

**Lecture 14**  
**Relate  $H(z)$  to Frequency Response**  
**16-Nov-98**

**Info: Web-CT, Lab, HW**

- **Calendar:**
  - **Final Exam is Period 15 (ugh!)**
  - **Quiz Solutions are posted**
- **Prob Set #6 posted by tomorrow**
  - **One more: Prob-Set #7 due on last day**
- **Lab #8 on Image Processing**
  - **Image Zooming as a Filter**

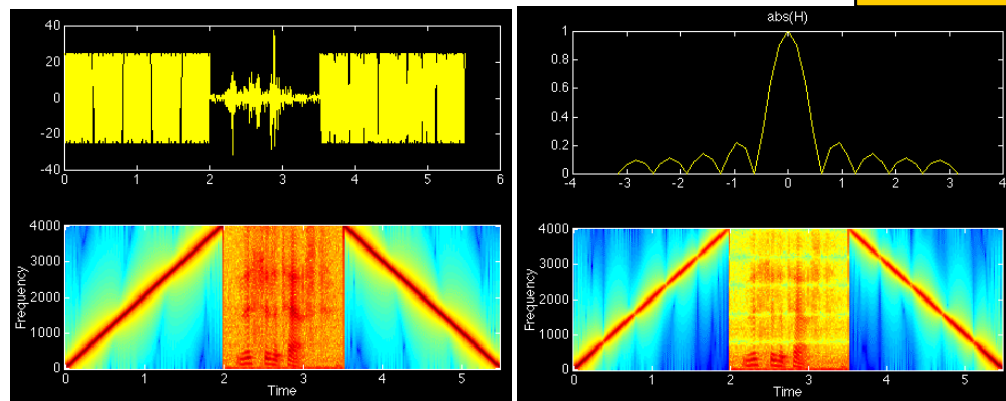
**READING ASSIGNMENTS**

- **This Lecture:**
  - **Chapter 7, pp. 220–230**
- **Other Reading:**
  - **Recitation: Ch. 7, pp. 217–220**
    - **CASCADING SYSTEMS**
  - **Next Lecture: Chapter 8, start**

**FIR Filtering Demo**

- **Chapter 6 Demos on CD-ROM**

10-pt AVG



# LECTURE OBJECTIVES

- Relate  $H(z)$  to FREQUENCY RESPONSE

$$H(\hat{\omega}) = H(z) \Big|_{z=e^{j\hat{\omega}}}$$

- Zeros of  $H(z)$
- THREE DOMAINS:**

- Show Relationship for FIR:

$$h[n] \leftrightarrow H(z) \leftrightarrow H(e^{j\hat{\omega}})$$

# TRANSFORM CONCEPT

- Move to a new domain where
  - OPERATIONS are EASIER/FAMILIAR

- Use **POLYNOMIALS**

$$H(z) = \sum_n h[n]z^{-n}$$

- TRANSFORM both ways

- $x[n] \rightarrow X(z)$  (into the z domain)
- $x[n] \leftarrow X(z)$  (back to the time domain)

# Z-Transform DEFINITION

- POLYNOMIAL** Representation

$$H(z) = \sum_n h[n]z^{-n}$$

- EXAMPLE:**

$$\{h[n]\} = \{2, 0, -3, 0, 2\}$$

$$\begin{aligned} H(z) &= 2z^{-0} + 0z^{-1} - 3z^{-2} + 0z^{-3} + 2z^{-4} \\ &= 2 - 3z^{-2} + 2z^{-4} \end{aligned}$$

APPLIES to Any SIGNAL

# Z-Transform of FIR Filter

- $h[n]$  is same as  $\{b_k\}$

SYSTEM FUNCTION

$$H(z) = \sum_{k=0}^M b_k z^{-k} = \sum_{k=0}^M h[k] z^{-k}$$

$$y[n] = \sum_{k=0}^M b_k x[n-k] = \sum_{k=0}^M h[k] x[n-k]$$

FIR DIFFERENCE EQUATION

CONVOLUTION

# DELAY PROPERTY

A delay of one sample multiplies the  $z$ -transform by  $z^{-1}$ .

$$x[n - 1] \iff z^{-1}X(z)$$

Time delay of  $n_0$  samples multiplies the  $z$ -transform by  $z^{-n_0}$

$$x[n - n_0] \iff z^{-n_0}X(z)$$

# CONVOLUTION PROPERTY

■ Convolution in the **n**-domain

| SAME AS

■ Multiplication in the **z**-domain

$$y[n] = h[n] * x[n] \iff Y(z) = H(z)X(z)$$

$$\begin{aligned} y[n] &= x[n] * h[n] \\ &= \sum_{k=0}^M h[k]x[n - k] \end{aligned}$$

