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Local approximation of operators

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Many applications, such as system identification, classification of time series, direct and inverse problems in partial differential equations, and uncertainty quantification lead to the question of approximation of a non-linear operator between metric spaces  $X$  and  $Y$ . We study the problem of determining the degree of approximation of a such operators on a compact subset  $K_X \subset X$  using a finite amount of information. If  $F : K_X \rightarrow K_Y$ , a well established strategy to approximate  $F(F)$  for some  $F \in K_X$  is to encode  $F$  (respectively,  $F(F)$ ) in terms of a finite number  $d$  (respectively  $m$ ) of real numbers. Together with appropriate reconstruction algorithms (decoders), the problem reduces to the approximation of  $m$  functions on a compact subset of a high dimensional Euclidean space  $\mathbb{R}^d$ , equivalently, the unit sphere  $\mathbb{S}^d$  embedded in  $\mathbb{R}^{d+1}$ . The problem is challenging because  $d, m$ , as well as the complexity of the approximation on  $\mathbb{S}^d$  are all large, and it is necessary to estimate the accuracy keeping track of the inter-dependence of all the approximations involved. In this paper, we establish constructive methods to do this efficiently; i.e., with the constants involved in the estimates on the approximation on  $\mathbb{S}^d$  being  $O(d^{1/6})$ . We study different smoothness classes for the operators, and also propose a method for approximation of  $F(F)$  using only information in a small neighborhood of  $F$ , resulting in an effective reduction in the number of parameters involved. To further mitigate the problem of large number of parameters, we propose prefabricated networks, resulting in a substantially smaller number of effective parameters. The problem is studied in both deterministic and probabilistic settings.