

EE-2200

Fall-98

Lecture 11

Frequency Response of FIR

2-Nov-98

Info: Web-CT, Lab, HW

■ **Calendar:**

■ **Quiz #2 on 13-Nov (Friday)**

■ **Prob Set #4 due TODAY**

■ **Solutions for #3 are posted (complete)**

■ **Lab #5 on Filtering**

■ **Frequency Response**

11/02/98

EE-2200 Fall-98 jMc

2

READING ASSIGNMENTS

■ **This Lecture:**

■ **Chapter 5, pp. 157–165, 169–176**

■ **Other Reading:**

■ **Recitation: Ch. 6, pp. 176–188**

■ **FREQUENCY RESPONSE EXAMPLES**

■ **Next Lecture: Chapter 6, pp. 188–194**

11/02/98

EE-2200 Fall-98 jMc

3

LECTURE OBJECTIVES

■ **SINUSOIDAL INPUT SIGNAL**

■ **DETERMINE FIR OUTPUT**

■ **FREQUENCY RESPONSE of FIR**

■ **MAGNITUDE vs. Frequency**

■ **PHASE vs. Freq**

■ **PLOTTING:**

$$H(\hat{\omega}) = |H(\hat{\omega})| e^{j\varphi(\hat{\omega})}$$

MAG

PHASE

11/02/98

EE-2200 Fall-98 jMc

4

DIGITAL "FILTERING"



■ CONCENTRATE on the **SPECTRUM**

■ SINUSOIDAL INPUT

■ INPUT $x[n]$ = SUM of SINUSOIDS

■ Then, OUTPUT $y[n]$ = SUM of SINUSOIDS

GENERAL FIR FILTER

■ FILTER COEFFICIENTS $\{b_k\}$

■ DEFINE THE FILTER

$$y[n] = \sum_{k=0}^M b_k x[n - k]$$

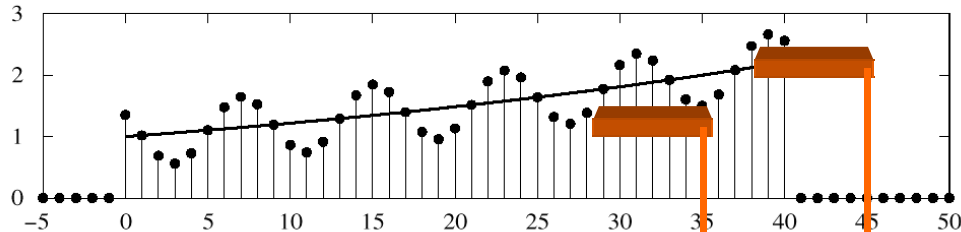
■ For example, $\{b_k\} = \{3, -1, 2, 1\}$