FIR Filter

MULTIPLY  
Z-TRANSFORMS

# CONVOLUTION PROPERTY

■ PROOF:

$$y[n] = x[n] * h[n] = \sum_{k=0}^M h[k]x[n - k]$$

$$Y(z) = \sum_{k=0}^M h[k] (z^{-k}X(z))$$

MULTIPLY  
Z-TRANSFORMS

$$= \left( \sum_{k=0}^M h[k]z^{-k} \right) X(z) = H(z)X(z).$$

# CONVOLUTION EXAMPLE

■ Finite-Length input  $x[n]$

Example 7.5

$$x[n] = \delta[n - 1] - \delta[n - 2] + \delta[n - 3] - \delta[n - 4]$$

$$\text{and } h[n] = \delta[n] + 2\delta[n - 1] + 3\delta[n - 2] + 4\delta[n - 3]$$

$$X(z) = 0 + 1z^{-1} - 1z^{-2} + 1z^{-3} - 1z^{-4}$$

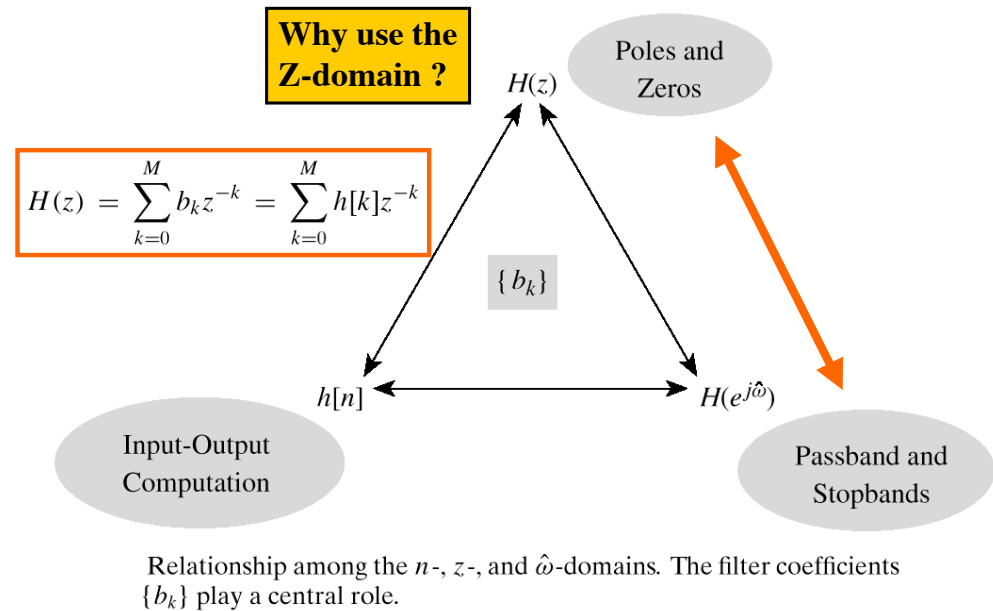
$$\text{and } H(z) = 1 + 2z^{-1} + 3z^{-2} + 4z^{-3}$$

MULTIPLY  
Z-TRANSFORMS

# ANOTHER ANALYSIS TOOL

- Why use the z-Transform ?
- The z-domain is **COMPLEX**
- $H(z)$  is a **COMPLEX-VALUED** function of a **COMPLEX VARIABLE**  $z$ .

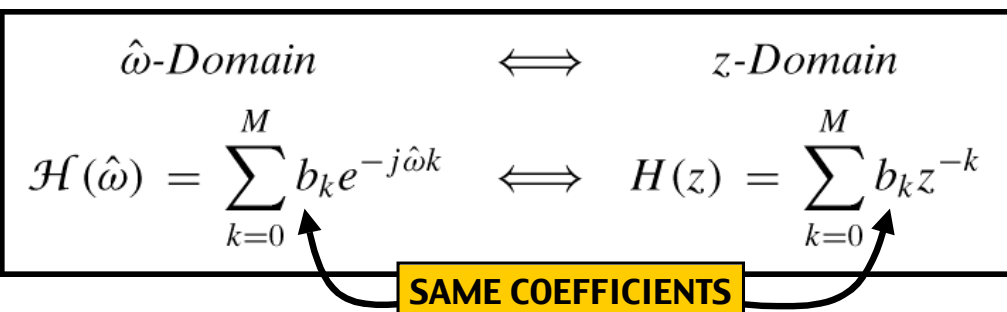
# THREE DOMAINS



# FREQUENCY RESPONSE ?

- Same Form:

$$z = e^{j\hat{\omega}}$$



# WHY USE the z-DOMAIN ?

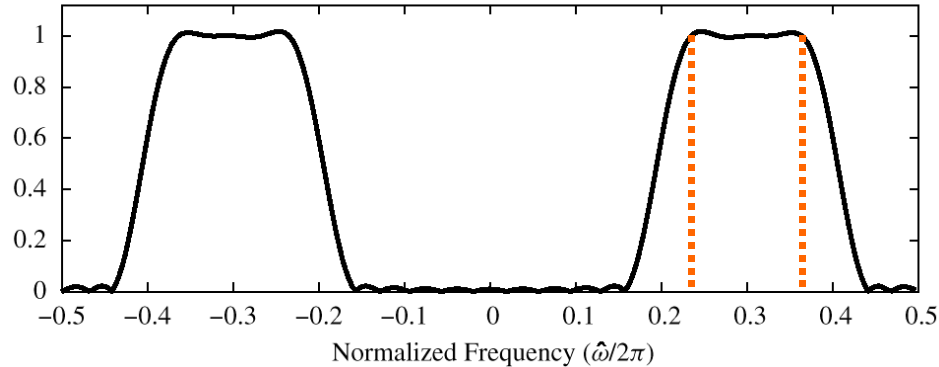
- FILTER DESIGN**
  - Derive  $\{b_k\}$  to **SYNTHESIZE** a good filter
  - The  $\{b_k\}$  are **POLYNOMIAL** coefficients
  - Design via the Polynomial **ROOTS**
- EXAMPLE:**
  - Design a Bandpass Filter with
  - Passband Spec:  $0.48\pi \leq \hat{\omega} \leq 0.72\pi$

# Filter Design SOFTWARE

## FILTER DESIGN EXAMPLE (L=24):

BPF with Passband:  $0.48\pi \leq \hat{\omega} \leq 0.72\pi$

Well-Designed 24-Point BPF



# ROOTS of H(z)

$$H(z) = (1 - z^{-1})(1 - z^{-1} + z^{-2})$$

$H(z) = 1 - 2z^{-1} + 2z^{-2} - z^{-3}$ , the roots are

$$z_1 = 1$$

$$z_2 = \frac{1}{2} + j\frac{1}{2}\sqrt{3} = 1e^{j\pi/3}$$

$$z_3 = \frac{1}{2} - j\frac{1}{2}\sqrt{3} = 1e^{-j\pi/3}$$

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# FACTORING H(z)

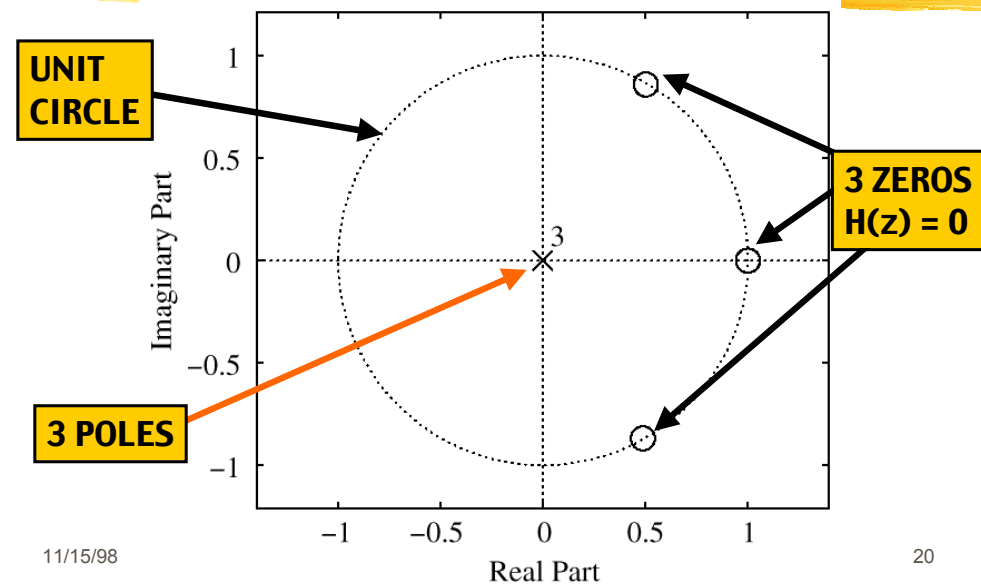
$$\begin{aligned} H(z) &= 1 - 2z^{-1} + 2z^{-2} - z^{-3} \\ &= (1 - z^{-1})(1 - e^{j\pi/3}z^{-1})(1 - e^{-j\pi/3}z^{-1}) \end{aligned}$$

