

**GEORGIA INSTITUTE OF TECHNOLOGY**  
 SCHOOL of ELECTRICAL & COMPUTER ENGINEERING  
**QUIZ #3**

DATE: 21-Nov-11

COURSE: ECE-2025

NAME:

LAST,

FIRST

GT username:

(ex: gpburdell3)

3 points

3 points

3 points

Recitation Section: Circle the date & time when your **Recitation Section** meets (not Lab):

L05:Tues-9:30am (Richards)	L06:Thur-9:30am (Casinovi)		
L07:Tues-Noon (Richards)	L08:Thur-Noon (Casinovi)		
L09:Tues-1:30pm (Chang)	L10:Thur-1:30pm (Coyle)		
L01:M-3pm (Barry)	L11:Tues-3pm (Chang)	L02:W-3pm (Clements)	L12:Thur-3pm (Baxley)
L03:M-4:30pm (Barry)	L04:W-4:30pm (Clements)	L14:Thur-4:30pm (Baxley)	

- Write your name on the front page ONLY. **DO NOT** unstaple the test.
- Closed book, but a calculator is permitted.
- One page ( $8\frac{1}{2}'' \times 11''$ ) of **HAND-WRITTEN** notes permitted. OK to write on both sides.
- **JUSTIFY** your reasoning **CLEARLY** to receive partial credit.
- You must write your answer in the space provided on the exam paper itself. Only these answers will be graded. Circle your answers, or write them in the boxes provided. If more space is needed for scratch work, use the backs of previous pages.

<i>Problem</i>	<i>Value</i>	<i>Score</i>
1	25	
2	25	
3	25	
4	25	
No/Wrong Rec	-3	

**PROBLEM Fall-11-Q.3.1:**

We've seen several equivalent ways to describe an LTI system. Below are a list of time domain descriptions (e.g., impulse response, difference equation, MATLAB code or filter coefficients) of LTI systems. For each one, choose from the list on the right the corresponding system function or frequency response. Note that there are more entries on the right than you will need to fill in the blanks on the left.

**Time-Domain Description****System Function/Frequency Response**

(a)  $y[n] = \sum_{k=1}^3 (\sqrt{k-1})x[n-k]$

**ANS =**

**1**  $H(e^{j\hat{\omega}}) = 2 \cos(\hat{\omega}) e^{-j3\hat{\omega}}$

**2**  $H(z) = \frac{z^{-2}(1-z^{-1})}{1-0.8z^{-1}}$

(b)  $y[n] = 0.9y[n-1] + 0.8y[n-2] + x[n] - x[n-3]$

**ANS =**

**3**  $H(e^{j\hat{\omega}}) = \frac{1 - e^{-j3\hat{\omega}}}{1 - 0.9e^{-j\hat{\omega}} - 0.8e^{-j2\hat{\omega}}}$

**4**  $H(e^{j\hat{\omega}}) = (1 + 2 \cos(\hat{\omega}))e^{-j3\hat{\omega}}$

(c) `yy=filter([0,0,1,0,1],1,xx);`

**ANS =**

**5**  $H(e^{j\hat{\omega}}) = \frac{1 - e^{-j3\hat{\omega}}}{1 + 0.9e^{-j\hat{\omega}} + 0.8e^{-j2\hat{\omega}}}$

(d)  $h[n] = 0.8^{n-2}u[n-2] - 0.8^{n-3}u[n-3]$

**ANS =**

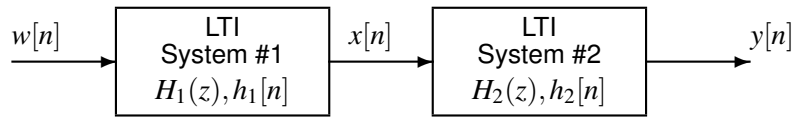
**6**  $H(z) = z^{-2}(1 + 0.707z^{-1})$

(e)  $h[n] = u[n-2] - u[n-5]$

**ANS =**

**PROBLEM Fall-11-Q.3.2:**

The diagram in the figure below depicts a *cascade connection* of two linear time-invariant systems, i.e., the output of the first system is the input to the second system, and the overall output is the output of the second system.



System #1 is the IIR filter described by the system function

$$H_1(z) = \frac{z^{-2}}{1 - 0.8z^{-1}},$$

and System #2 is the FIR filter described by the system function  $H_2(z) = z^{-3} - z^{-4}$ . Each part of this question can be worked independently.

- (a) Determine the poles and zeros of the first system  $H_1(z)$  and list them below. If there are no finite poles or zeros, write **NONE** in the corresponding space. If a pole or zero occurs multiple times, be sure to list it multiple times in your answer.

ZEROS at  $z =$

POLES at  $z =$

- (b) Determine the impulse response of the second system  $h_2[n]$ .

