

HW #12, Solutions

problem 12.1

$$\begin{aligned}
 (a) & \left[\pi e^{-10t} \cos(10\pi t) u(t) + u(t-0.09) \right] \delta(t-0.03) \\
 &= \left[\pi e^{-10(0.03)} \cos(10\pi(0.03)) u(0.03) + u(0.03-0.09) \right] \delta(t-0.03) \\
 &= \left[\pi e^{-0.3} \cos(0.3\pi) \right] \delta(t-0.03)
 \end{aligned}$$

$$\begin{aligned}
 (b) & \left[3\delta(t+2) - 7\delta(t) \right] * \left[\delta(t+2) + \delta(t-2) \right] \\
 &= 3\delta(t+4) + 3\delta(t) - 7\delta(t+2) - 7\delta(t-2)
 \end{aligned}$$

$$\begin{aligned}
 (c) & \frac{d}{dt} \left[e^{(t-3)} \cos(10\pi(t-3)) u(t-3) \right] \\
 &= e^{(t-3)} \cos(10\pi(t-3)) u(t-3) - e^{(t-3)} 10\pi \sin(10\pi(t-3)) u(t-3) \\
 &\quad + e^{(t-3)} \cos(10\pi(t-3)) \delta(t-3) \\
 &= e^{(t-3)} \left[\cos(10\pi(t-3)) - 10\pi \sin(10\pi(t-3)) \right] u(t-3) \\
 &\quad + \delta(t-3)
 \end{aligned}$$

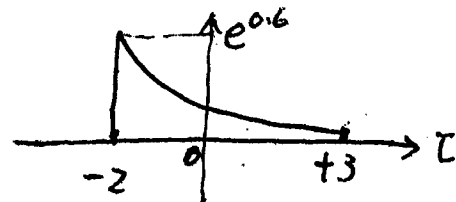
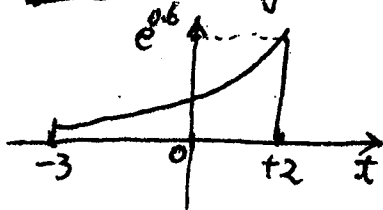
$$\begin{aligned}
 (d) & \int_{-\infty}^{t-0.1} \delta(\tau+0.2) \cos(4\pi\tau) u(\tau) d\tau \\
 &= \int_{-\infty}^{t-0.1} \cos(4\pi(\tau-0.2)) \delta(\tau+0.2) u(\tau-0.2) d\tau \\
 &= \cos(-0.8\pi) \int_{-\infty}^{t-0.1} \delta(\tau+0.2) d\tau \\
 &= \cos(0.8\pi) u(\tau+0.2) \Big|_{-\infty}^{t-0.1} \\
 &= \cos(0.8\pi) u(t-0.1+0.2) \\
 &= \cos(0.8\pi) u(t+0.1)
 \end{aligned}$$

problem 12.3

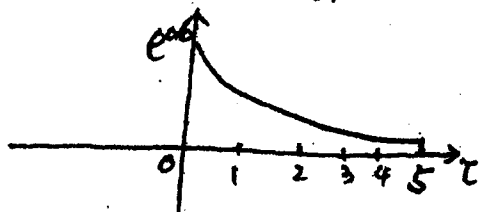
$$h(t) = e^{0.3t} [u(t+3) - u(t-2)] = \begin{cases} e^{0.3t} & -3 \leq t < 2 \\ 0 & \text{otherwise} \end{cases}$$

(a) plot $h(t-\tau)$ for $t=0, 2, 4$

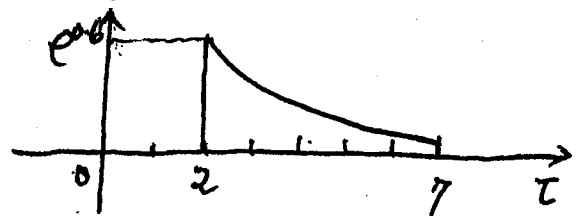
first the original $h(t)$, $h(t-\tau) = h(-\tau)$, when $t=0$



$h(t-\tau) = h(2-\tau)$, when $t=2$



$h(t-\tau) = h(4-\tau)$, $t=4$



(b) $y(t) = \delta(t-1) * e^{0.3t} [u(t+3) - u(t-2)]$
 $= e^{0.3(t-1)} [u(t+2) - u(t-3)]$

