

## Lecture 14 Z Transforms: Introduction 10-Oct-03

## Info: Web-CT, Lab, HW

- NO Lab next week (13—16 Oct)
- **ATTEND a RECITATION** on Wed or Thurs
- Prob Set #7 due **NEXT WEEK in Recitation**
  - Last Recitation is 4:30 pm on Thursday
- Quiz #2 on 24-Oct (Friday)
  - Coverage: HW **#5, #6, #7**, and #8
  - One page of **Hand-written** notes
  - Review Session: ECE Aud, Wed (22-Oct ??)
- Lab #7 will be due **WEEK of 21-Oct**

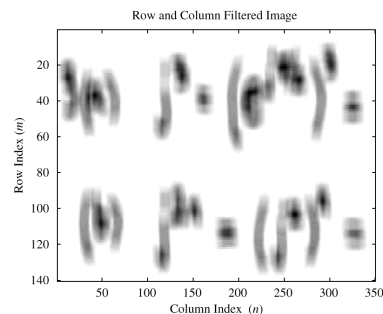
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## FILTER TYPES

- LOW-PASS FILTER (**LPF**)
  - BLURRING
  - ATTENUATES HIGH FREQUENCIES
- HIGH-PASS FILTER (**HPF**)
  - SHARPENING for IMAGES
  - BOOSTS THE HIGHS
  - REMOVES DC
- BAND-PASS FILTER (**BPF**)



## Superficial Knowledge

- It depends how carefully you think about it. If you don't think very carefully it's obvious; but if you think about it in depth, you'll get confused and it won't be obvious.

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Lecture

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## READING ASSIGNMENTS

- This Lecture:
  - Chapter 7, Sects 7-1 through 7-5
- Other Reading:
  - Recitation: Ch. 7
    - CASCADING SYSTEMS
  - Next Lecture: Chapter 7, 7-6 to the end

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## LECTURE OBJECTIVES

- INTRODUCE the Z-TRANSFORM
  - Give Mathematical Definition
  - Show how the  $H(z)$  POLYNOMIAL simplifies analysis
    - **CONVOLUTION** is SIMPLIFIED !
- Z-Transform can be applied to
  - FIR Filter:  $h[n] \rightarrow H(z)$
  - Signals:  $x[n] \rightarrow X(z)$

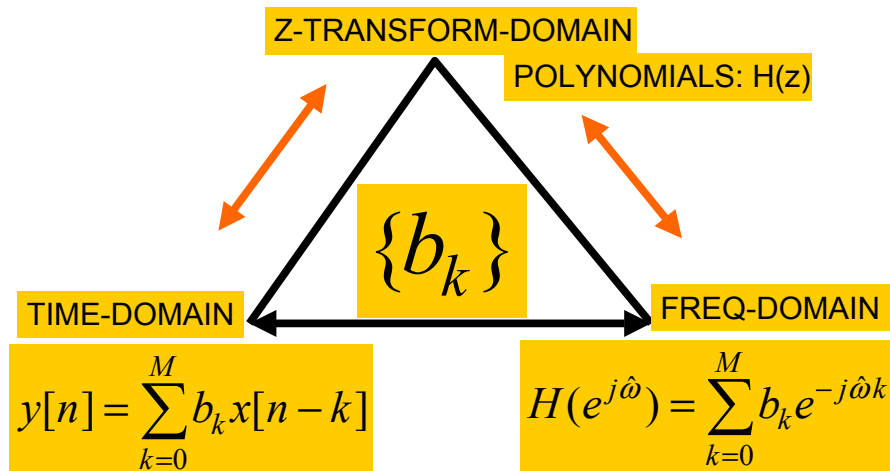
$$H(z) = \sum_n h[n]z^{-n}$$

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## TWO (no, THREE) DOMAINS



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## TRANSFORM CONCEPT

- Move to a new domain where
  - OPERATIONS are EASIER & FAMILIAR
  - Use POLYNOMIALS
- TRANSFORM both ways
  - $x[n] \rightarrow X(z)$  (into the z domain)
  - $X(z) \rightarrow x[n]$  (back to the time domain)

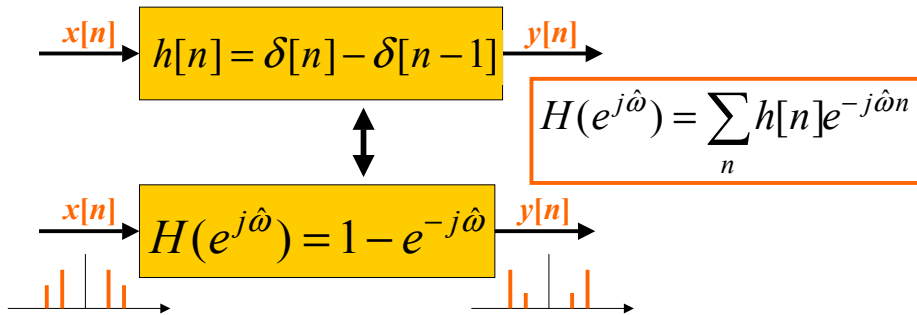
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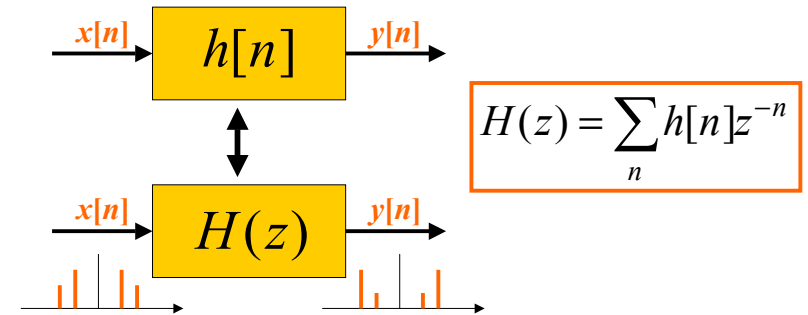
# “TRANSFORM” EXAMPLE

