

Lecture 16

IIR Filters: $H(z)$, Feedback,
and Frequency Response

19-Oct-09

Lab & HW Info

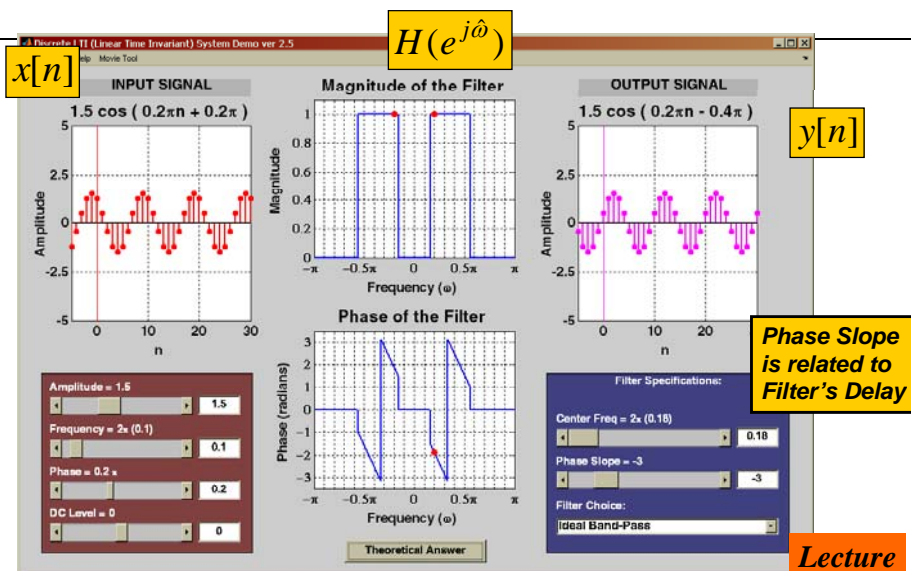
- Quiz #2 on 23-Oct (Friday)
 - One Page HAND-WRITTEN notes; Calculator OK
 - Take test with your assigned lecture section
 - Coverage: HW #4, #5, #6, #7 and #8
 - Chapters 3(FourierSeries), 4(Sampling), 5(FIR Filters) and 6(Frequency Response)
- Quiz Review: Thurs @6pm, Klaus 2456
- Lab #8 starts 20-Oct
 - Frequency Response of your hearing
- HW #8 due this week
 - Frequency Response will be covered on Quiz #2

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DLTIDEMO: Ideal Filters (Lab)



READING ASSIGNMENTS

- This Lecture:
 - Chapter 8, Sects. 8-4 8-5 & 8-6
- Other Reading:
 - Recitation: Chapter 8, all
 - POLE-ZERO PLOTS

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LECTURE OBJECTIVES

- IIR: Infinite-Length Impulse Response
- SYSTEM FUNCTION: $H(z)$
- FEEDBACK Difference Equations
- FREQUENCY RESPONSE of IIR

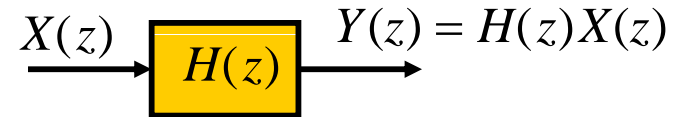
$$H(e^{j\hat{\omega}}) = H(z) \Big|_{z=e^{j\hat{\omega}}}$$

- THREE-DOMAIN APPROACH

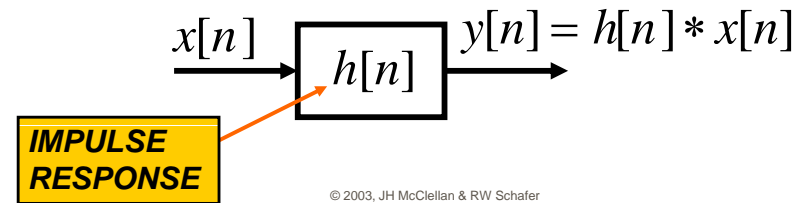
$$h[n] \leftrightarrow H(z) \leftrightarrow H(e^{j\hat{\omega}})$$