(c) $x(t) = e^{-0.2t} [u(t) - u(t-6)] = \begin{cases} e^{-0.2t} & 0 \leq t < 6 \\ 0 & \text{otherwise} \end{cases}$
 $y(t) = \int_a^b e^{0.3\tau} e^{-0.2(t-\tau)} d\tau$
 $= e^{-0.2t} \int_a^b e^{0.5\tau} d\tau = e^{-0.2t} \frac{(e^{0.5b} - e^{0.5a})}{0.5}$

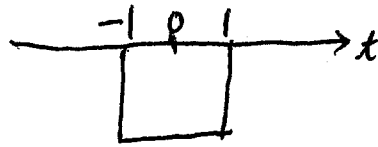
$$y(t) = \begin{cases} 0 & \text{for } t < -3 \\ e^{-0.2t} \int_{-3}^t e^{\tau/2} d\tau = 2e^{-0.2t} (e^{0.5t} - e^{-1.5}) & \text{for } -3 \leq t < 2 \\ e^{-0.2t} \int_{-3}^2 e^{\tau/2} d\tau = 2e^{-0.2t} (e - e^{-1.5}) & \text{for } 2 \leq t < 3 \\ e^{-0.2t} \int_{t-6}^2 e^{\tau/2} d\tau = 2e^{-0.2t} (e - e^{0.5t-3}) & \text{for } 3 \leq t < 8 \\ 0 & \text{for } 8 \leq t \end{cases}$$