if we multiply  $H(z)$  by  $z^3/z^3$ ,

we obtain the following two equivalent forms:

$$\begin{aligned} H(z) &= \frac{z^3 - 2z^2 + 2z - 1}{z^3} \\ &= \frac{(z - 1)(z - e^{j\pi/3})(z - e^{-j\pi/3})}{z^3} \end{aligned}$$

# PLOT ZEROS in z-DOMAIN

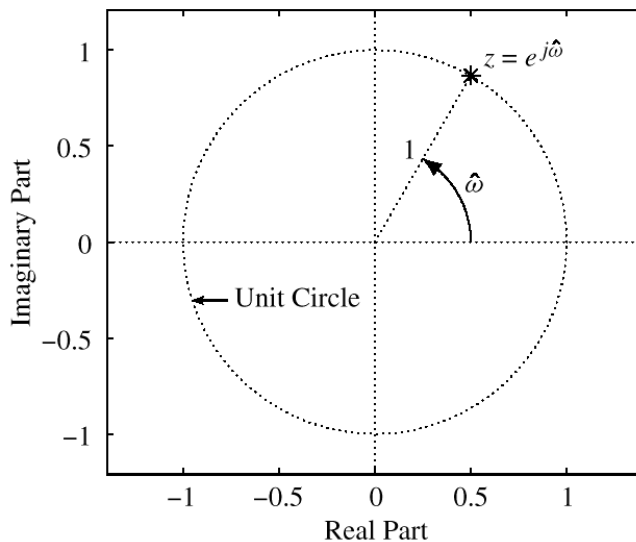


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$$\mathcal{H}(\hat{\omega}) = H(e^{j\hat{\omega}}) = H(z)|_{z=e^{j\hat{\omega}}}$$

The Complex z-Plane



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## CHANGE in NOTATION

- Relate  $H(z)$  to FREQUENCY RESPONSE

$$H(\hat{\omega}) = H(z)|_{z=e^{j\hat{\omega}}}$$

- NOTATION for FREQUENCY RESPONSE

$$H(\hat{\omega}) \leftrightarrow H(e^{j\hat{\omega}})$$

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## NULLING FILTER

- PLACE ZEROS to make  $y[n] = 0$

$$H(z) = 1 - 2z^{-1} + 2z^{-2} - z^{-3} \quad \leftarrow \text{3 ZEROS } H(z) = 0$$

the output resulting from each of the following three signals will be zero:

$$H(z_1) = 0 \quad x_1[n] = (z_1)^n = 1 \quad \rightarrow \quad y_1[n] = 0$$

$$H(z_2) = 0 \quad x_2[n] = (z_2)^n = e^{j\pi n/3} \quad y_2[n] = 0$$

$$H(z_3) = 0 \quad x_3[n] = (z_3)^n = e^{-j\pi n/3} \quad y_3[n] = 0$$

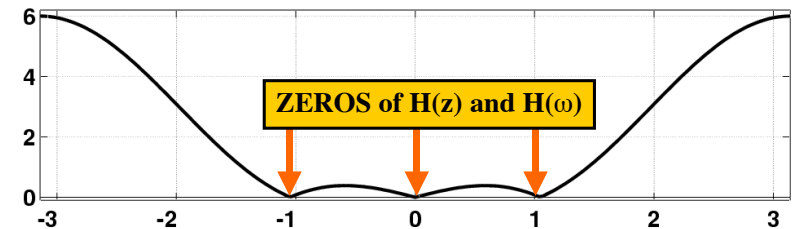
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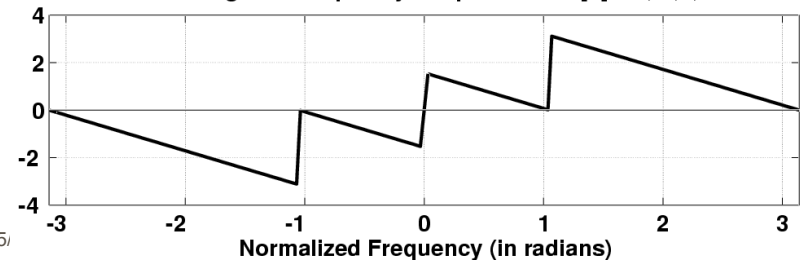
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## FIR Frequency Response

