manufacturing process that have to be corrected in the next efforts. Moreover, the obtained experimental data is a very valuable database to be used in sharpening the MHD computational tools and also to develop physical/mathematical models for MHD duct flows with an FCI

To possibly explain the pressure drop results in the experiment, two physical model were suggested. In the first model, the entire FCI was assumed to be highly electrically conducting, including the protective CVD facesheet due to the PbLi ingress into the FCI through microscopic cracks in the CVD layer. Using the COMSOL software, the best match between the measurements and the computational data for the pressure drop in the PbLi was found at the electrical conductivity of the FCI of 64,000 S/m, which is significantly higher than the electrical conductivity of the original foam-based SiC FCI but at the same time two orders of magnitude lower than the electrical conductivity of PbLi. This is consistent with the FCI mass gain observed in the experiment, which was found to be equivalent to 31% of the total FCI volume filled with PbLi.

Another possible scenario of the PbLi ingress is that the CVD layer mainly retained its electroinsulating properties over the whole course of the experiment but the ingress occurred through the local defects in the CVD layer, for examples at the points of contact between the centering pins and the FCI. Also, some local defects in the CVD layer might be formed as a result of the manufacturing process. The latter was indirectly confirmed by the microscopic analysis of the unused FCI samples (not exposed to PbLi), which showed that the inner CVD layer was significantly thinner than the outer layer, at some locations reaching $\sim 0.1 \text{ mm}$. This scenario was also analyzed in numerical computations using a UCLA multi-material MHD code. The observed tendencies suggest that such a scenario of PbLi ingress is quite possible.

To conclude, more work is needed, including development of SiC materials and sealing layers that assure no PbLi ingress before implementing an FCI in a real fusion device.

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