$$y[n] = \sum_{k=0}^3 b_k x[n - k]$$

$$= 3x[n] - x[n - 1] + 2x[n - 2] + x[n - 3]$$

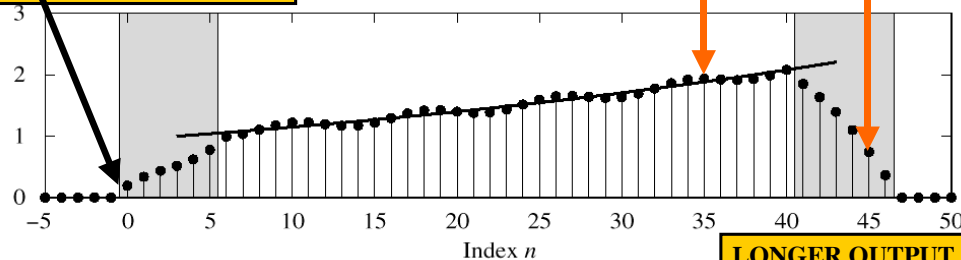
ANIMATION of FIR FILTER

Input Signal: $x[n] = (1.02)^n + \cos(2\pi n/8 + \pi/4)$ for $0 \leq n \leq 40$



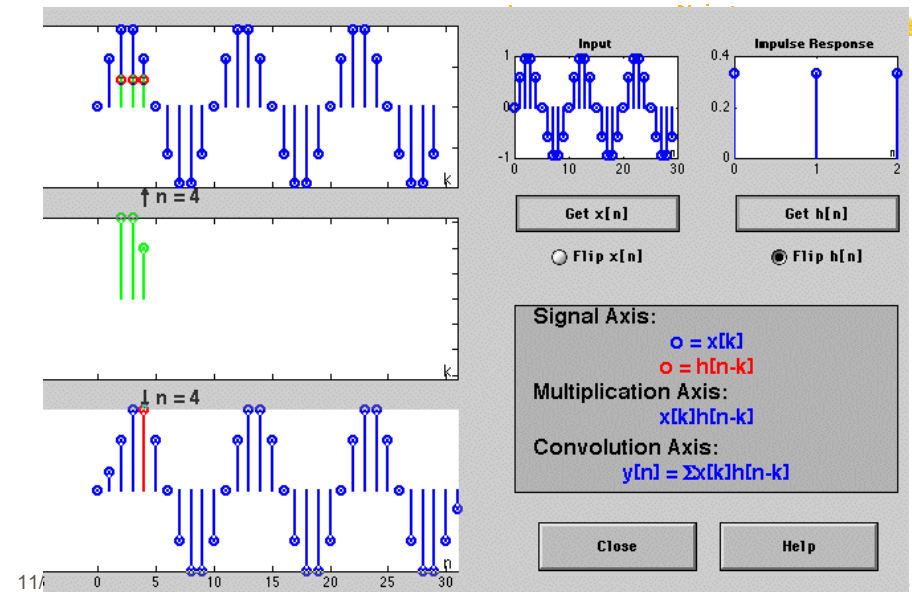
CAUSAL: Use Previous

Output of 7-Point Running-Average Filter



LONGER OUTPUT

CONVDEMO: MATLAB GUI




SPECIAL INPUT SIGNALS

- $x[n] = \text{SINUSOID}$
- $y[n]$ will also be a **SINUSOID**
 - Different Amplitude and Phase
 - **SAME** Frequency
- **AMPLITUDE & PHASE CHANGE**
 - Called the **FREQUENCY RESPONSE**

COMPLEX EXPONENTIAL

$$x[n] = Ae^{j\phi} e^{j\hat{\omega}n} \quad -\infty < n < \infty$$


$$y[n] = \sum_{k=0}^M b_k x[n-k] = \sum_{k=0}^M h[k] x[n-k]$$

FIR DIFFERENCE EQUATION

COMPLEX EXP OUTPUT

- Use the FIR “Difference Equation”

$$\begin{aligned} y[n] &= \sum_{k=0}^M b_k Ae^{j\phi} e^{j\hat{\omega}(n-k)} \\ &= \left(\sum_{k=0}^M b_k e^{-j\hat{\omega}k} \right) Ae^{j\phi} e^{j\hat{\omega}n} \\ &= \mathcal{H}(\hat{\omega}) Ae^{j\phi} e^{j\hat{\omega}n} \quad -\infty < n < \infty \end{aligned}$$

FREQUENCY REPNSE

- At each frequency, we can define

$$\mathcal{H}(\hat{\omega}) = \sum_{k=0}^M b_k e^{-j\hat{\omega}k}$$

- **Complex-valued formula**
 - Has **MAGNITUDE vs. frequency**
 - And **PHASE vs. frequency**

