

EE-2025

Spring-2001

Lecture 14
Zeros of $H(z)$
Frequency Domain
12-March-01

Info: Quiz #2

■ Quiz #2 Results

■ **Median: 84** Average = 80.6

■ Graders:

Prob-1: McClellan

Prob-2: Frazier

Prob-3: W. Smith

Prob-4: Casinovi

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2

Info: Web-CT, Lab, HW

■ Get NEW CHAPTERS

■ Continuous-Time Signals & Systems

■ [PDF \(Web-CT\) or Bookstore](#)

■ HW #8 Due NEXT week

■ Lab #7 due NEXT week

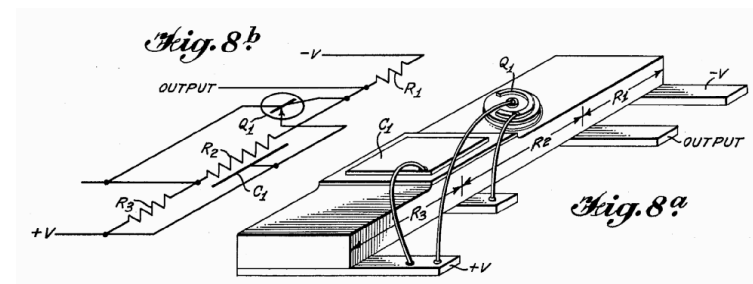
■ Lab #8 on Touch-Tone Decoding

■ Spans two weeks (Warm-up this week)

NOBEL PRIZE WINNER

■ Integrated Circuit: 1959 by Jack Kilby

■ <http://www.eepatents.com/feature/>



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LECTURE

4

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3

Lecture 14
Zeros of $H(z)$
Frequency Domain

READING ASSIGNMENTS

- This Lecture:
 - Chapter 7, pp. 220-230
- Other Reading:
 - Recitation & Lab: Ch. 7, pp. 220-239
 - ZEROS (and POLES)
 - Next Lecture: Notes on Continuous-Time

LECTURE OBJECTIVES

- ZEROS and POLES
- Relate $H(z)$ to FREQUENCY RESPONSE

$$H(\hat{\omega}) = H(z) \Big|_{z=e^{j\hat{\omega}}}$$

THREE DOMAINS:

■ Show Relationship for FIR:

$$h[n] \leftrightarrow H(z) \leftrightarrow H(e^{j\hat{\omega}})$$

DESIGN PROBLEM

- Example:
 - Design a Lowpass FIR filter (Find b_k)
 - Reject completely 0.7π , 0.8π , and 0.9π
 - Estimate the filter length needed to accomplish this task. How many b_k ?
- Z POLYNOMIALS provide the TOOLS

Z-Transform DEFINITION

- POLYNOMIAL Representation of LTI SYSTEM:

$$H(z) = \sum_n h[n]z^{-n}$$

APPLIES to Any SIGNAL

- EXAMPLE:

$$\{h[n]\} = \{2, 0, -3, 0, 2\}$$

$$H(z) = 2z^{-0} + 0z^{-1} - 3z^{-2} + 0z^{-3} + 2z^{-4}$$

$$= 2 - 3z^{-2} + 2z^{-4}$$

$$= 2 - 3(z^{-1})^2 + 2(z^{-1})^4$$

POLYNOMIAL in z^{-1}

CONVOLUTION PROPERTY

- Convolution in the n -domain
 | SAME AS
 Multiplication in the z -domain

$$y[n] = h[n] * x[n] \Leftrightarrow Y(z) = H(z)X(z)$$

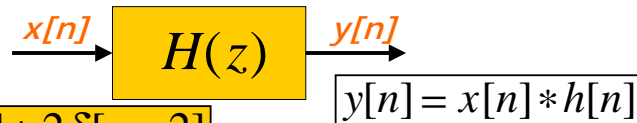
$$y[n] = h[n] * x[n]$$

$$= \sum_{k=0}^M h[k]x[n-k]$$

FIR Filter

MULTIPLY Z-TRANSFORMS

CONVOLUTION EXAMPLE



$$x[n] = \delta[n-1] + 2\delta[n-2]$$

$$h[n] = \delta[n] - \delta[n-1]$$

$$X(z) = z^{-1} + 2z^{-2}$$

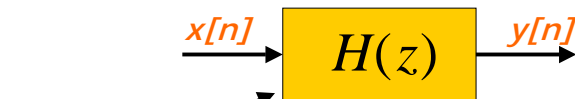
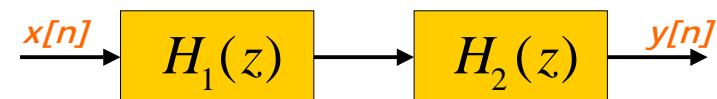
$$H(z) = 1 - z^{-1}$$

