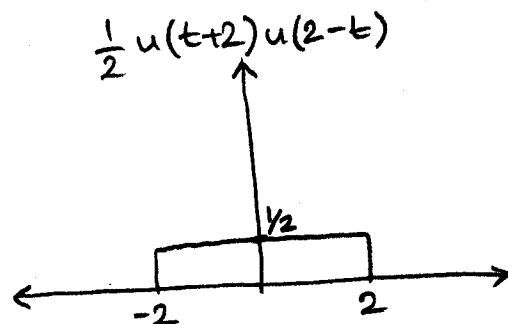
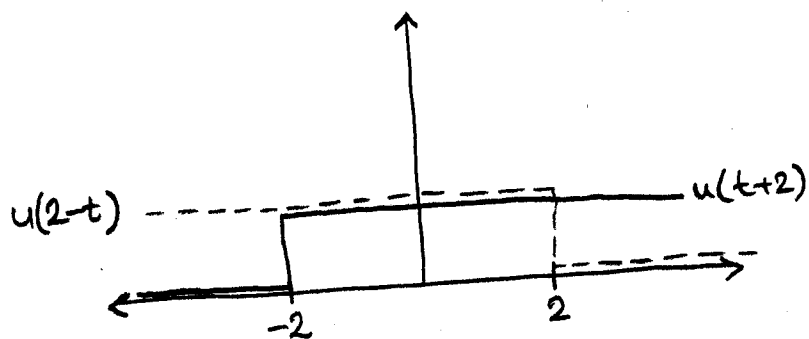


Solutions for Problem Set #14

(1)

14.1

(a) $x(t) = \frac{1}{2} u(t+2) u(2-t)$



$$x(t) = \frac{1}{2} u(t+2) u(2-t) = \frac{1}{2} [u(t+2) - u(t-2)]$$

$$X(j\omega) = \frac{\sin(2\omega)}{\omega}$$

(b) $x(t) = \frac{d}{dt} \left(\frac{\sin(20\pi t)}{10\pi t} \right)$

Let $y(t) = \frac{1}{10} \cdot \frac{\sin(20\pi t)}{\pi t}$. Then, $Y(j\omega) = \frac{1}{10} [u(\omega+20\pi) - u(\omega-20\pi)]$

$$X(j\omega) = (j\omega) \cdot Y(j\omega) = (j\omega) \cdot \frac{1}{10} \cdot [u(\omega+20\pi) - u(\omega-20\pi)]$$

(c) $x(t) = \frac{\sin(20\pi t)}{10\pi t} \cdot \cos(100\pi t)$

$$X(j\omega) = \frac{1}{2} Y(j(\omega-100\pi)) + \frac{1}{2} Y(j(\omega+100\pi))$$

Use $Y(j\omega)$ from part (b).

$$X(j\omega) = \frac{1}{20} [u(\omega-80\pi) - u(\omega-120\pi)] + \frac{1}{20} [u(\omega+120\pi) - u(\omega+80\pi)]$$

$$(d) X(j\omega) = \frac{e^{-j2\omega}}{3+j4\omega}$$

$$X(j\omega) = e^{-j2\omega} \cdot \frac{1}{4} \cdot \frac{1}{\frac{3}{4}+j\omega}$$

$$\text{Let } V(j\omega) = \frac{1}{4} \cdot \frac{1}{\frac{3}{4}+j\omega} \quad \text{Then, } v(t) = \frac{1}{4} \cdot e^{-\frac{3}{4}t} \cdot u(t)$$

$$x(t) = v(t-2)$$

$$x(t) = \frac{1}{4} \cdot e^{-\frac{3}{4}(t-2)} \cdot u(t-2)$$

$$(e) X(j\omega) = \frac{j2\omega}{3+4j\omega}$$

$$X(j\omega) = \frac{2}{4} \cdot \frac{j\omega}{\frac{3}{4}+j\omega} = \frac{1}{2} \cdot j\omega \cdot \frac{1}{\frac{3}{4}+j\omega}$$

$$x(t) = \frac{1}{2} \frac{d}{dt} e^{-\frac{3}{4}t} u(t)$$

$$= \frac{1}{2} e^{-\frac{3}{4}t} \left(\delta(t) - \frac{3}{4} u(t) \right)$$

(f) Let $\omega_0 = 20\pi$ and $a_k = e^{j\pi k}$. Then,

$$X(j\omega) = \pi \sum_{k=-\infty}^{\infty} a_k \cdot \delta(\omega - k \cdot \omega_0)$$

$$x(t) = \frac{1}{2} \cdot \sum_{k=-\infty}^{\infty} a_k \cdot e^{jk\omega_0 t}$$

$$= \frac{1}{2} \sum_{k=-\infty}^{\infty} e^{j\pi k} \cdot e^{jk20\pi t}$$

PROBLEM 14.1*:

(f) $X(j\omega) = \sum_{k=-\infty}^{\infty} \pi e^{j\pi k} \delta(\omega - 20\pi k)$ (*Make a plot of $x(t)$ obtained in this part.*)

Solution: The regularly spaced impulses in ω represent the Fourier Series coefficients of a periodic signal in the time domain. Thus

$$X(j\omega) = \sum_{k=-\infty}^{\infty} \pi e^{j\pi k} \delta(\omega - 20\pi k) = \sum_{k=-\infty}^{\infty} 2\pi a_k \delta(\omega - 20\pi k)$$

Can you find the signal $x(t)$ that has the Fourier Series coefficients given by $a_k = \frac{1}{2} e^{j\pi k}$?