EXAMPLE 6.1

Example 6.1

$$\{b_k\} = \{1, 2, 1\}$$

$$\mathcal{H}(\hat{\omega}) = 1 + 2e^{-j\hat{\omega}} + e^{-j\hat{\omega}2}$$

To obtain formulas for the magnitude and phase of the frequency response

$$\mathcal{H}(\hat{\omega}) = 1 + 2e^{-j\hat{\omega}} + e^{-j\hat{\omega}2}$$

$$= e^{-j\hat{\omega}} (e^{j\hat{\omega}} + 2 + e^{-j\hat{\omega}})$$

$$= e^{-j\hat{\omega}} (2 + 2 \cos \hat{\omega})$$

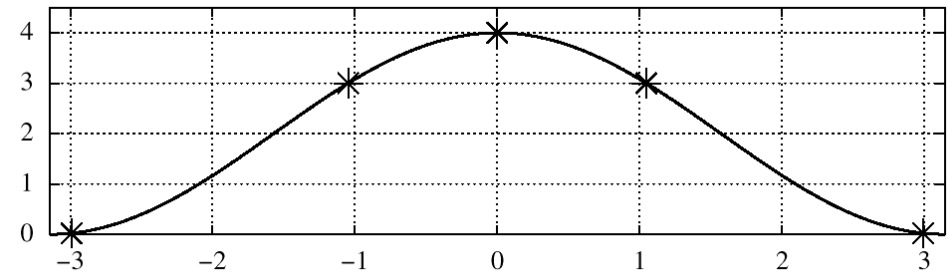
SYMMETRY

Since $(2 + 2 \cos \hat{\omega}) \geq 0$ for frequencies $-\pi < \hat{\omega} \leq \pi$,

the magnitude is $|\mathcal{H}(\hat{\omega})| = (2 + 2 \cos \hat{\omega})$

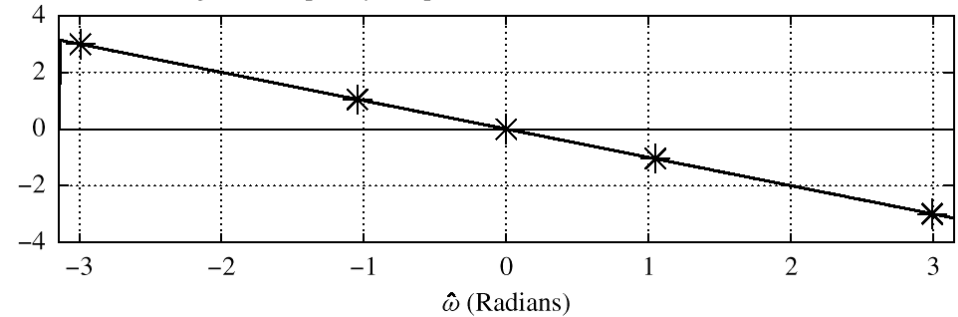
and the phase is $\angle \mathcal{H}(\hat{\omega}) = -\hat{\omega}$.

Magnitude of Frequency Response of FIR Filter with Coefficients [1, 2, 1]



$$|\mathcal{H}(\hat{\omega})| = (2 + 2 \cos \hat{\omega})e^{-j\hat{\omega}}$$

Phase Angle of Frequency Response of FIR Filter with Coefficients [1, 2, 1]



MATLAB: FREQUENCY RESPONSE

■ `yy = freqz(bb, 1, ww)`

■ VECTOR **bb** contains Filter Coefficients

■ DSP-First: `yy = freekz(bb, 1, ww)`

■ FILTER COEFFICIENTS $\{b_k\}$

$$\mathcal{H}(\hat{\omega}) = \sum_{k=0}^M b_k e^{-j\hat{\omega}k}$$

EXAMPLE 6.2

■ Find $y[n]$ when $x[n] = \text{complex exp.}$

Example 6.2 Consider the complex input $x[n] = 2e^{j\pi/4}e^{j\pi n/3}$.

$$|\mathcal{H}(\pi/3)| = 2 + 2 \cos(\pi/3) = 3 \text{ and } \angle \mathcal{H}(\hat{\omega}) = -\pi/3.$$

Therefore, the output of the system for the given input is

$$\begin{aligned} y[n] &= 3e^{-j\pi/3} \cdot 2e^{j\pi/4}e^{j\pi n/3} \\ &= (3 \cdot 2) \cdot e^{(j\pi/4 - j\pi/3)}e^{j\pi n/3} \\ &= 6e^{-j\pi/12}e^{j\pi n/3} = 6e^{j\pi/4}e^{j\pi(n-1)/3} \end{aligned}$$