$$Y(z) = (z^{-1} + 2z^{-2})(1 - z^{-1}) = z^{-1} + z^{-2} - 2z^{-3}$$

$$y[n] = \delta[n-1] + \delta[n-2] - 2\delta[n-3]$$

CASCADE EQUIVALENT

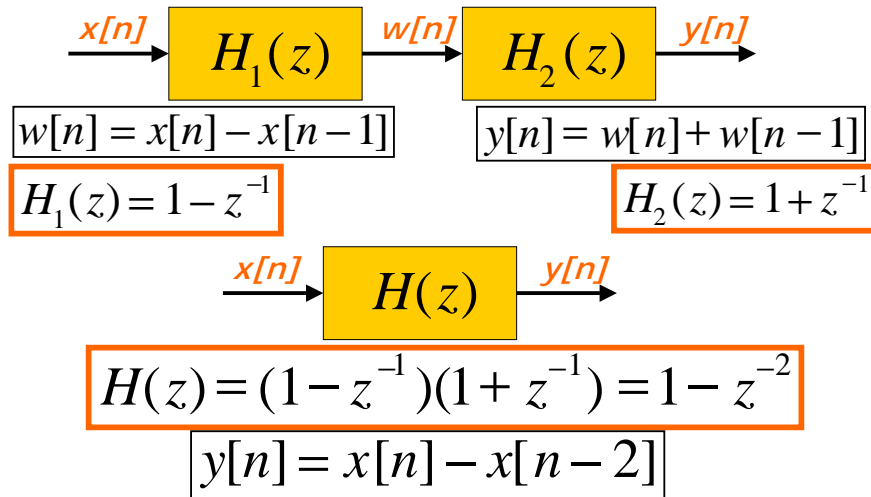
- Multiply the System Functions



EQUIVALENT SYSTEM

$$H(z) = H_1(z)H_2(z)$$

CASCADE EXAMPLE

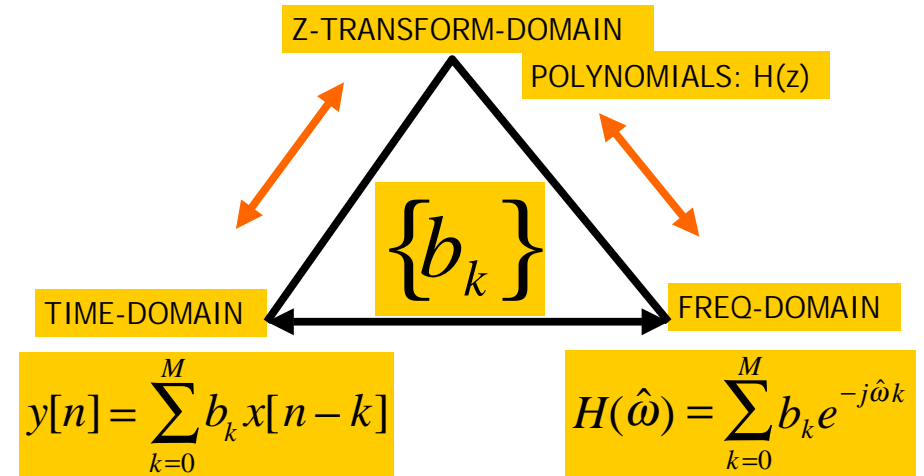


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9

THREE DOMAINS

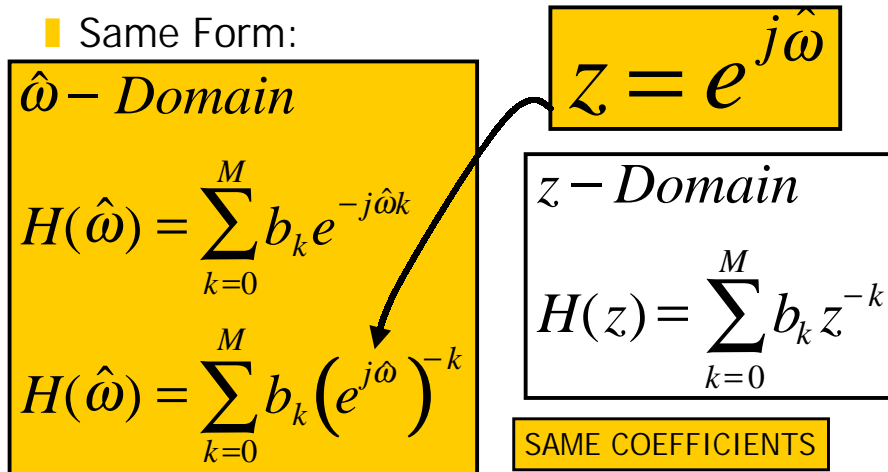


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10

FREQUENCY RESPONSE ?