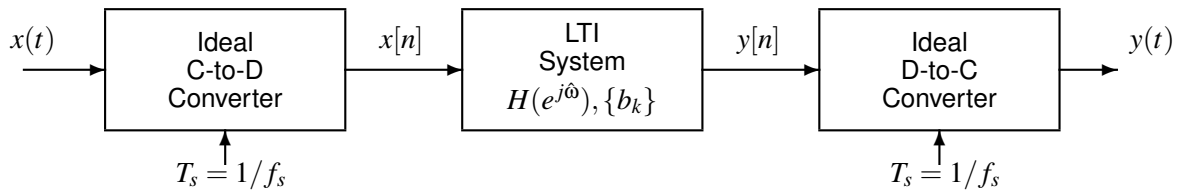
$h_2[n] =$

- (c) Determine the overall output  $y[n]$  when the input is a delayed unit step function  $w[n] = u[n - 2]$ .

$y[n] =$

**PROBLEM Fall-11-Q.3.3:**

Consider the following system for discrete-time filtering of continuous-time signals:



Both parts of this question should be worked independently.

- (a) For this part, assume that the LTI system in the figure is defined by the frequency response  $H(e^{j\hat{\omega}}) = \cos(\hat{\omega})e^{-j2\hat{\omega}}$ , and the sampling rate is  $f_s = 400$ . Determine the overall system output  $y(t)$  if the input is  $x(t) = 10 + \cos(2\pi 50t) + \cos(2\pi 500t + 3\pi/4)$ .

$y(t) =$

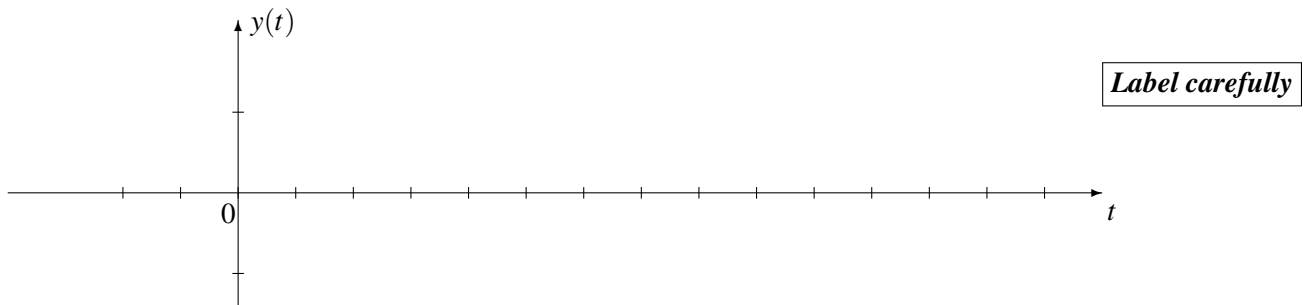
- (b) This part deals with the design of FIR nulling filters similar to the filters you designed in Lab 8. Given the following three conditions, determine the values of the FIR filter coefficients  $b_0, b_1$  and  $b_2$ . First, when the input to the FIR filter is  $x[n] = 15 \cos(3\pi n/4 + \pi/3)$  the output is  $y[n] = 0$ . Second, the filter coefficients should be scaled so that when the input is the DC signal  $x[n] = 10$  the output is  $y[n] = 30$ . Finally, assume that  $b_2 = b_0$ .

$b_0 =$	$b_1 =$	$b_2 =$
---------	---------	---------

**PROBLEM Fall-11-Q.3.4:**

The following two questions about continuous-time convolution should be worked independently.