LTI SYSTEMS

- LTI:
 - Linear & Time-Invariant
- COMPLETELY CHARACTERIZED by:
 - FREQUENCY RESPONSE
 - IMPULSE RESPONSE $h[n]$
- Two DOMAINS: time & frequency
 - Go back and forth

Time & Frequency

- Frequency Response from $h[n]$
 - Here is the FIR case:

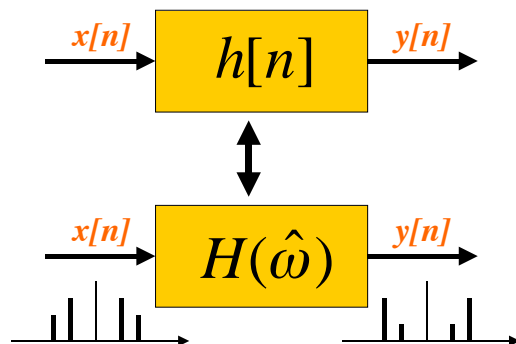
The frequency response of an LTI system

$$\mathcal{H}(\hat{\omega}) = \sum_{k=0}^M b_k e^{-j\hat{\omega}k} = \sum_{k=0}^M h[k] e^{-j\hat{\omega}k} \quad (6.1.4)$$

IMPULSE RESPONSE

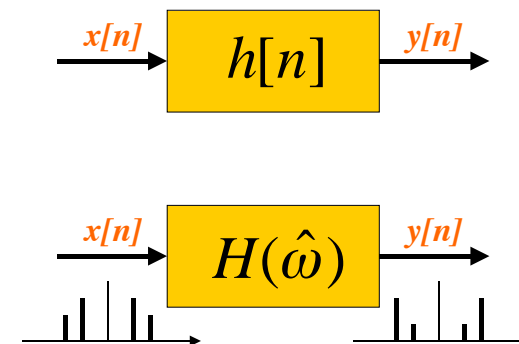
BLOCK DIAGRAMS

- Equivalent Representations



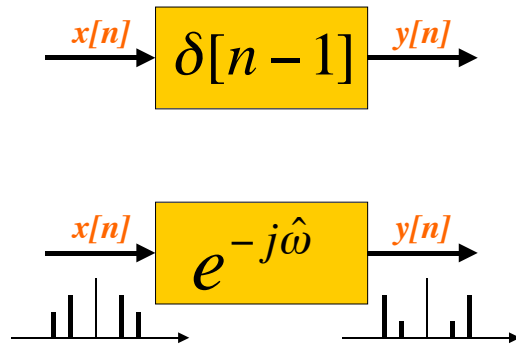
DELAY SYSTEM ??

- UNIT DELAY: find $h[n]$ and $H(\omega)$



DELAY SYSTEM

- UNIT DELAY: find $h[n]$ and $H(\omega)$



CASCADE SYSTEMS

- Does the order of S_1 & S_2 matter?
 - NO, LTI SYSTEMS can be rearranged !!!
 - WHAT ARE THE FILTER COEFFS? $\{b_k\}$
 - WHAT is the FREQUENCY RESPONSE ?

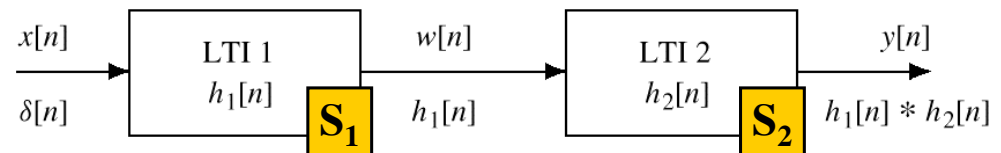


Figure 5.19 A Cascade of Two LTI Systems.

CASCADE EQUIVALENT

- Multiply the Frequency Responses

