

**ECE 3075A**  
**Random Signals**

**Lecture 13**  
**Joint Moments & Marginal Distributions**

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**More on Correlation Coefficient**

$$\rho = E\left\{\left[\frac{X - \bar{X}}{\sigma_X}\right]\left[\frac{Y - \bar{Y}}{\sigma_Y}\right]\right\} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \left[\frac{x - \bar{X}}{\sigma_X}\right]\left[\frac{y - \bar{Y}}{\sigma_Y}\right] f_{XY}(x, y) dx dy$$

$$= \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{xy - \bar{X}y - x\bar{Y} + \bar{X}\bar{Y}}{\sigma_X \sigma_Y} f_{XY}(x, y) dx dy = \frac{E[XY] - \bar{X}\bar{Y}}{\sigma_X \sigma_Y}$$

Define normalized r.v.  $\xi = \frac{X - \bar{X}}{\sigma_X}$  and  $\eta = \frac{Y - \bar{Y}}{\sigma_Y}$

Both  $\xi$  and  $\eta$  are zero mean and unit variance, that is

$$\bar{\xi} = \bar{\eta} = 0 \text{ and } \sigma_{\xi}^2 = \sigma_{\eta}^2 = 1. \text{ Then, } \rho = E[\xi\eta]$$

$$E[(\xi \pm \eta)^2] = E[\xi^2 \pm 2\xi\eta + \eta^2] = \sigma_{\xi}^2 \pm 2\rho + \sigma_{\eta}^2 = 2(1 \pm \rho) \geq 0$$

Therefore,  $-1 \leq \rho \leq 1$

And if the two r.v.s are independent,  $\rho = E[\xi\eta] = \bar{\xi}\bar{\eta} = 0$

**Example – Exercise 3-4.1**

Two random variables have means of 1 and variances of 1 and 4, respectively. Their correlation coefficient is 0.5.

- a) Find the variance of their sum.
- b) Find the mean square value of their sum.
- c) Find the mean square value of their difference.

$$1 = \sigma_X^2 = \bar{X}^2 - \bar{X}^2 = \bar{X}^2 - 1 \quad \therefore \bar{X}^2 = 2, \text{ and } 4 = \sigma_Y^2 = \bar{Y}^2 - \bar{Y}^2 = \bar{Y}^2 - 1 \quad \therefore \bar{Y}^2 = 5$$

$$0.5 = \rho = \frac{E[XY] - \bar{X}\bar{Y}}{\sigma_X \sigma_Y} = \frac{\bar{XY} - 1}{2} \quad \therefore \bar{XY} = 2$$

$$\sigma_{X+Y}^2 = E[(X + Y - \bar{X} - \bar{Y})^2] = \bar{X}^2 + 2\bar{XY} + \bar{Y}^2 - (\bar{X} + \bar{Y})^2$$

$$= 2 + 4 + 5 - 4 = 7 \quad (\text{Is this independent of the means?})$$

$$E[(X + Y)^2] = \bar{X}^2 + 2\bar{XY} + \bar{Y}^2 = 2 + 4 + 5 = 11$$

$$E[(X - Y)^2] = \bar{X}^2 - 2\bar{XY} + \bar{Y}^2 = 2 - 4 + 5 = 3$$

**Conditional Probability**

Recall  $F_X(x|M) = \Pr(X \leq x | M) = \frac{\Pr(X \leq x, M)}{\Pr(M)}, \Pr(M) > 0$

If  $M = \{Y \leq y\}$ ,

$$F_X(x|M) = \Pr(X \leq x | Y \leq y) = \frac{\Pr(X \leq x, Y \leq y)}{\Pr(Y \leq y)} = \frac{F_{X,Y}(x, y)}{F_Y(y)}$$