Recall: CONVOLUTION PROPERTY

- **MULTIPLICATION** of z-TRANSFORMS

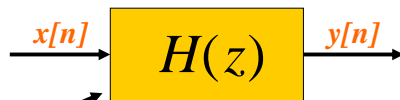
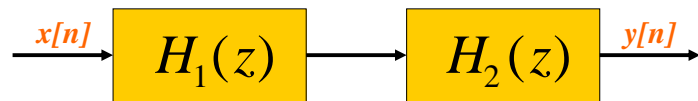


- **CONVOLUTION** in TIME-DOMAIN



Recall: CASCADE EQUIVALENT

- Multiply the System Functions



EQUIVALENT SYSTEM

$$H(z) = H_1(z)H_2(z)$$

Motivation: De-Convolution

- Can you make $y[n]$ equal to $s[n]$?

- $Y(z) = H(z)S(z)$



$$H(z) = 1 = H_1(z)H_2(z)$$

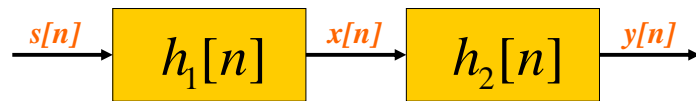
$$\Rightarrow H_2(z) = 1/H_1(z)$$

$$H_1(z) = 1 - az^{-1}$$

$$\Rightarrow H_2(z) = \frac{1}{1 - az^{-1}}$$

WHY DE-convolution ?

- Given $h_2[n]$, we must solve for $h_1[n]$ in a convolution equation:



$$\begin{aligned} x[n] &= s[n] * h_1[n] \\ y[n] &= x[n] * h_2[n] = s[n] * h_1[n] * h_2[n] \\ \Rightarrow h_1[n] * h_2[n] &= \delta[n] \end{aligned}$$

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First-Order Transform Pair

$$h[n] = b_0 (a_1)^n u[n] \leftrightarrow H(z) = \frac{b_0}{1 - a_1 z^{-1}}$$

- Proof: use GEOMETRIC SEQUENCE:

$$\begin{aligned} H(z) &= b_0 \sum_{n=0}^{\infty} a_1^n z^{-n} = b_0 \sum_{n=0}^{\infty} (a_1 z^{-1})^n \\ &= \frac{b_0}{1 - a_1 z^{-1}} \quad \text{if } |z| > |a_1| \end{aligned}$$

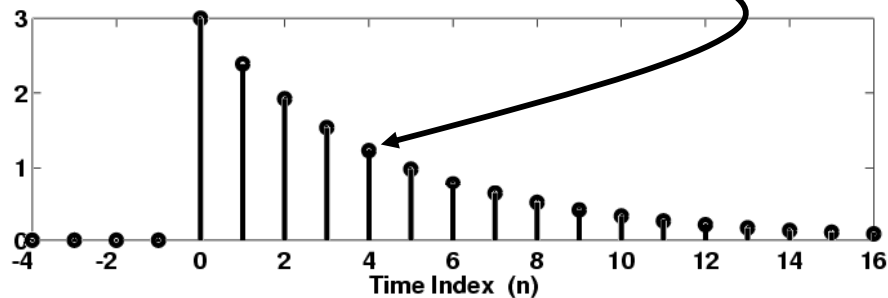
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Typical IMPULSE Response