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11

CHANGE in NOTATION

- Relate $H(z)$ to FREQUENCY RESPONSE

$$H(\hat{\omega}) = H(z) \Big|_{z=e^{j\hat{\omega}}}$$

- NEW NOTATION for FREQUENCY RESPONSE

$$H(\hat{\omega}) \leftrightarrow H(e^{j\hat{\omega}})$$

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12

ANOTHER ANALYSIS TOOL

- z-Transform POLYNOMIALS are EASY !
 - ▮ ROOTS, FACTORS, etc.
- **ZEROS and POLES: where is $H(z) = 0$?**
- The z-domain is **COMPLEX**
 - ▮ $H(z)$ is a **COMPLEX-VALUED** function of a **COMPLEX VARIABLE** z .

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13

ZEROS of $H(z)$

- Find z , where $H(z)=0$

$$H(z) = 1 - \frac{1}{2} z^{-1}$$

$$1 - \frac{1}{2} z^{-1} = 0 ?$$

$$z - \frac{1}{2} = 0$$

$$\text{Zero at: } z = \frac{1}{2}$$

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14

ZEROS of $H(z)$

- Find z , where $H(z)=0$
 - ▮ Interesting when z is ON the unit circle.

$$H(z) = 1 - 2z^{-1} + 2z^{-2} - z^{-3}$$

$$H(z) = (1 - z^{-1})(1 - z^{-1} + z^{-2})$$

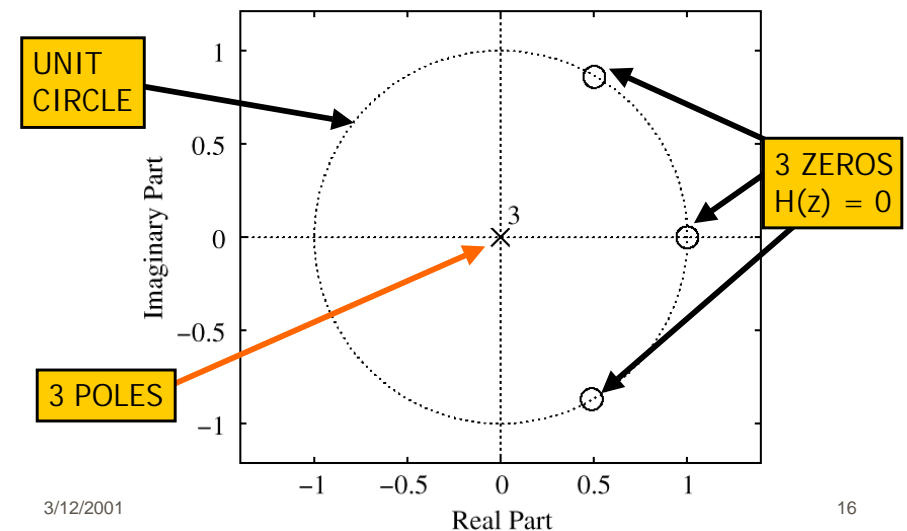
$$\text{Roots: } z = 1, \frac{1}{2} \pm j\frac{\sqrt{3}}{2} \quad \boxed{e^{\pm j\pi/3}}$$

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15

PLOT ZEROS in z-DOMAIN



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16

POLES of $H(z)$

Find z , where $H(z) \rightarrow \infty$

Not very interesting for the FIR case

$$H(z) = 1 - 2z^{-1} + 2z^{-2} - z^{-3}$$

$$H(z) = \frac{z^3 - 2z^2 + 2z - 1}{z^3}$$

Three Poles at: $z = 0$

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17

FREQ. RESPONSE from ZEROS

$$H(e^{j\hat{\omega}}) = H(z) \Big|_{z=e^{j\hat{\omega}}}$$

- Relate $H(z)$ to FREQUENCY RESPONSE
- EVALUATE $H(z)$ on the **UNIT CIRCLE**
 - ANGLE is same as FREQUENCY

