

ECE 3075A
Random Signals

Lecture 1

**Introduction to Probability Theory & Its
Applications in Electrical & Computer
Engineering**

School of Electrical and Computer Engineering
Georgia Institute of Technology
Fall, 2003

Syllabus

- Lecturer: Professor B.H. Juang
- GTA: TBA
- Lecture time: MWF 1500-1555 @ Van Leer C341
- Office hours: MF 1400-1455 @ Bunger Henry 310
- Text: Cooper & McGillem, *Probabilistic Methods of Signal & System Analysis*, 3rd edition
- Homework: assignment given every week; due one week after date of assignment at class time
- Other information, announcements, regular update:
<http://users.ece.gatech.edu/~juang>

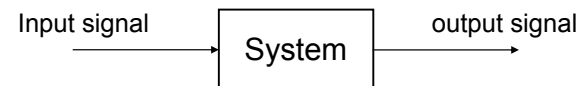
Exams and Grading Schedule

- Three quizzes and one final exam
- Open book tests
- Grading schedule

Quiz #1	September 15	15%
Quiz #2	October 10	15%
Quiz #3	November 10	15%
Homework	Every week, unless noted otherwise	20%
Final	July 28, 1130-1420	35%

System & Signal

- Concept of signals and systems
- Description or characterization of signals & systems
- Deterministic description versus characterization of random systems and signals
- Analysis of signal and system
- Foundation of analysis: probability theory, random variables and stochastic processes



Signal

- An expression that carries “useful” information.
- Origin of signal
 - Measurements of phenomenon or behavior
e.g., temperature in a room, path of a storm, stock price
 - Man-made expressions
e.g., language in conversation, flag waving, a wink
- A signal may represent the occurrence of an event, in a discrete manner (e.g., the result of an election), or as a continuous-time function (e.g., a music note or a sequence of music notes realized by an instrument).
- A signal can be parametric (e.g., the frequency of a pure tone) or non-parametric (e.g., thumbs-up).

System

- A system is a function that maps or transforms an input domain to an output domain. It behaves as a processor or a transducer that responds to an input signal to produce an output signal.
- A system is defined by a set of system parameters, which determine how the input-output mapping is to be conducted. For example,
$$y = f(x; \lambda)$$
where x is input and λ is the parameter of the system.
- A system can also be defined non-parametrically.
- A system that generates a signal is often called a **source**. (Question: How to describe the behavior of a source?)

Deterministic vs. Random Signals/Systems

- Deterministic (or non-random) signal or system

Examples:

$$x(t; \omega, \theta) = A \cos(\omega t + \theta)$$

$$y(t) = x(t) \sin(2\omega t)$$

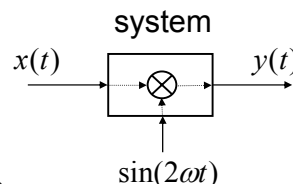
- Random signal or system

$$\mathbf{x}(t; \boldsymbol{\omega}, \boldsymbol{\theta}) = \mathbf{A} \cos(\boldsymbol{\omega} t + \boldsymbol{\theta}) + \mathbf{n}(t)$$

$$\mathbf{y}(t) = \mathbf{x}(t) \sin(2\boldsymbol{\omega} t) + \mathbf{v}(t)$$

The values of $\boldsymbol{\omega}$, $\boldsymbol{\theta}$ are **uncertain**.

$\mathbf{n}(t)$ and $\mathbf{v}(t)$ are noise/contamination.



Why Use Probabilistic Methods for Analysis

- Many sources produce signal that cannot be easily described in a deterministic manner. E.g., speech.
- Observation of real signal is almost always contaminated by noise or disturbance which may be random. For example, a returned radar signal is always mixed with noise. A speech signal recorded in an office has background noise and some echo.
- Parameters of a system may fluctuate unpredictably, resulting in uncertainty in input-output relationship.
- When uncertainty is present, a deterministic characterization of the signal or the system becomes inadequate.

Preliminary Concept - Example

Measurement of power of a signal

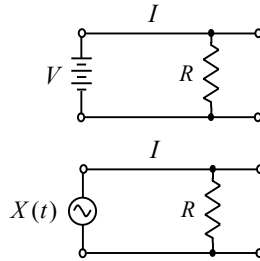
V is constant – a DC signal

$$I = \frac{V}{R} \quad \text{and} \quad P = IV = I^2 R$$

$X(t) = V_0 \cos(\omega t + \theta)$ - an AC signal

$$I = \frac{V_0 \cos(\omega t + \theta)}{R} = I_0 \cos(\omega t + \theta)$$

$$\text{RMS current} = \left\{ \frac{1}{T} \int_0^T I_0^2 \cos^2(\omega t) dt \right\}^{1/2} = \frac{I_0}{\sqrt{2}} = 0.707 I_0 \quad P = \frac{I_0^2 R}{2}$$



What if $X(t)$ is a random signal or noise?

Review of Calculus & Math Quantities

$$\cos(x \pm y) = \cos(x) \cos(y) \mp \sin(x) \sin(y)$$

$$\sin(x \pm y) = \sin(x) \cos(y) \pm \cos(x) \sin(y)$$

$$\cos(2x) = \cos^2(x) - \sin^2(x)$$

$$\cos(x) = \frac{1}{2} [e^{jx} + e^{-jx}] \quad \sin(x) = \frac{1}{2j} [e^{jx} - e^{-jx}]$$

$$2 \cos(x) \cos(y) = \cos(x - y) + \cos(x + y)$$

$$2 \sin(x) \sin(y) = \cos(x - y) - \cos(x + y)$$

$$2 \sin(x) \cos(y) = \sin(x - y) + \sin(x + y)$$

$$2 \cos^2(x) = 1 + \cos(2x)$$

$$2 \sin^2(x) = 1 - \cos(2x)$$

Review of Calculus

$$\int (a + bx)^n dx = \frac{(a + bx)^{n+1}}{b(n+1)} \quad n > 0$$

$$\int_{-3}^2 (1 + 2x)^4 dx = \frac{(1 + 2x)^5}{2(4+1)} \Big|_{x=-3}^2 = \frac{5^5 - (-5)^5}{10} = 5^4 = 625$$

$$\int \frac{dx}{a + bx} = \frac{1}{b} \ln |a + bx|$$

$$\int e^{ax} dx = \frac{e^{ax}}{a} \quad \int_0^{100} 2e^{-3x} dx = \frac{2}{-3} e^{-3x} \Big|_{x=0}^{100} \approx \frac{2}{3}$$

$$\int x e^{ax} dx = e^{ax} [x a^{-1} - a^{-2}]$$

$$\int \cos(x) dx = \sin(x) \quad \int \sin(x) dx = -\cos(x)$$