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{j20\pi kt} = \sum_{k=-\infty}^{\infty} \frac{1}{2} e^{j\pi k} e^{j20\pi kt} = \frac{1}{2} \sum_{k=-\infty}^{\infty} e^{j20\pi k(t+1/20)} \quad (1)$$

The answer comes from the identity: $\sum_{n=-\infty}^{\infty} \delta(t - nT) = \frac{1}{T} \sum_{k=-\infty}^{\infty} e^{j2\pi kt/T}$

The value of T is $T = 1/10$, and we need the identity with t replaced by $(t + 1/20)$ in order to match Eq. (1).

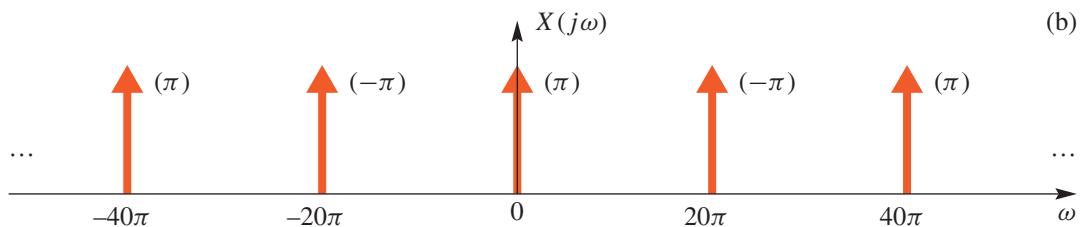
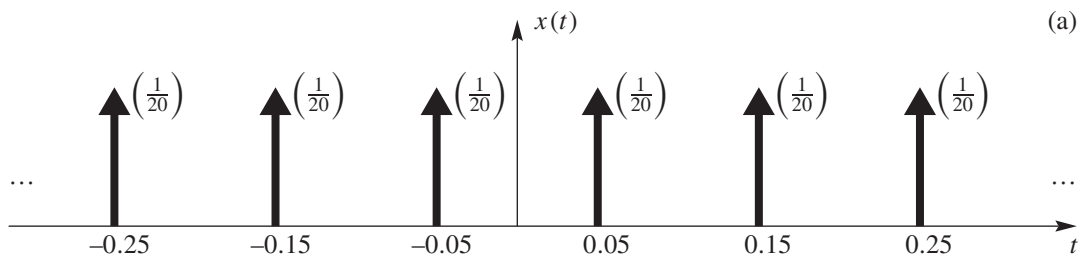
$$\sum_{n=-\infty}^{\infty} \delta(t + 1/20 - n/10) = 10 \sum_{k=-\infty}^{\infty} e^{j20\pi k(t+1/20)}$$

Finally, the signal $x(t)$ in (1) can be written as an impulse train:

$$x(t) = \sum_{n=-\infty}^{\infty} \frac{1}{20} \delta(t + 0.05 - 0.1n)$$

where the impulses are located at $t = \dots, -0.15, -0.05, 0.05, 0.15, 0.25, \dots$

From this equation, the plot of $x(t)$ is a shifted impulse train.



Note: Another way to get this answer is to use the *Shifting Property*

$$x(t - t_d) \longleftrightarrow e^{-j\omega t_d} X(j\omega)$$

and apply it to $X(j\omega)$ rewritten as:

$$X(j\omega) = \sum_{k=-\infty}^{\infty} \pi e^{j\pi k} \delta(\omega - 20\pi k) = e^{j\omega/20} \left(\sum_{k=-\infty}^{\infty} \pi \delta(\omega - 20\pi k) \right)$$

because $e^{j\omega/20}$ evaluated at $\omega = 20\pi k$ is $e^{j\pi k}$, from which we conclude that the time shift is $t_d = 1/20$ secs.