Similarly,  $F_X(x|y_1 < Y \leq y_2) = \frac{F_{X,Y}(x, y_2) - F_{X,Y}(x, y_1)}{F_Y(y_2) - F_Y(y_1)}$

$$f_X(x|Y = y) = \lim_{\Delta y \rightarrow 0} \frac{F_{X,Y}(x, y + \Delta y) - F_{X,Y}(x, y)}{F_Y(y + \Delta y) - F_Y(y)} = \frac{\partial F_{X,Y}(x, y) / \partial y}{\partial F_Y(y) / \partial y} = \frac{\int_{-\infty}^x f_{X,Y}(u, y) du}{f_Y(y)}$$

$$f_X(x|Y = y) = \frac{d}{dx} \int_{-\infty}^x f_{X,Y}(u, y) du = \frac{f_{X,Y}(x, y)}{f_Y(y)}, \quad f_Y(y|X = x) = \frac{f_{X,Y}(x, y)}{f_X(x)}$$

*Notation issue coming up!*

## Conditional Probability - Notation

$$f_{Y|X}(y|X=x) = f_{Y|X}(y|x) = \frac{f_{X,Y}(x,y)}{f_X(x)}$$

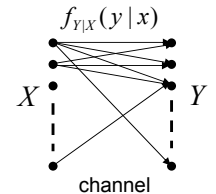
$$f_{X|Y}(x|Y=y) = f_{X|Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_Y(y)}$$

We use  $f_{Y|X}(y|x)$  and  $f_{X|Y}(x|y)$  to make explicit the fact that  $x$  and  $y$  are “**realized**” random variables, rather than a parameter that define the density function  $f(y|x)$  or  $f(x|y)$ . If they are “parameters”, we’d use the notation like  $f(y;x)$  or  $f(x;y)$  [or more likely,  $f(y;a)$  or  $f(x;b)$ ]

Marginals:  $f_X(x) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dy = \int_{-\infty}^{\infty} f_{X|Y}(x|y) f_Y(y) dy$   
 $f_Y(y) = \int_{-\infty}^{\infty} f_{X,Y}(x,y) dx = \int_{-\infty}^{\infty} f_{Y|X}(y|x) f_X(x) dx$

## Use of Conditional Probability - Example

- Consider an additive noise channel  $Y = X + N$ . I.e., a “random” source puts out signal  $X$  but at the destination, it is observed as  $Y$  due to additive noise  $N$ .



- We are often interested in estimating  $x$  (i.e., what was sent) based on the received signal  $y$ .

- Use Bayes formula

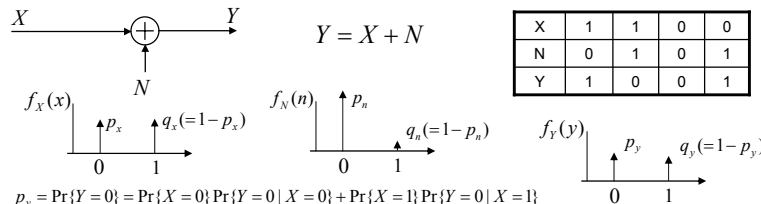
$$f_{X|Y}(x|y) = \frac{f_{Y|X}(y|x) f_X(x)}{f_Y(y)}$$

$$f_{Y|X}(y|x) = f_N(n) = f_N(y-x) \quad [\text{Note: here, we are looking at } Y = x+N, \text{ because } x \text{ is known}]$$

$$f_{X|Y}(x|y) = \frac{f_N(y-x) f_X(x)}{f_Y(y)} = \frac{f_N(y-x) f_X(x)}{\int_{-\infty}^{\infty} f_N(y-x) f_X(x) dx}$$

For a given observation  $y$ ,  $\arg \max_x f_{X|Y}(x|y)$  is a good estimate of the original symbol.

## Binary Channel Example



$$p_y = \Pr\{Y=0\} = \Pr\{X=0\} + \Pr\{Y=0|X=1\} = p_x + \Pr\{Y=0|X=1\}$$

$$\Pr\{Y=0|X=0\} = \Pr\{N=0\} = p_n, \quad \Pr\{Y=0|X=1\} = \Pr\{N=1\} = q_n$$

$$\therefore p_y = p_x p_n + q_n q_x = p_x p_n + (1-p_x)(1-p_n) = 1 - p_x - p_n + 2p_x p_n \quad \text{and} \quad q_y = 1 - p_y = p_x + p_n - 2p_x p_n$$

$$f_{X|Y}(x|y) = f_{Y|X}(y|x) f_X(x) [f_Y(y)]^{-1} = f_N(y-x) f_X(x) \left[ \int_{-\infty}^{\infty} f_N(y-x) f_X(x) dx \right]^{-1}$$

y	x	$f_{X Y}(x y)$
0	0	$p_n p_x (p_y)^{-1}$
0	1	$q_n q_x (p_y)^{-1}$
1	0	$q_n p_x (q_y)^{-1}$
1	1	$p_n q_x (q_y)^{-1}$