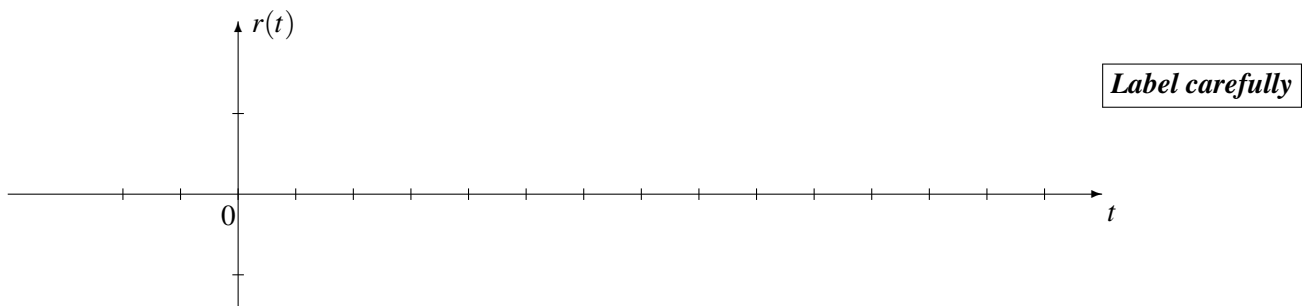
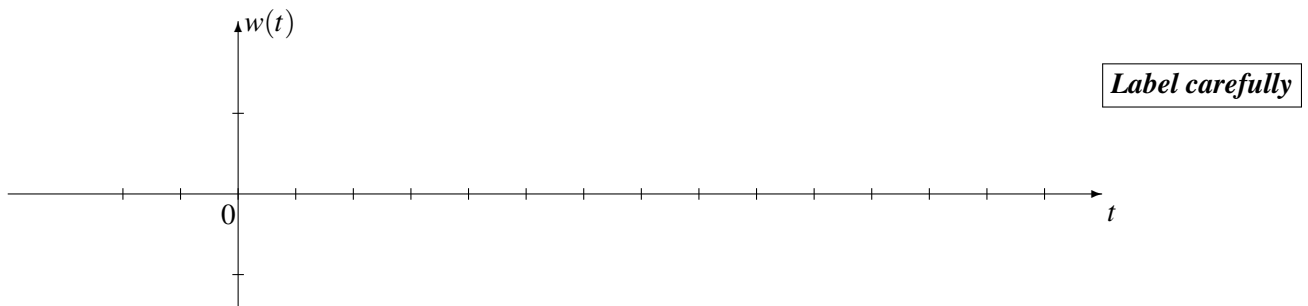
- (a) If the input to an LTI system is  $x(t) = u(t + 2) - u(t - 3)$ , determine the output signal  $y(t) = x(t) * h(t)$  when  $h(t) = 40\delta(t - 3) - 40\delta(t - 5)$ . Give your answer as a carefully labeled sketch showing numerical values on both the time and amplitude axes.



- (b) If the signal  $r(t)$  is a rectangular pulse, then  $w(t) = r(t) * r(t)$  is a triangle. Suppose that

$$w(t) = r(t) * r(t) = (4t)[u(t) - u(t - 4)] + (32 - 4t)[u(t - 4) - u(t - 8)].$$

On the axes below, give carefully labeled sketches of both  $w(t)$  and  $r(t)$ .





**PROBLEM Fall-11-Q.3.1:**

We've seen several equivalent ways to describe an LTI system. Below are a list of time domain descriptions (e.g., impulse response, difference equation, MATLAB code or filter coefficients) of LTI systems. For each one, choose from the list on the right the corresponding system function or frequency response. Note that there are more entries on the right than you will need to fill in the blanks on the left.

**Time-Domain Description****System Function/Frequency Response**

(a)  $y[n] = \sum_{k=1}^3 (\sqrt{k-1})x[n-k]$

**ANS = 6**

**1**  $H(e^{j\hat{\omega}}) = 2 \cos(\hat{\omega}) e^{-j3\hat{\omega}}$

**2**  $H(z) = \frac{z^{-2}(1-z^{-1})}{1-0.8z^{-1}}$

(b)  $y[n] = 0.9y[n-1] + 0.8y[n-2] + x[n] - x[n-3]$

**ANS = 3**

**3**  $H(e^{j\hat{\omega}}) = \frac{1 - e^{-j3\hat{\omega}}}{1 - 0.9e^{-j\hat{\omega}} - 0.8e^{-j2\hat{\omega}}}$

(c) `yy=filter([0,0,1,0,1],1,xx);`

**ANS = 1**

**4**  $H(e^{j\hat{\omega}}) = (1 + 2 \cos(\hat{\omega}))e^{-j3\hat{\omega}}$

**5**  $H(e^{j\hat{\omega}}) = \frac{1 - e^{-j3\hat{\omega}}}{1 + 0.9e^{-j\hat{\omega}} + 0.8e^{-j2\hat{\omega}}}$

(d)  $h[n] = 0.8^{n-2}u[n-2] - 0.8^{n-3}u[n-3]$

**ANS = 2**

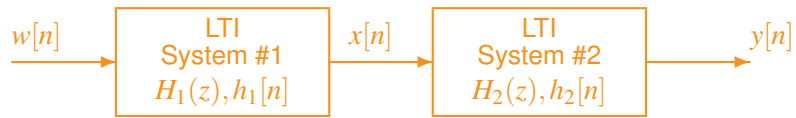
**6**  $H(z) = z^{-2}(1 + 0.707z^{-1})$

(e)  $h[n] = u[n-2] - u[n-5]$

**ANS = 4**

**PROBLEM Fall-11-Q.3.2:**

The diagram in the figure below depicts a *cascade connection* of two linear time-invariant systems, i.e., the output of the first system is the input to the second system, and the overall output is the output of the second system.



System #1 is the IIR filter described by the system function

$$H_1(z) = \frac{z^{-2}}{1 - 0.8z^{-1}},$$

and System #2 is the FIR filter described by the system function  $H_2(z) = z^{-3} - z^{-4}$ . Each part of this question can be worked independently.