14.2

(a) From figure (b) $\Rightarrow f_{\max} = \frac{80\pi}{2\pi} = 40 \text{ Hz}$

From Sampling Theorem $\Rightarrow f_s \geq 2 \cdot f_{\max} = 80 \text{ samples/sec}$

$$T_s = \frac{1}{80} \text{ sec} \quad \omega_s = \frac{2\pi}{T_s} = 160\pi$$

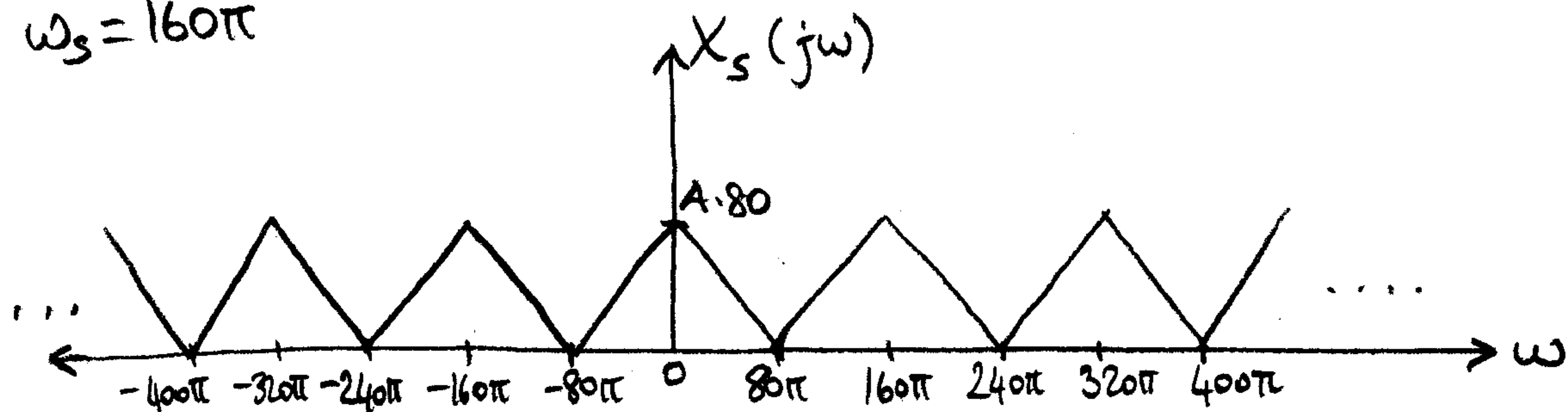
$$x_s(t) = x(t) \cdot p(t)$$

$$X_s(j\omega) = \frac{1}{2\pi} X(j\omega) * P(j\omega)$$

$$= \frac{1}{2\pi} X(j\omega) * \frac{2\pi}{T_s} \sum_{k=-\infty}^{\infty} \delta(\omega - \frac{2\pi}{T_s} k)$$

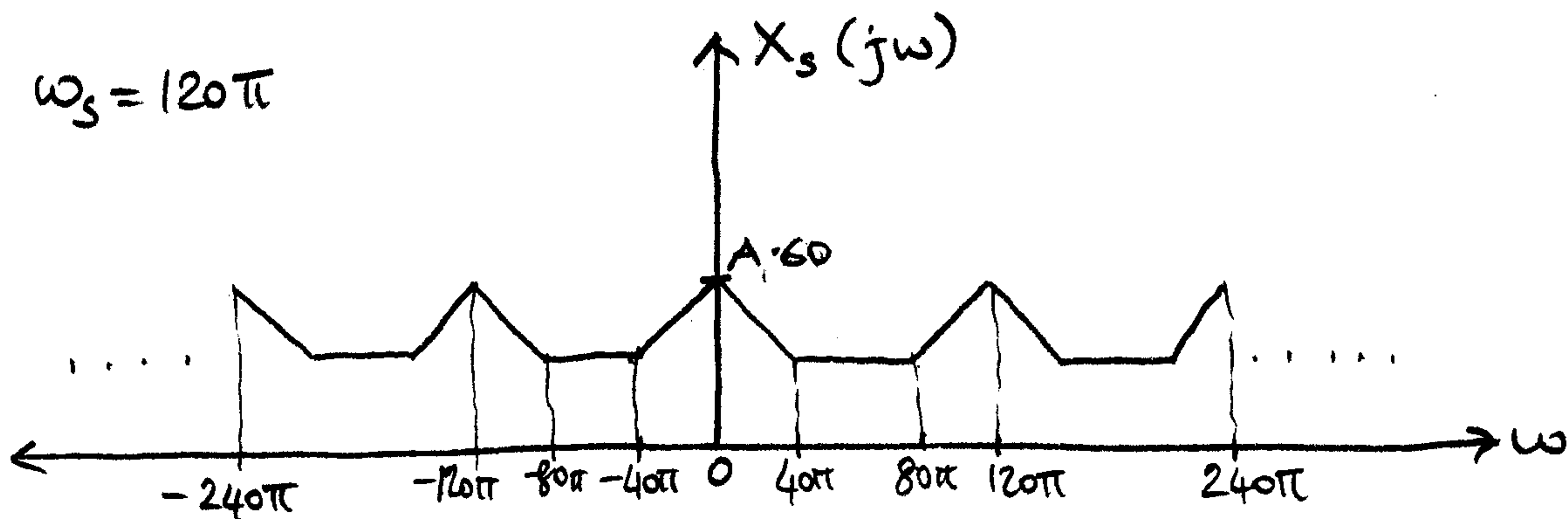
$$= \frac{1}{T_s} \sum_{k=-\infty}^{\infty} X(j\omega - 160\pi k)$$