$z = e^{j\hat{\omega}}$ (as $\hat{\omega}$ varies)
defines a **CIRCLE**, radius = 1

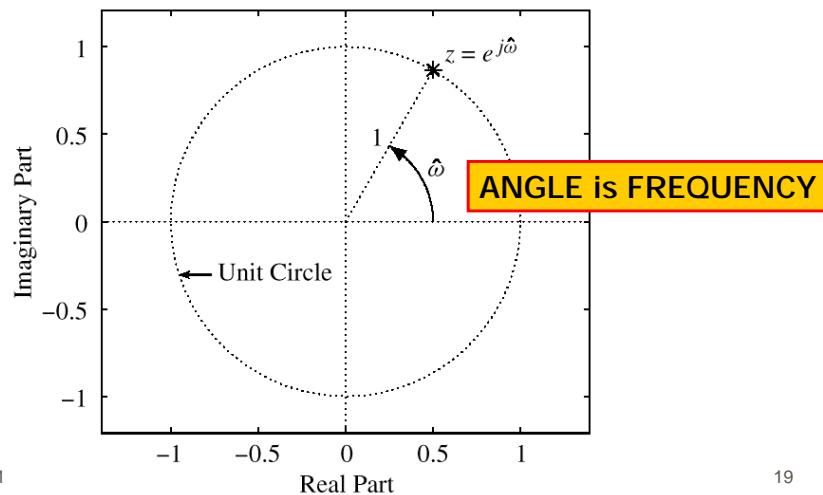
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18

$$\mathcal{H}(\hat{\omega}) = H(e^{j\hat{\omega}}) = H(z) \Big|_{z=e^{j\hat{\omega}}}$$

The Complex z -Plane

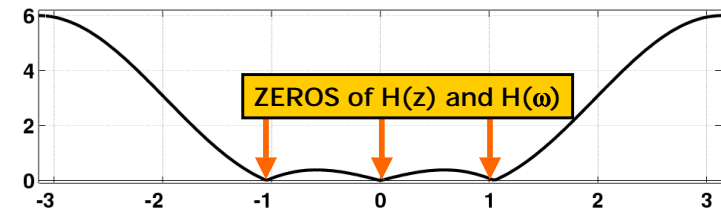


3/1

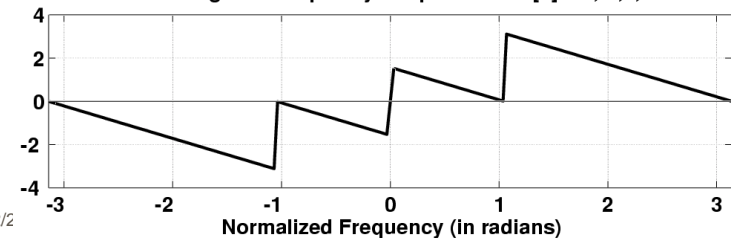
19

FIR Frequency Response

Magnitude of Frequency Response for $h[n] = 1, -2, 2, -1$



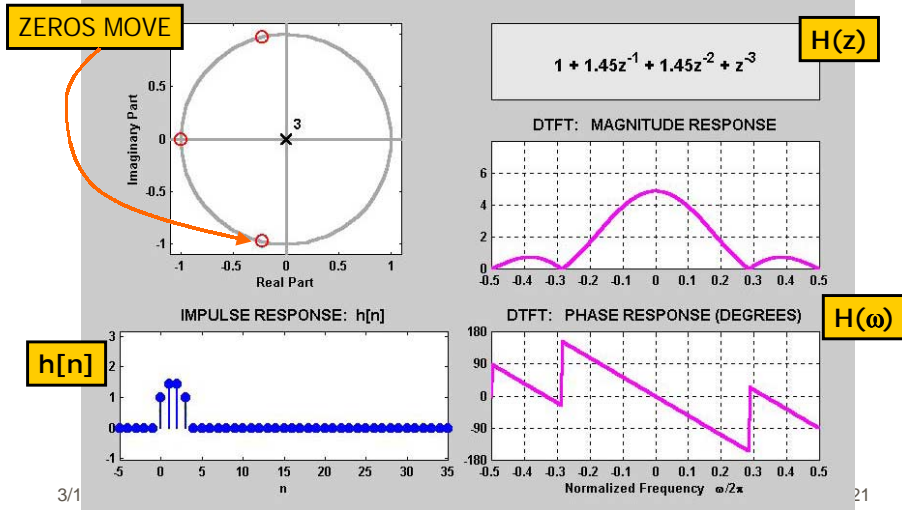
Phase Angle of Frequency Response for $h[n] = 1, -2, 2, -1$