- (a) Determine the poles and zeros of the first system  $H_1(z)$  and list them below. If there are no finite poles or zeros, write **NONE** in the corresponding space. If a pole or zero occurs multiple times, be sure to list it multiple times in your answer.

ZEROS at  $z =$  NONE

POLES at  $z = 0, 0.8$

- (b) Determine the impulse response of the second system  $h_2[n]$ .

$$h_2[n] = \delta[n - 3] - \delta[n - 4]$$

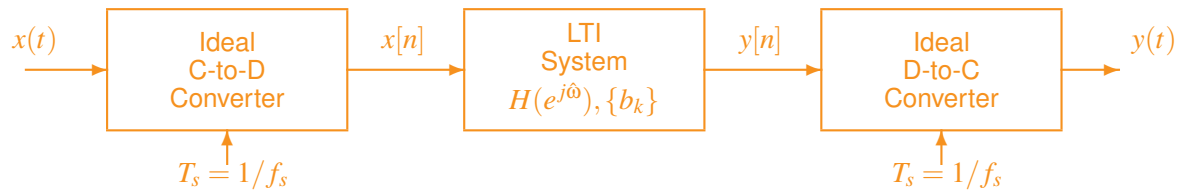
- (c) Determine the overall output  $y[n]$  when the input is a delayed unit step function  $w[n] = u[n - 2]$ .

$$y[n] = 0.8^{n-7} u[n - 7]$$



**PROBLEM Fall-11-Q.3.3:**

Consider the following system for discrete-time filtering of continuous-time signals:



Both parts of this question should be worked independently.

- (a) For this part, assume that the LTI system in the figure is defined by the frequency response  $H(e^{j\hat{\omega}}) = \cos(\hat{\omega})e^{-j2\hat{\omega}}$ , and the sampling rate is  $f_s = 400$ . Determine the overall system output  $y(t)$  if the input is  $x(t) = 10 + \cos(2\pi 50t) + \cos(2\pi 500t + 3\pi/4)$ .

$$y(t) = 10 + \frac{\sqrt{2}}{2} \cos(2\pi 50t - \pi/2)$$

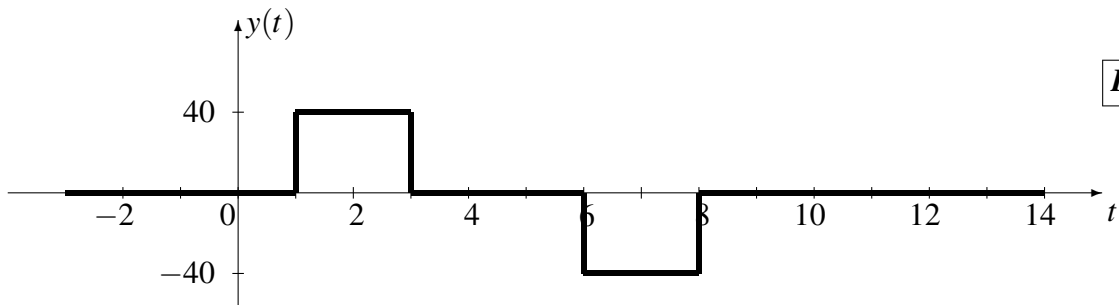
- (b) This part deals with the design of FIR nulling filters similar to the filters you designed in Lab 8. Given the following three conditions, determine the values of the FIR filter coefficients  $b_0, b_1$  and  $b_2$ . First, when the input to the FIR filter is  $x[n] = 15 \cos(3\pi n/4 + \pi/3)$  the output is  $y[n] = 0$ . Second, the filter coefficients should be scaled so that when the input is the DC signal  $x[n] = 10$  the output is  $y[n] = 30$ . Finally, assume that  $b_2 = b_0$ .

$$b_0 = 0.879 \quad b_1 = 1.243 \quad b_2 = 0.879$$

**PROBLEM Fall-11-Q.3.4:**

The following two questions about continuous-time convolution should be worked independently.

- (a) If the input to an LTI system is  $x(t) = u(t + 2) - u(t - 3)$ , determine the output signal  $y(t) = x(t) * h(t)$  when  $h(t) = 40\delta(t - 3) - 40\delta(t - 5)$ . Give your answer as a carefully labeled sketch showing numerical values on both the time and amplitude axes.



- (b) If the signal  $r(t)$  is a rectangular pulse, then  $w(t) = r(t) * r(t)$  is a triangle. Suppose that

$$w(t) = r(t) * r(t) = (4t)[u(t) - u(t - 4)] + (32 - 4t)[u(t - 4) - u(t - 8)].$$

On the axes below, give carefully labeled sketches of both  $w(t)$  and  $r(t)$ .