$$\omega_s = 160\pi$$

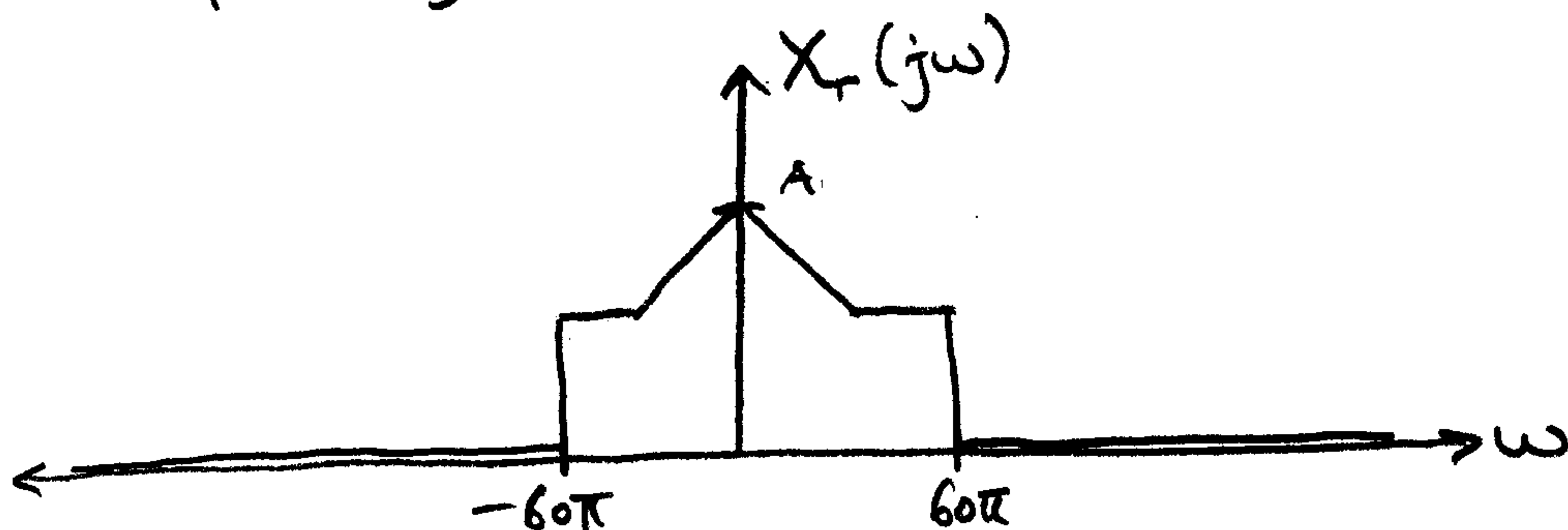


(b)

$$\omega_s = 120\pi$$



(c) The LPF defined by $H_r(j\omega)$ removes all frequencies beyond 60π .



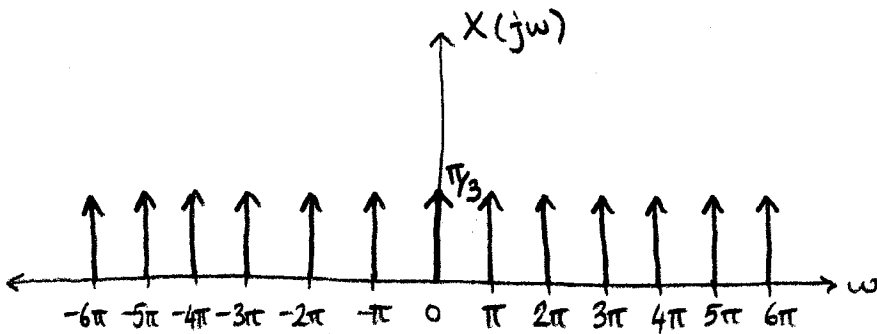
14.3

$$(a) \quad x(t) = \sum_{n=-\infty}^{\infty} \frac{1}{3} \delta(t-2n)$$

$$\text{Use } \sum_{n=-\infty}^{\infty} \delta(t-nT) \xleftrightarrow{F} \frac{2\pi}{T} \sum_{n=-\infty}^{\infty} \delta(\omega - \frac{2\pi}{T} n)$$

where $T=2$.