problem 12.4

a linear time-invariant system, $h(t) = u(t-1) - u(t+1)$

(a) plot $h(t-\tau)$ vs. τ , for $t = -3$ and $t = 2$, Label the plot

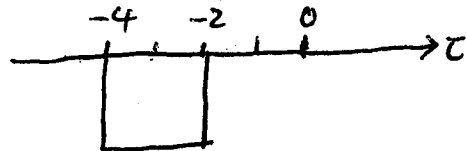
$$h(t) = u(t-1) - u(t+1)$$



$$h(t-\tau) \text{ for } t = -3$$

$$= h(-3-\tau) = u(-3-\tau-1) - u(-3-\tau+1)$$

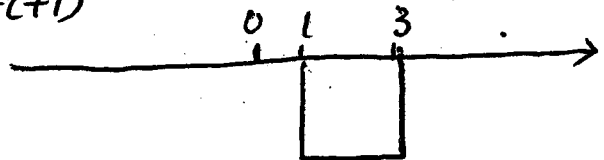
$$= u(-4-\tau) - u(-2-\tau)$$



$$h(t-\tau) \text{ for } t = 2$$

$$= h(2-\tau) = u(2-\tau-1) - u(2-\tau+1)$$

$$= u(1-\tau) - u(3-\tau)$$



(b) no, the system is not causal. Because $h(t) \neq 0$, when $t < 0$

(c) The system is stable. Because $\int_{-\infty}^{\infty} |h(t)| dt$ is finite

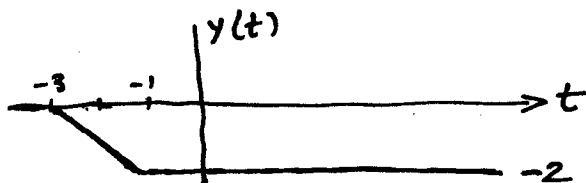
$$(d) x(t) = u(t+2)$$

$$y(t) = u(t+2) * (u(t-1) - u(t+1))$$

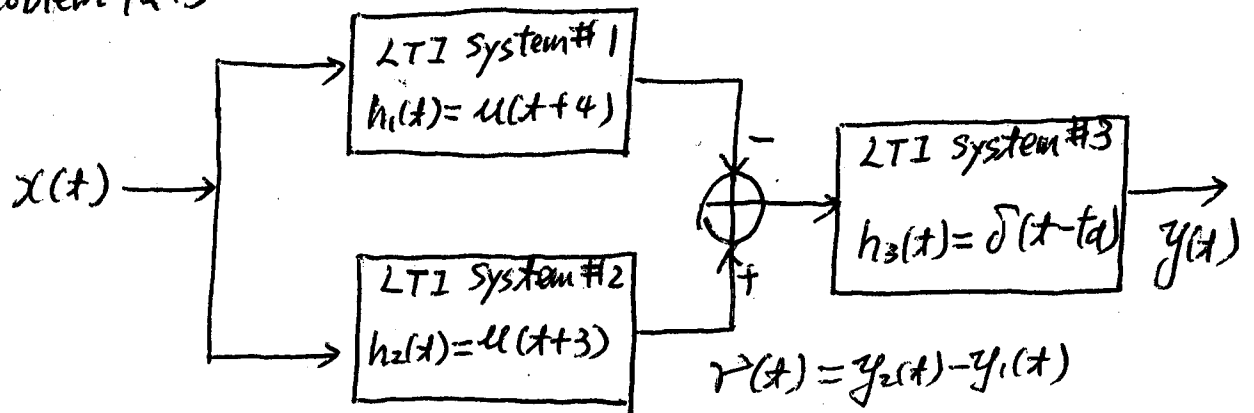
$$= u(t+2) * u(t-1) - u(t+2) * u(t+1)$$

$$= (t+1)u(t+1) - (t+3)u(t+3)$$

$$= \begin{cases} 0 & \text{for } t \leq t_1 = -3 \\ -(t+3) & \text{for } t_1 < t < t_2 = -1 \\ -2 & \text{for } t_2 \leq t \end{cases}$$



problem 12.5

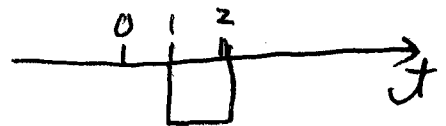


(a) If $t_d = 5$, what is the overall impulse response of the LTI system

$$h(t) = [-h_1(t) + h_2(t)] * h_3(t)$$

$$= [-u(t+4) + u(t+3)] * \delta(t-5) \quad h(t) \text{ plot}$$

$$= -u(t-1) + u(t-2)$$



(b) $t_d \geq 4$, so that $h(t) = 0$ when $t < 0$

(c) - systems #1 and #2 are unstable because

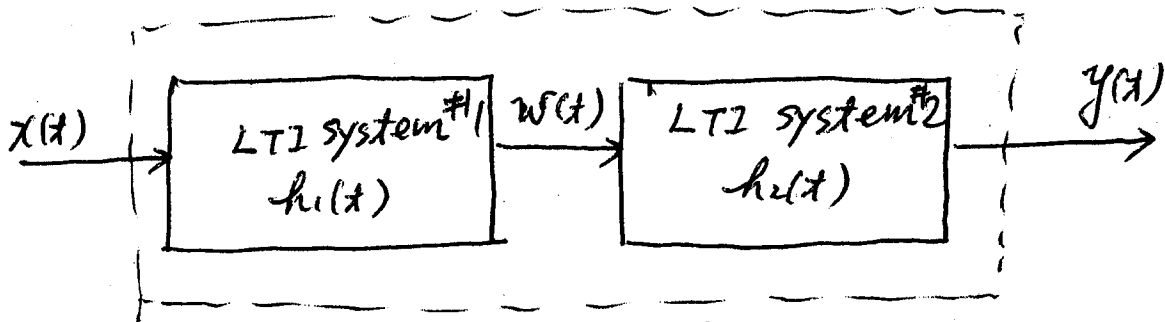
$\int_{-\infty}^{\infty} |h_i(t-\tau)| d\tau$ is proportional to t

when $t \rightarrow \infty$ the integral value is approaching infinite

(d) - system #3 is stable because the value is finite and non-zero at $t = t_d$

- the overall system is stable because the non-zero value existed for finite period of time.

problem 12.6



$$h_1(t) = \delta(t) - e^{-3t} u(t)$$

the second system has

$$y(t) = \int_{-\infty}^{\infty} e^{-2\tau} u(\tau) w(t-2-\tau) d\tau$$

(a) Find the impulse response of the second system

$$h_2(t) = e^{-2(t-2)} u(t-2)$$

proof: $y(t) = \int_{-\infty}^{\infty} e^{-2(\tau'-2)} u(\tau'-2) w(t-\tau') d\tau'$

set $\tau = \tau' - 2 \rightarrow d\tau = d\tau'$ and $\tau' = \tau + 2$

$$y(t) = \int_{-\infty}^{\infty} e^{-2\tau} u(\tau) w(t-2-\tau) d\tau$$

(b)

$$y(t) = [\delta(t) - e^{-3t} u(t)] * [e^{-2(t-2)} u(t-2)]$$

$$= e^{-2(t-2)} u(t-2) - \int_0^2 e^{-3\tau} e^{-2(t-2-\tau)} d\tau$$

$$= e^{-2(t-2)} u(t-2) - \int_0^2 e^{-\tau} e^{-2(t-2)} d\tau$$

$$= e^{-2(t-2)} u(t-2) - e^{-2(t-2)} \left. \frac{e^{-\tau}}{-1} \right|_0^2$$

$$= e^{-2(t-2)} u(t-2) + (e^{-2} - 1) e^{-2(t-2)}$$

$$= e^{-2(t-2)} u(t-2) + (e^{-2} - 1) e^{-2(2-t)}$$