- Equivalent Representations



# Z-TRANSFORM IDEA

- POLYNOMIAL REPRESENTATION



# Z-Transform DEFINITION

- POLYNOMIAL Representation of LTI SYSTEM:

$$H(z) = \sum_n h[n]z^{-n}$$

- EXAMPLE:

$$\{h[n]\} = \{2, 0, -3, 0, 2\}$$

$$H(z) = 2z^{-0} + 0z^{-1} - 3z^{-2} + 0z^{-3} + 2z^{-4}$$

$$= 2 - 3z^{-2} + 2z^{-4}$$

$$= 2 - 3(z^{-1})^2 + 2(z^{-1})^4$$

APPLIES to Any SIGNAL

POLYNOMIAL in  $z^{-1}$

# Z-Transform EXAMPLE

- ANY SIGNAL has a z-Transform:

$$X(z) = \sum_n x[n]z^{-n}$$

## Example 7.1

$n$	$n < -1$	-1	0	1	2	3	4	5	$n > 5$
$x[n]$	0	0	2	4	6	4	2	0	0

$$X(z) = ? \quad X(z) = 2 + 4z^{-1} + 6z^{-2} + 4z^{-3} + 2z^{-4}$$

### Example 7.2

$$X(z) = 1 - 2z^{-1} + 3z^{-3} - z^{-5}$$

EXPONENT GIVES TIME LOCATION

$$x[n] = \begin{cases} 0 & n < 0 \\ 1 & n = 0 \\ -2 & n = 1 \\ 0 & n = 2 \\ 3 & n = 3 \\ 0 & n = 4 \\ -1 & n = 5 \\ 0 & n > 5 \end{cases}$$

$$x[n] = ?$$

$$x[n] = \delta[n] - 2\delta[n-1] + 3\delta[n-3] - \delta[n-5]$$

## Z-Transform of FIR Filter

- CALLLED the **SYSTEM FUNCTION**

- h[n] is same as {b<sub>k</sub>}

SYSTEM FUNCTION

$$H(z) = \sum_{k=0}^M b_k z^{-k} = \sum_{k=0}^M h[k] z^{-k}$$

$$y[n] = \sum_{k=0}^M b_k x[n-k] = \sum_{k=0}^M h[k] x[n-k]$$

FIR DIFFERENCE EQUATION

CONVOLUTION

## Z-Transform of FIR Filter

- Get H(z) DIRECTLY from the {b<sub>k</sub>}
- Example 7.3 in the book:

$$y[n] = 6x[n] - 5x[n-1] + x[n-2]$$

$$\{b_k\} = \{6, -5, 1\}$$

$$H(z) = \sum b_k z^{-k} = 6 - 5z^{-1} + z^{-2}$$

## Ex. DELAY SYSTEM

- UNIT DELAY: find h[n] and H(z)

$$x[n] \rightarrow \delta[n-1] \rightarrow y[n] = x[n-1]$$

$$H(z) = \sum \delta[n-1] z^{-n} = z^{-1}$$

$$x[n] \rightarrow z^{-1} \rightarrow y[n]$$

## DELAY EXAMPLE

- UNIT DELAY: find  $y[n]$  via polynomials
  - $x[n] = \{3, 1, 4, 1, 5, 9, 0, 0, 0, \dots\}$

$$Y(z) = z^{-1}X(z)$$

$$Y(z) = z^{-1}(3 + z^{-1} + 4z^{-2} + z^{-3} + 5z^{-4} + 9z^{-5})$$

$$Y(z) = 0z^0 + 3z^{-1} + z^{-2} + 4z^{-3} + z^{-4} + 5z^{-5} + 9z^{-6}$$

$n$	$n < 0$	0	1	2	3	4	5	6	$n > 6$
$y[n]$	0	0	3	1	4	1	5	9	0

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## DELAY PROPERTY

*A delay of one sample multiplies the  $z$ -transform by  $z^{-1}$ .*

$$x[n - 1] \iff z^{-1}X(z)$$

*Time delay of  $n_0$  samples multiplies the  $z$ -transform by  $z^{-n_0}$*

$$x[n - n_0] \iff z^{-n_0}X(z)$$

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## GENERAL I/O PROBLEM

- Input is  $x[n]$ , find  $y[n]$  (for FIR,  $h[n]$ )
- How to combine  $X(z)$  and  $H(z)$  ?