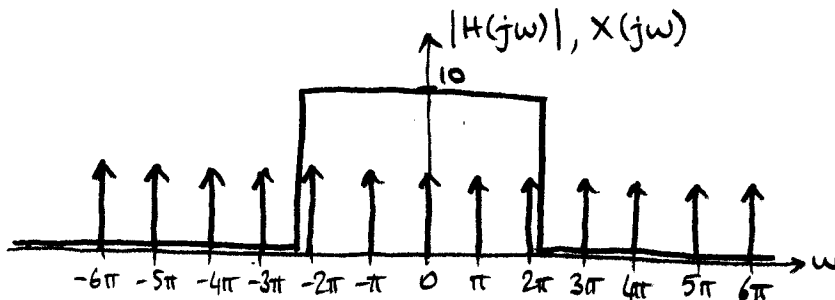
$$\begin{aligned} X(j\omega) &= \frac{1}{3} \cdot \frac{2\pi}{2} \sum_{n=-\infty}^{\infty} \delta(\omega - \frac{2\pi}{2} n) \\ &= \frac{\pi}{3} \sum_{n=-\infty}^{\infty} \delta(\omega - \pi n) \end{aligned}$$



(b)

$$H(j\omega) = e^{-j\omega 0.1} \cdot 10 [u(\omega + 2.2\pi) - u(\omega - 2.2\pi)] = \begin{cases} 10 \cdot e^{-j\omega 0.1} & , -2.2\pi \leq \omega < 2.2\pi \\ 0 & , \text{o/w} \end{cases}$$

$e^{-j\omega 0.1}$ does not contribute to $|H(j\omega)|$



$$\begin{aligned}
 (c) \quad Y(j\omega) &= X(j\omega) \cdot H(j\omega) = \frac{10\pi}{3} \cdot e^{-j\omega 0.1} (\delta(\omega+2\pi) + \delta(\omega+\pi) + \delta(\omega) + \delta(\omega-\pi) + \delta(\omega-2\pi)) \\
 &= \frac{5}{3} e^{-j\omega 0.1} (2\pi\delta(\omega+2\pi) + 2\pi\delta(\omega+\pi) + 2\pi\delta(\omega-0) + 2\pi\delta(\omega-\pi) + 2\pi\delta(\omega-2\pi)) \\
 y(t) &= \frac{5}{3} \left(e^{j2\pi(t-0.1)} + e^{j\pi(t-0.1)} + e^{j0} + e^{j\pi(t-0.1)} + e^{j2\pi(t-0.1)} \right)
 \end{aligned}$$

$$y(t) = \frac{5}{3} + \frac{10}{3} \cos(\pi(t-0.1)) + \frac{10}{3} \cos(2\pi(t-0.1))$$

(d) For $y(t)$ to be constant, $Y(j\omega)$ should not have any components of the form $\delta(\omega-\omega_0)$. Therefore, only $\delta(\omega)$ must pass through the filter. So, we conclude that $\omega_0 < \pi$.

In this case, $Y(j\omega)$ becomes

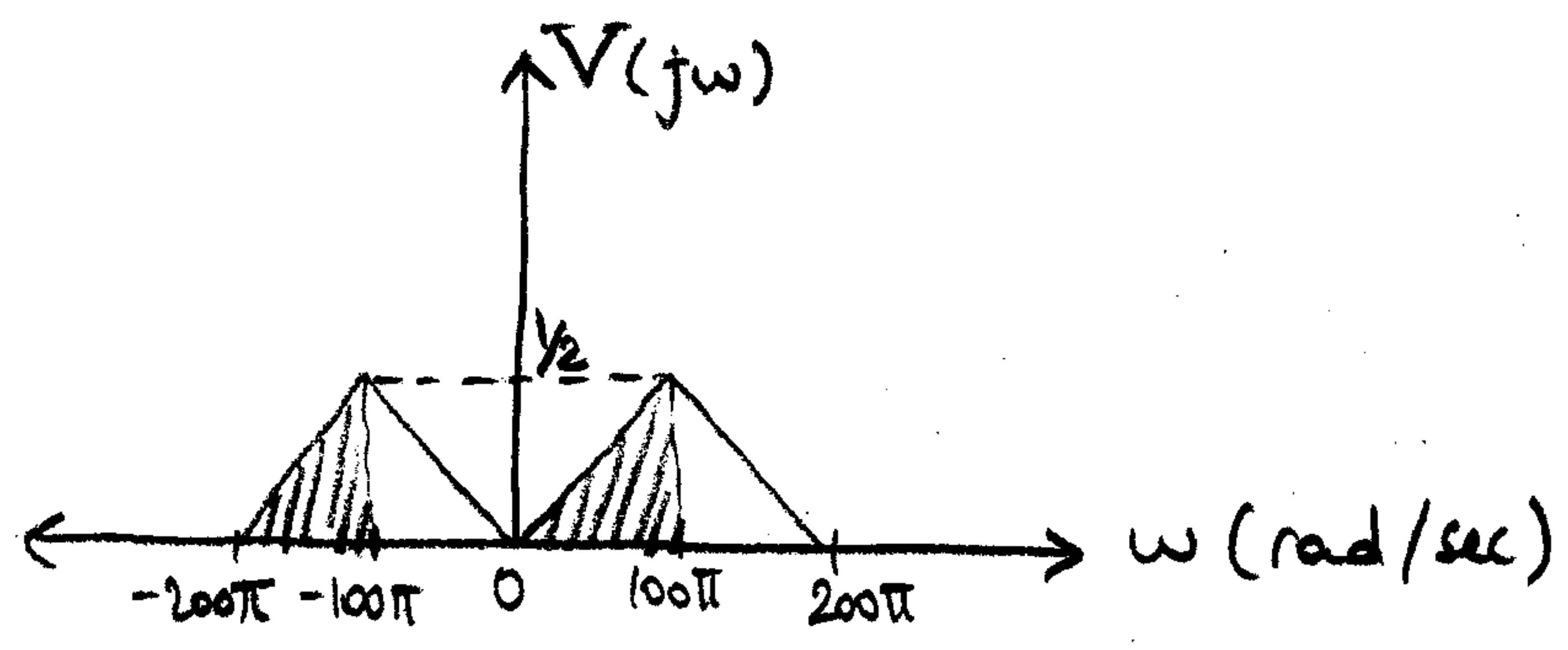
$$Y(j\omega) = \frac{5}{3} e^{-j\omega 0.1} \cdot 2\pi\delta(\omega-0)$$