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20

3 DOMAINS MOVIE: FIR

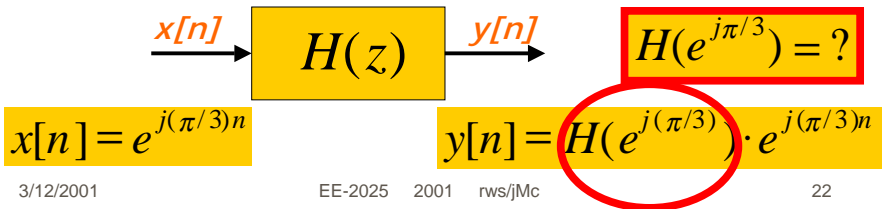


NULLING PROPERTY of H(z)

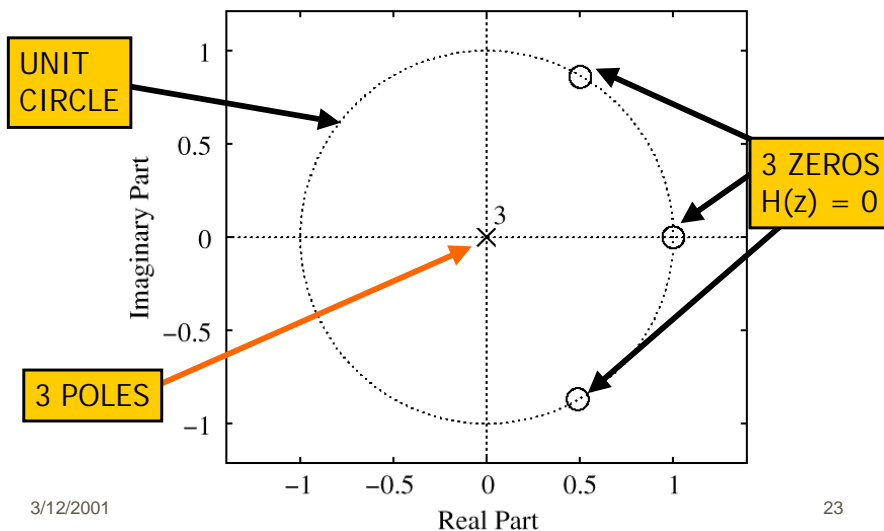
- When $H(z)=0$ on the unit circle.
 - Find inputs $x[n]$ that give zero output

$$H(z) = 1 - 2z^{-1} + 2z^{-2} - z^{-3}$$

$$H(e^{j\hat{\omega}}) = 1 - 2e^{-j\hat{\omega}} + 2e^{-j2\hat{\omega}} - e^{-j3\hat{\omega}}$$



PLOT ZEROS in z-DOMAIN



NULLING PROPERTY of H(z)

- Evaluate $H(z)$ at the input "frequency"

$$H(e^{j\hat{\omega}}) = 1 - 2e^{-j\hat{\omega}} + 2e^{-j2\hat{\omega}} - e^{-j3\hat{\omega}}$$

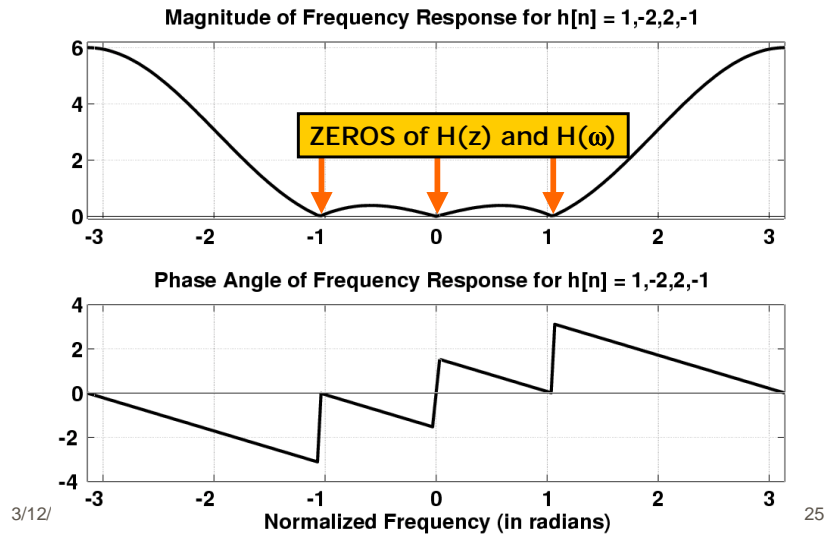
$$y[n] = H(e^{j\pi/3}) \cdot e^{j(\pi/3)n}$$