Magnitude of Frequency Response for  $h[n] = 1, -2, 2, -1$



Phase Angle of Frequency Response for  $h[n] = 1, -2, 2, -1$



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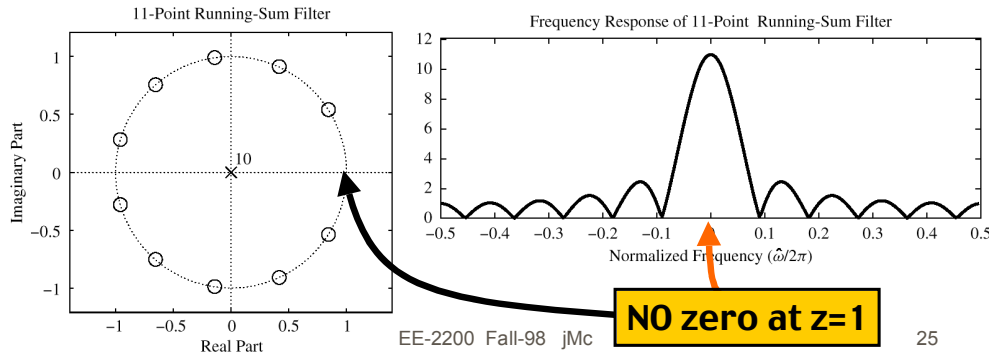
Normalized Frequency (in radians)

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# 11-pt RUNNING SUM $H(z)$

$$H(z) = \sum_{k=0}^{10} z^{-k}$$

$$H(z) = (1 - e^{j2\pi/11}z^{-1})(1 - e^{j4\pi/11}z^{-1}) \dots (1 - e^{j20\pi/11}z^{-1})$$



# L-pt RUNNING SUM $H(z)$

$$H(z) = \sum_{k=0}^{L-1} z^{-k} = \frac{1 - z^{-L}}{1 - z^{-1}} = \frac{z^L - 1}{z^{L-1}(z - 1)}$$

$$z^L - 1 = 0 \implies z^L = 1$$

$$z = e^{j2\pi k/L} \text{ for } k = 0, 1, 2, \dots, L - 1$$

**ZEROS on  
UNIT CIRCLE**

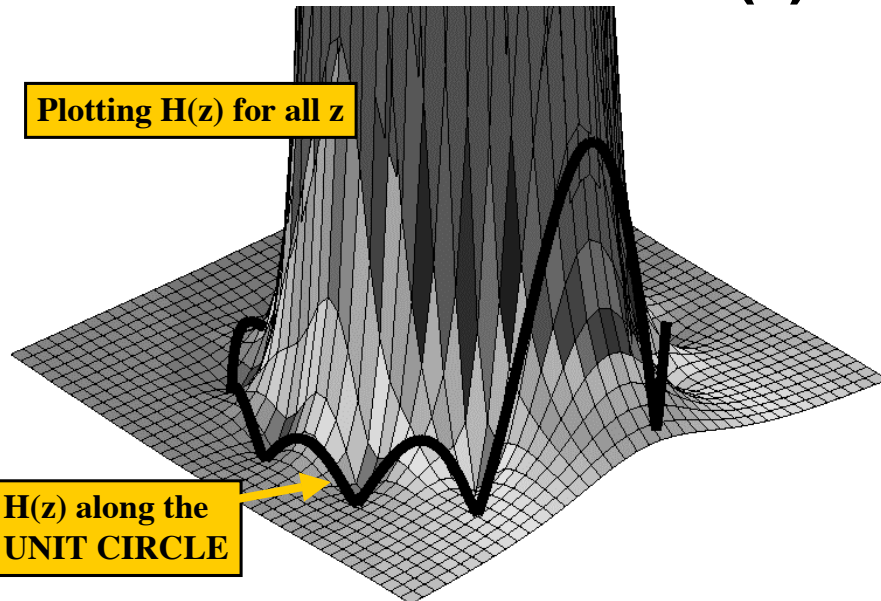
**Numerator  
has (z-1) term  
when k=0**

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# COMPLEX FUNCTION: $H(z)$

**Plotting  $H(z)$  for all  $z$**



# POP QUIZ

- Given:  $H(\hat{\omega}) = e^{-j\hat{\omega}} \cos(\hat{\omega})$
- Find the Impulse Response,  $h[n]$
- Find the output,  $y[n]$ 
  - When  $x[n] = \cos(0.25\pi n)$

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