$$y(t) = \frac{5}{3} e^{j0} = \frac{5}{3} = C$$

14.4

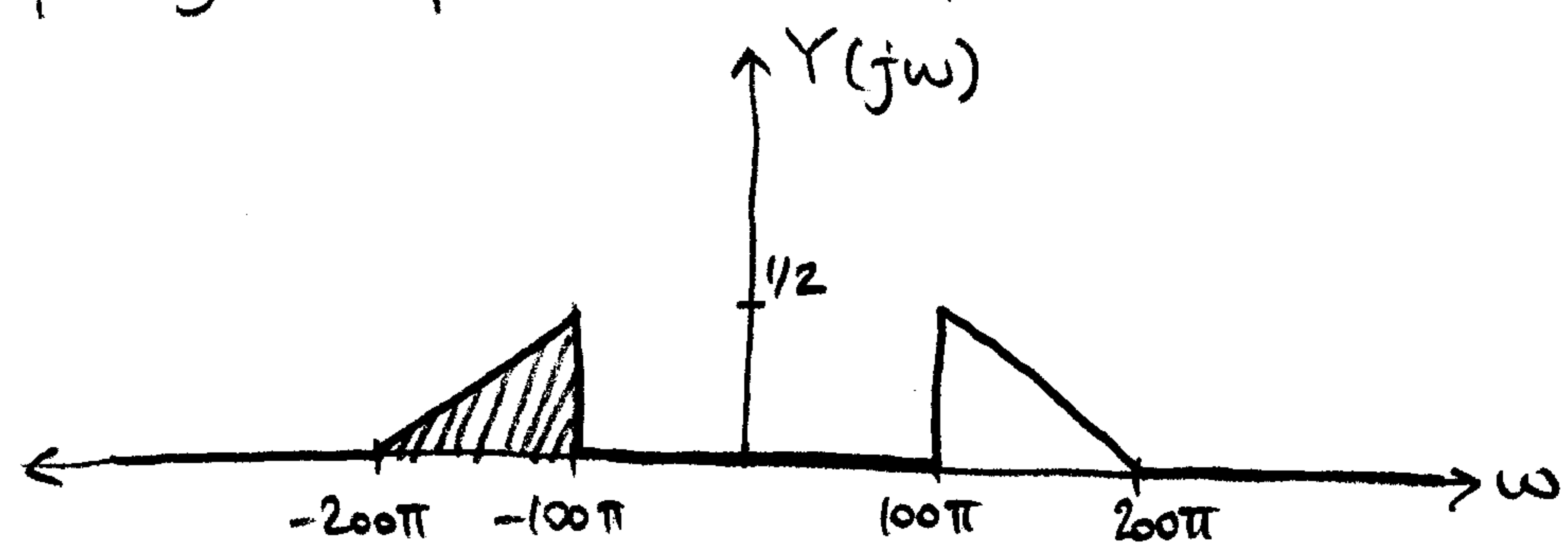
(a) $v(t) = x(t) \cdot \cos(100\pi t)$

$$V(j\omega) = \frac{1}{2} X(j(\omega - 100\pi)) + \frac{1}{2} X(j(\omega + 100\pi))$$