$$y[n] = (1 - 2e^{-j\pi/3} + 2e^{-j2\pi/3} - e^{-j3\pi/3}) \cdot e^{j(\pi/3)n}$$

$$(1 - 2(\frac{1}{2} - j\frac{\sqrt{3}}{2}) + 2(-\frac{1}{2} - j\frac{\sqrt{3}}{2}) + 1)$$

$$y[n] = (1 - 1 + j\sqrt{3} - 1 - j\sqrt{3} + 1) \cdot e^{j(\pi/3)n} = 0$$

FIR Frequency Response



L-pt RUNNING SUM $H(z)$

$$H(z) = \sum_{k=0}^{L-1} \frac{1}{L} z^{-k} = \frac{1 - z^{-L}}{L(1 - z^{-1})} = \frac{z^L - 1}{Lz^{L-1}(z - 1)}$$

$$z^L - 1 = 0 \Rightarrow z^L = 1 = e^{j2\pi k}$$

$$z = e^{j(2\pi/L)k} \text{ for } k = 1, 2, \dots, L-1$$

ZEROS on UNIT CIRCLE

$(z-1)$ in denominator cancels $k=0$ term

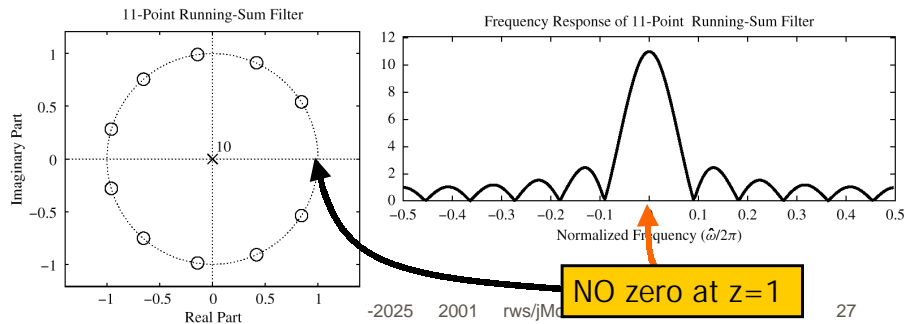
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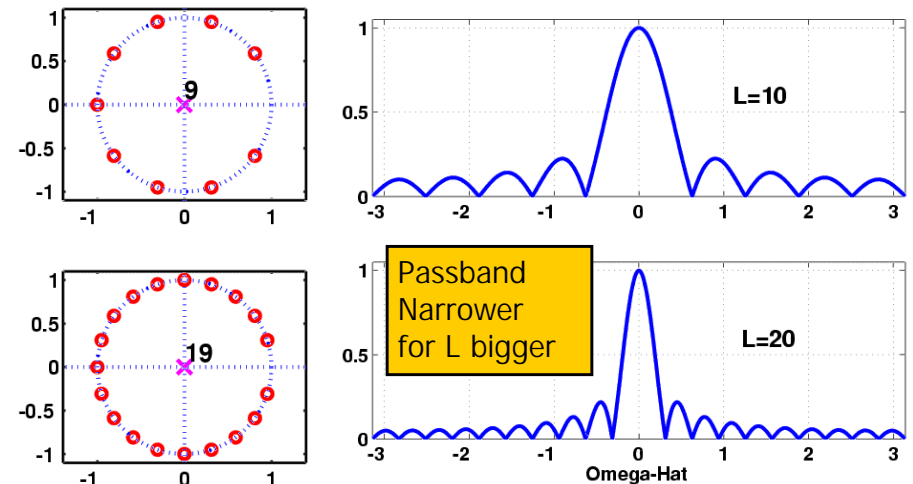
11-pt RUNNING SUM $H(z)$

$$H(z) = \sum_{k=0}^{10} z^{-k}$$

$$H(z) = (1 - e^{j2\pi/11} z^{-1})(1 - e^{j4\pi/11} z^{-1}) \dots (1 - e^{j20\pi/11} z^{-1})$$



FILTER DESIGN: CHANGE L



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28