### Example 7.5

$$x[n] = \delta[n - 1] - \delta[n - 2] + \delta[n - 3] - \delta[n - 4]$$

$$\text{and } h[n] = \delta[n] + 2\delta[n - 1] + 3\delta[n - 2] + 4\delta[n - 3]$$

$$X(z) = 0 + 1z^{-1} - 1z^{-2} + 1z^{-3} - 1z^{-4}$$

$$\text{and } H(z) = 1 + 2z^{-1} + 3z^{-2} + 4z^{-3}$$

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## FIR Filter = CONVOLUTION

$x[n], X(z)$	0	+1	-1	+1	-1			
$h[n], H(z)$	1	2	3	4				
	0	+1	-1	+1	-1			
		0	+2	-2	+2	-2		
			0	+3	-3	+3	-3	
				0	+4	-4	+4	-4
$y[n], Y(z)$	0	+1	+1	+2	+2	-3	+1	-4

$$y[n] = \sum_{k=0}^M b_k x[n - k] = \sum_{k=0}^M h[k] x[n - k]$$

**CONVOLUTION**

# CONVOLUTION PROPERTY

- PROOF:

$$y[n] = x[n] * h[n] = \sum_{k=0}^M h[k]x[n - k]$$

$$Y(z) = \sum_{k=0}^M h[k] (z^{-k} X(z))$$

**MULTIPLY Z-TRANSFORMS**

$$= \left( \sum_{k=0}^M h[k]z^{-k} \right) X(z) = H(z)X(z).$$

# CONVOLUTION EXAMPLE

- MULTIPLY** the z-TRANSFORMS:

Example 7.5

$$x[n] = \delta[n - 1] - \delta[n - 2] + \delta[n - 3] - \delta[n - 4]$$

and  $h[n] = \delta[n] + 2\delta[n - 1] + 3\delta[n - 2] + 4\delta[n - 3]$

$$X(z) = 0 + 1z^{-1} - 1z^{-2} + 1z^{-3} - 1z^{-4}$$

and  $H(z) = 1 + 2z^{-1} + 3z^{-2} + 4z^{-3}$

**MULTIPLY  $H(z)X(z)$**

# CONVOLUTION EXAMPLE

- Finite-Length input  $x[n]$
- FIR Filter ( $L=4$ )

**MULTIPLY Z-TRANSFORMS**

$$Y(z) = H(z)X(z)$$

$$= (1 + 2z^{-1} + 3z^{-2} + 4z^{-3})(z^{-1} - z^{-2} + z^{-3} - z^{-4})$$

$$= z^{-1} + (-1 + 2)z^{-2} + (1 - 2 + 3)z^{-3} + (-1 + 2 - 3 + 4)z^{-4}$$

$$+ (-2 + 3 - 4)z^{-5} + (-3 + 4)z^{-6} + (-4)z^{-7}$$

$$= z^{-1} + z^{-2} + 2z^{-3} + 2z^{-4} - 3z^{-5} + z^{-6} - 4z^{-7}$$

**$y[n] = ?$**

# CASCADE SYSTEMS

- Does the order of  $S_1$  &  $S_2$  matter?
  - NO, **LTI SYSTEMS can be rearranged !!!**
  - Remember:  $h_1[n] * h_2[n]$
  - How to combine  $H_1(z)$  and  $H_2(z)$  ?

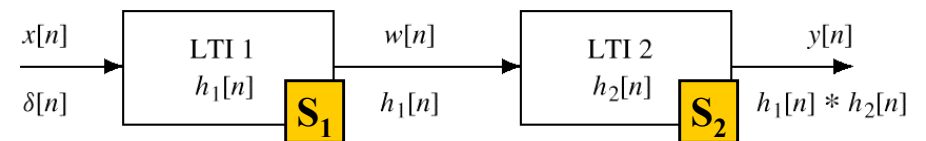
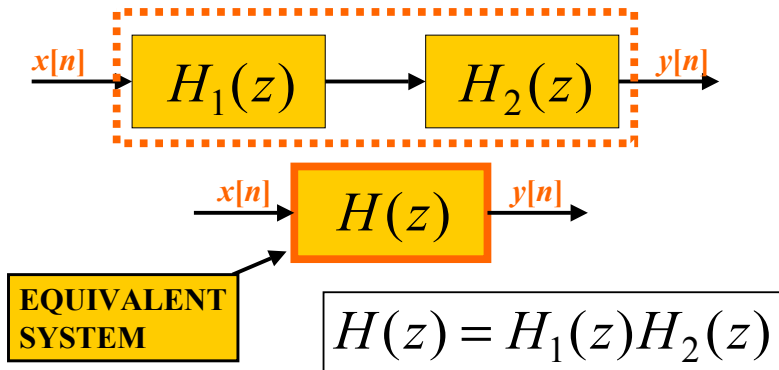


Figure 5.19 A Cascade of Two LTI Systems.

## CASCADE EQUIVALENT

- Multiply the System Functions



## CASCADE EXAMPLE