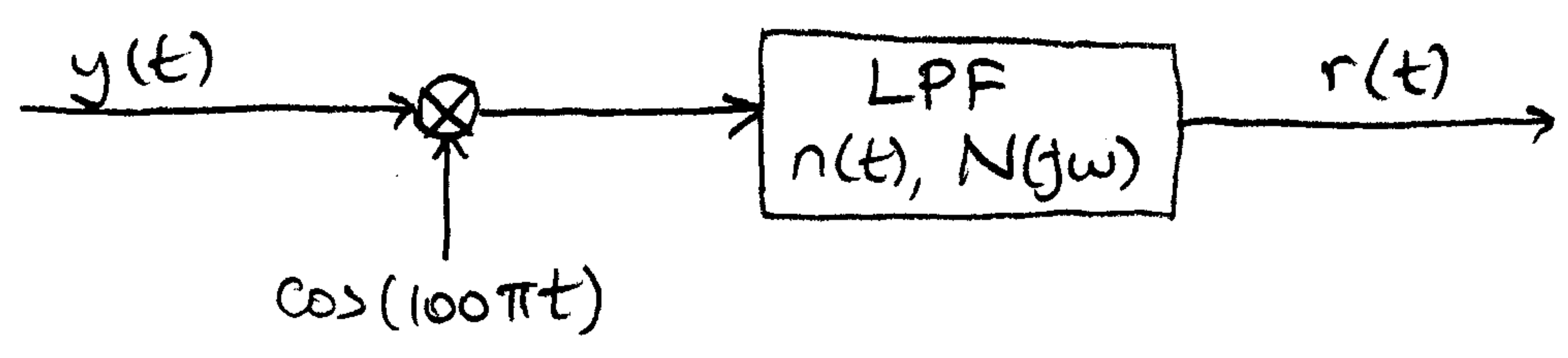


Note that $X(j\omega)$ is shifted left and right by 100π .

$H(j\omega)$ is a HPF with $\omega_{co} = 100\pi$. Therefore, it will remove all frequency components with $|\omega| < 100\pi$. Thus, we get



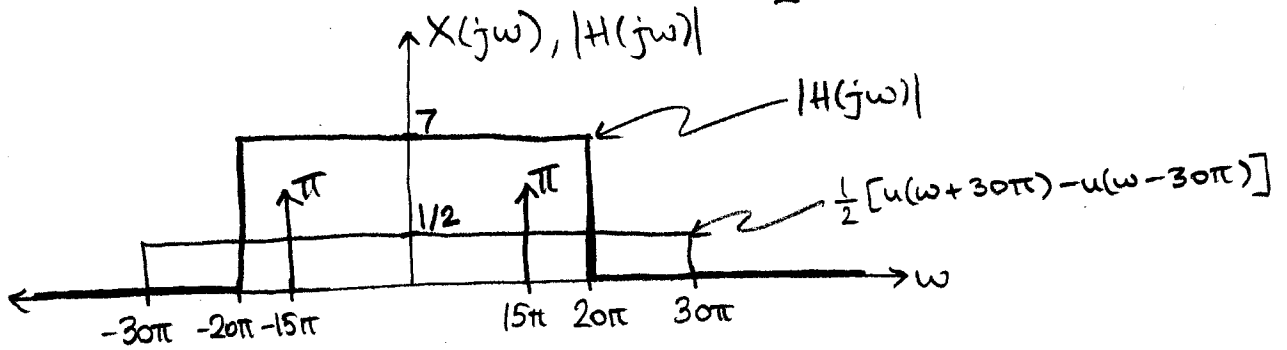
(b) If we take the plot above, shift it left and right by 100π and filter out all components with $|\omega| > 100\pi$, we will get the input $X(j\omega)$ back, i.e.,



where
$$N(j\omega) = \begin{cases} 0, & |\omega| > 100\pi \\ 4, & |\omega| \leq 100\pi \end{cases}$$

14.5

(a) $X(j\omega) = \pi \delta(\omega - 15\pi) + \pi \delta(\omega + 15\pi) + \frac{1}{2} [u(\omega + 30\pi) - u(\omega - 30\pi)]$



$$Y(j\omega) = (\pi \delta(\omega - 15\pi) + \pi \delta(\omega + 15\pi)) \cdot 7 \cdot e^{-j\frac{\omega}{25}} + \frac{1}{2} [u(\omega + 20\pi) - u(\omega - 20\pi)] \cdot 7 \cdot e^{-j\frac{\omega}{25}}$$

$$y(t) = 7 \cdot \cos(15\pi(t - 1/25)) + 7 \cdot \frac{\sin(20\pi(t - 1/25))}{2\pi(t - 1/25)}$$

(b) $\cos(50\pi t) \xrightarrow{F} \pi \delta(\omega - 50\pi) + \pi \delta(\omega + 50\pi)$

So, this component will be removed by the filter, and the output signal will be the same as in part (a)