$$h[n] = b_0 (a_1)^n u[n] = 3(0.8)^n u[n]$$

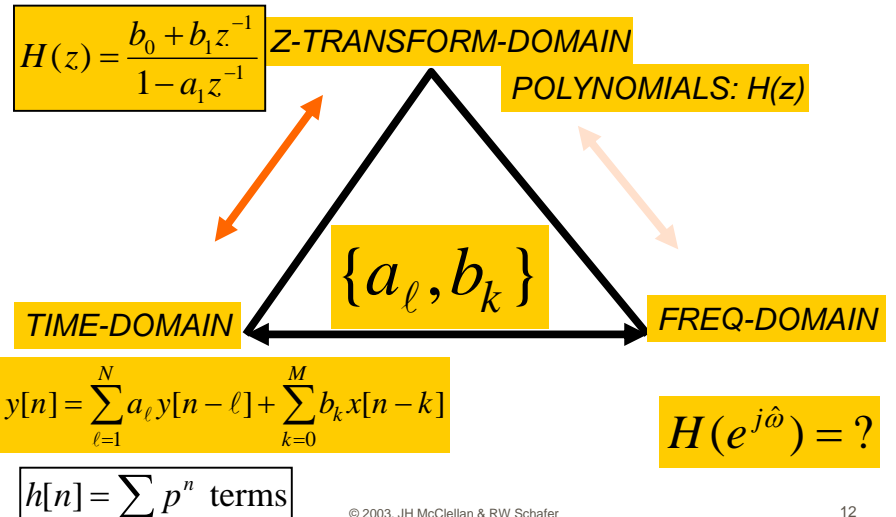


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THREE DOMAINS



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H(z) → Difference Equation

- WHAT are the FILTER COEFFICIENTS ?

$$H(z) = \frac{Y(z)}{X(z)} = \frac{b_0 + b_1 z^{-1}}{1 - a_1 z^{-1}} = \frac{B(z)}{A(z)}$$

$$(1 - a_1 z^{-1})Y(z) = (b_0 + b_1 z^{-1})X(z)$$

$$Y(z) - a_1 z^{-1}Y(z) = b_0 X(z) + b_1 z^{-1}X(z)$$

Recall: DELAY PROPERTY of X(z)

- DELAY in TIME ↔ Multiply X(z) by z^{-1}

$$x[n] \leftrightarrow X(z)$$

$$x[n-1] \leftrightarrow z^{-1}X(z)$$

Proof:

$$\sum_{n=-\infty}^{\infty} x[n-1]z^{-n} = \sum_{\ell=-\infty}^{\infty} x[\ell]z^{-(\ell+1)}$$

$$= z^{-1} \sum_{\ell=-\infty}^{\infty} x[\ell]z^{-\ell} = z^{-1}X(z)$$

H(z) → Difference Equation

- DERIVE the Filter Coefficients from H(z)
 - Use **DELAY PROPERTY**

$$Y(z) = a_1 z^{-1}Y(z) + b_0 X(z) + b_1 z^{-1}X(z)$$

$$y[n] = a_1 y[n-1] + b_0 x[n] + b_1 x[n-1]$$

EASIER with DELAY PROPERTY

Time delay of n_0 samples multiplies the z-transform by z^{-n_0}

$$x[n - n_0] \iff z^{-n_0}X(z)$$

H(z) = z-Transform{ h[n] }

- Summarize FIRST-ORDER IIR Filter:

$$y[n] = a_1 y[n-1] + b_0 x[n] + b_1 x[n-1]$$

$$h[n] = b_0 (a_1)^n u[n] + b_1 (a_1)^{n-1} u[n-1]$$

$$H(z) = \frac{b_0 + b_1 z^{-1}}{1 - a_1 z^{-1}} = \frac{b_0}{1 - a_1 z^{-1}} + z^{-1} \frac{b_1}{1 - a_1 z^{-1}}$$

SYSTEM FUNCTION

- DIFFERENCE EQUATION:

$$y[n] = 0.8y[n-1] + 3x[n] - 2x[n-1]$$

- READ** the FILTER COEFFS:

$H(z)$

$$Y(z) = \left(\frac{3 - 2z^{-1}}{1 - 0.8z^{-1}} \right) X(z)$$

ONE FEEDBACK TERM

- ADD **PREVIOUS** OUTPUTS

$$y[n] = a_1y[n-1] + b_0x[n] + b_1x[n-1]$$

PREVIOUS
FEEDBACK

FIR PART of the FILTER

FEED-FORWARD

- CAUSALITY

- NOT USING **FUTURE** OUTPUTS or INPUTS

FILTER COEFFICIENTS

- ADD **PREVIOUS** OUTPUTS

$$y[n] = 0.8y[n-1] + 3x[n] - 2x[n-1]$$

FEEDBACK COEFFICIENT

SIGN CHANGE

- MATLAB

`yy = filter([3,-2],[1,-0.8],xx)`

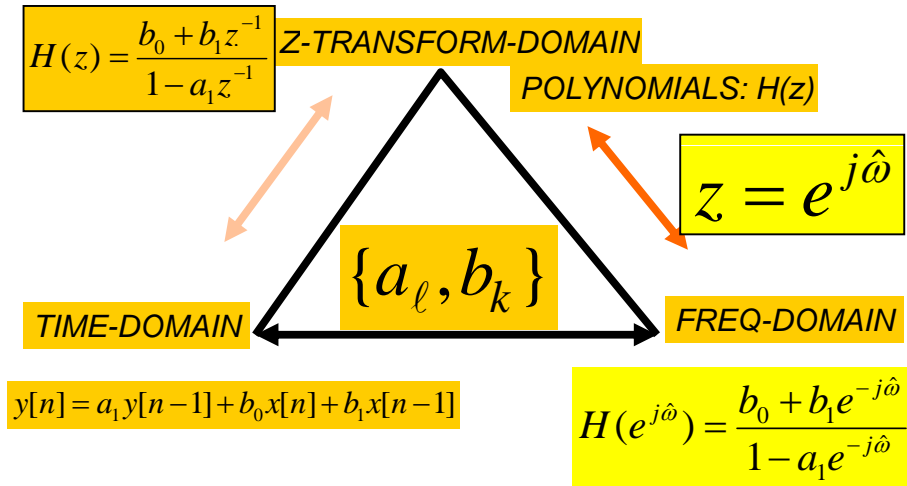
LTI? AT REST CONDITION

- $y[n] = 0$, for $n < 0$
- When $x[n] = 0$, for $n < 0$

INITIAL REST CONDITIONS

- The input must be assumed to be zero prior to some starting time n_0 , i.e., $x[n] = 0$ for $n < n_0$. We say that such inputs are *suddenly applied*.
- The output is likewise assumed to be zero prior to the starting time of the signal, i.e., $y[n] = 0$ for $n < n_0$. We say that the system is *initially at rest* if its output is zero prior to the application of a suddenly applied input.

THREE DOMAINS: $H(e^{j\hat{\omega}})$



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FREQUENCY RESPONSE

- EVALUATE on the UNIT CIRCLE

$$H(e^{j\hat{\omega}}) = H(z)|_{z=e^{j\hat{\omega}}}$$

$$H(z) = \frac{b_0 + b_1z^{-1}}{1 - a_1z^{-1}}$$

$$H(e^{j\hat{\omega}}) = H(z)|_{z=e^{j\hat{\omega}}} = \frac{b_0 + b_1e^{-j\hat{\omega}}}{1 - a_1e^{-j\hat{\omega}}}$$

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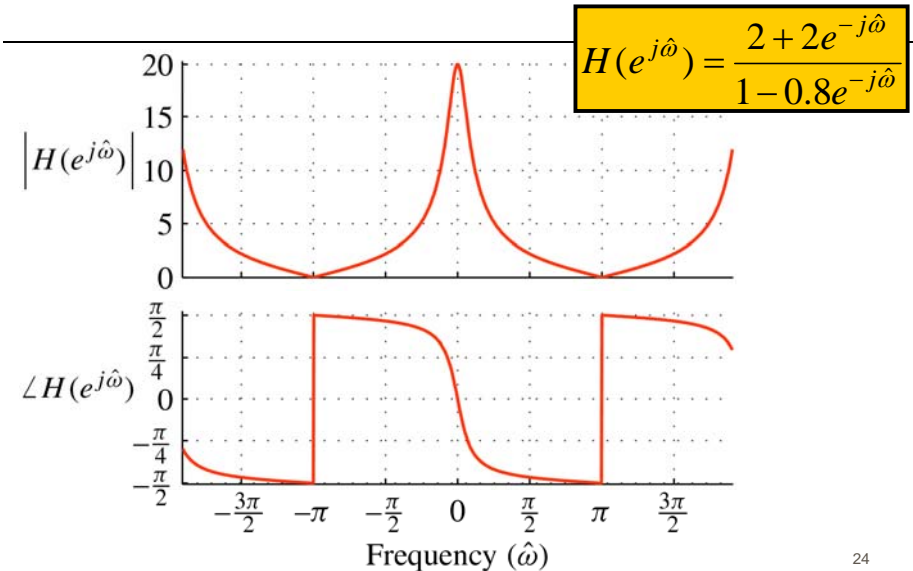
FREQ. RESPONSE FORMULA

$$H(z) = \frac{2 + 2z^{-1}}{1 - 0.8z^{-1}} \rightarrow H(e^{j\hat{\omega}}) = \frac{2 + 2e^{-j\hat{\omega}}}{1 - 0.8e^{-j\hat{\omega}}}$$

$$\text{@ } \hat{\omega} = 0, \quad |H(e^{j\hat{\omega}})| = \frac{2 + 2}{1 - 0.8} = 20$$

$$\text{@ } \hat{\omega} = \pi, \quad |H(e^{j\hat{\omega}})| = \frac{2 + 2(-1)}{1 + 0.8} = 0$$

Frequency Response Plot



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SINUSOIDAL RESPONSE

- $x[n] = \text{SINUSOID} \Rightarrow y[n]$ is SINUSOID
- Get MAGNITUDE & PHASE from $H(z)$

if $x[n] = e^{j\hat{\omega}n}$
 then $y[n] = H(e^{j\hat{\omega}}) e^{j\hat{\omega}n}$
 where $H(e^{j\hat{\omega}}) = H(z) \Big|_{z=e^{j\hat{\omega}}}$

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POP QUIZ

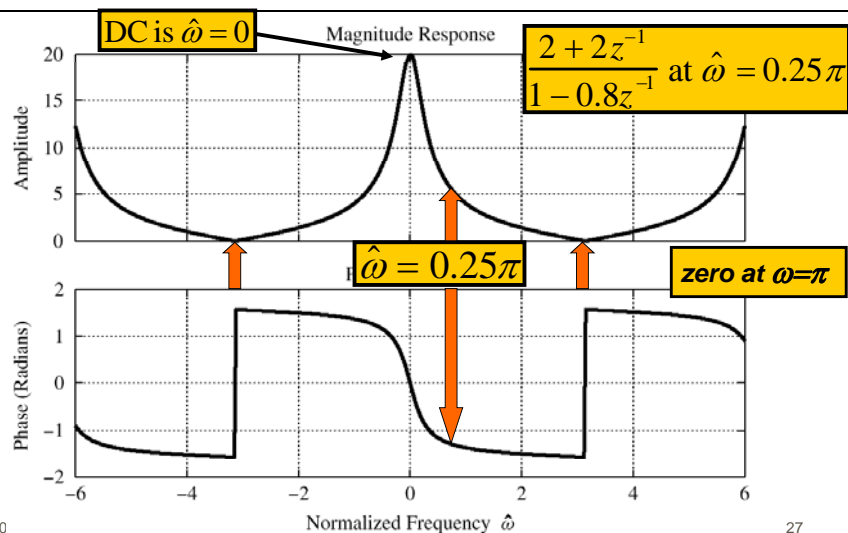
- Given: $H(z) = \frac{2 + 2z^{-1}}{1 - 0.8z^{-1}}$
- Find the Impulse Response, $h[n]$
- Find the output, $y[n]$
 - When $x[n] = \cos(0.25\pi n)$

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Evaluate FREQ. RESPONSE



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POP QUIZ: Eval Freq. Resp.

- Given: $H(z) = \frac{2 + 2z^{-1}}{1 - 0.8z^{-1}}$
- Find output, $y[n]$, when $x[n] = \cos(0.25\pi n)$
 - Evaluate at $z = e^{j0.25\pi}$

$$H(z) = \frac{2 + 2(\frac{\sqrt{2}}{2} - j\frac{\sqrt{2}}{2})}{1 - 0.8e^{-j0.25\pi}} = 5.182e^{-j1.309}$$

$$y[n] = 5.182 \cos(0.25\pi n - 0.417\pi)$$