(c) $\frac{1}{2} \delta(t) \xrightarrow{F} \frac{1}{2}$

So, this component will have the same effect as $\frac{\sin(30\pi t)}{2\pi t}$

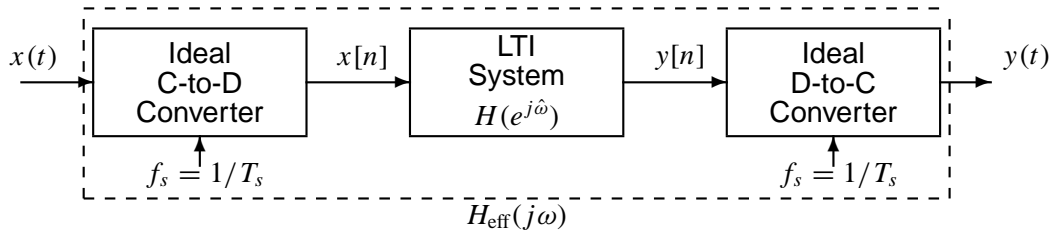
after filtering because both components are equivalent to $\frac{1}{2}$ in the range $[-20\pi, 20\pi]$ in the frequency domain.

Therefore, the output will be the same as in part (a).

(d) As explained above, the filtered output in part (a) is composed of two impulses at -15π and 15π , and a constant of $\frac{1}{2}$. In part (b), the third component is completely removed by the filter. In part (c), $\frac{1}{2} \delta(t)$ has the same net effect as $\frac{\sin(30\pi t)}{2\pi t}$ in the filtered range. Therefore, the output is the same in all parts.

PROBLEM 14.6:

Consider the following system for discrete-time filtering of a continuous-time signal:



- (a) The difference equation

$$y[n] = 0.8y[n - 1] + x[n] + x[n - 2],$$

has a system function $H(z)$ and frequency response given by

$$H(z) = \frac{1 + z^{-2}}{1 - 0.8z^{-1}} \quad \text{and} \quad H(e^{j\hat{\omega}}) = \frac{1 + e^{-j2\hat{\omega}}}{1 - 0.8e^{-j\hat{\omega}}}$$

The overall effective frequency response, $H_{\text{eff}}(j\omega)$, of the above system is obtained by replacing $\hat{\omega}$ with $\omega/200$

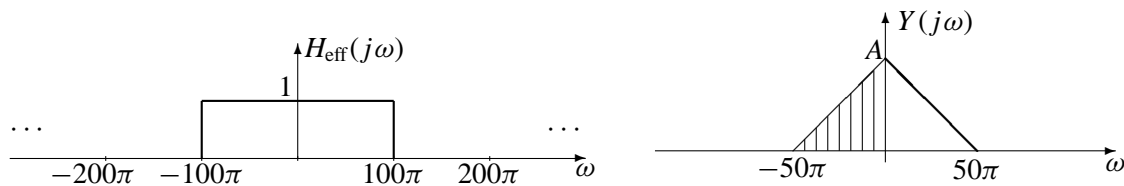
$$H_{\text{eff}}(j\omega) = \begin{cases} \frac{1 + e^{-j\omega/100}}{1 - 0.8e^{-j\omega/200}} & \text{for } |\omega| \leq 200\pi \\ \text{not defined} & \text{for } |\omega| > 200\pi \end{cases}$$

If the input is $x(t) = 2 \cos(100\pi t)$, we evaluate $H_{\text{eff}}(j\omega)$ at $\omega = 100\pi$.

$$H_{\text{eff}}(j100\pi) = \frac{1 + e^{-j100\pi/100}}{1 - 0.8e^{-j100\pi/200}} = \frac{1 + e^{-j\pi}}{1 - 0.8e^{-j\pi}} = 0$$

So, the output is $y(t) = 0$.

- (b) In order for the Fourier transforms of the input and output to satisfy the relation $Y(j\omega) = H_{\text{eff}}(j\omega)X(j\omega)$, the Sampling Theorem must be enforced so that we have no aliasing. Thus the *smallest* value of the sampling frequency f_s is $f_s = 50$ Hz, which is equivalent to $\omega_s = 100\pi$ rad/s.
- (c) The discrete-time system's frequency response $H(e^{j\hat{\omega}})$ becomes the effective analog frequency response by using the change of variable $\hat{\omega} = \omega/f_s = \omega/200$. Thus we can use the frequency response plot of $H(e^{j\hat{\omega}})$ if we relabel the frequency axis.



The plot of $Y(j\omega)$, the Fourier transform of the output $y(t)$, will be identical to $X(j\omega)$ because the passband of the ideal LPF includes the frequency $\omega = 50\pi$ rad/s.

- (d) If the input signal is going to pass through the lowpass filter unaltered, then the highest frequency $\omega = 50\pi$ rad/s must map to $\hat{\omega}$ that is less than or equal to $\hat{\omega} = \pi/2$ because $\pi/2$ is the edge of the passband of the LPF. In other words, we can write

$$\hat{\omega} = \omega/f_s \quad \Rightarrow \quad \frac{\pi}{2} = \frac{50\pi}{f_s} \quad \Rightarrow \quad f_s = 100 \text{ Hz}$$