Let  $p_x = 0.5$  and  $p_n = 0.9$ .  
 $\rightarrow p_y = 0.5 * 0.9 + 0.5 * 0.1 = 0.5$

y	x	$f_{X Y}(x y)$
0	0	0.9
0	1	0.1
1	0	0.1
1	1	0.9

Let  $p_x = 0.3$  and  $p_n = 0.6$ .  
 $\rightarrow p_y = 0.3 * 0.6 + 0.7 * 0.4 = 0.46$

y	x	$f_{X Y}(x y)$
0	0	9/23
0	1	14/23
1	0	2/9
1	1	7/9

## Modeling Measurement & Noise - Example

- In space probe, high energy particles are received from space. The interval between particle arrival times is considered a measurement of a certain space activity. (Recall Poisson distribution.) The arrival interval is a random signal with exponential distribution

$$f_X(x) = \begin{cases} b \exp(-bx) & x \geq 0 \\ 0 & x < 0 \end{cases}$$

- The measured signal usually has an additive noise component with Gaussian distribution:

$$Y = X + N \quad \text{and} \quad f_N(n) = (\sqrt{2\pi}\sigma_N)^{-1} \exp(-n^2 / 2\sigma_N^2)$$

$$f_Y(y) = \int_{-\infty}^{\infty} f_{Y|X}(y|x) f_X(x) dx = \int_{-\infty}^{\infty} f_N(y-x) f_X(x) dx$$

$$= \int_0^{\infty} \frac{b}{\sqrt{2\pi}\sigma_N} \exp(-bx) \exp\left(-\frac{(y-x)^2}{2\sigma_N^2}\right) dx = b \exp\left(-by + \frac{b^2\sigma_N^2}{2}\right) \mathcal{Q}\left(-\frac{y-b\sigma_N^2}{\sigma_N}\right)$$

## Measurement & Noise – Example (cont'd)

- The a posteriori probability density function is

$$f_{X|Y}(x|y) = \begin{cases} [f_Y(y)]^{-1} \frac{b}{\sqrt{2\pi}\sigma_N} \exp(-bx) \exp\left(-\frac{(y-x)^2}{2\sigma_N^2}\right), & x \geq 0 \\ 0, & x < 0 \end{cases}$$

$$f_{X|Y}(x|y) = \begin{cases} [f_Y(y)]^{-1} \frac{b}{\sqrt{2\pi}\sigma_N} \exp\left(-bx - \frac{(y-x)^2}{2\sigma_N^2}\right), & x \geq 0 \\ 0, & x < 0 \end{cases}$$

Given  $y$  (received, known), we estimate the signal  $x$  (unknown) by  $\arg \max_x f_{X|Y}(x|y)$  which is achieved at  $\arg \min_x 2\sigma_N^2 bx + (y-x)^2$

$$\frac{d}{dx} 2\sigma_N^2 bx + (y-x)^2 = 2\sigma_N^2 b - 2(y-x) = 0, \quad \rightarrow \quad x = y - \sigma_N^2 b \text{ if } y \geq \sigma_N^2 b$$

Therefore, if  $y \geq \sigma_N^2 b$ ,  $\hat{x} = y - \sigma_N^2 b$ , and  $y < \sigma_N^2 b$ ,  $\hat{x} = 0$

## Statistical Independence

- When two random variables are independent, a knowledge of one r.v. gives no information about the value of the other.

$X$  and  $Y$  are statistically independent, iff  $f_{X,Y}(x,y) = f_X(x)f_Y(y)$

$$E[XY] = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xy f_{X,Y}(x,y) dx dy = \int_{-\infty}^{\infty} f_X(x) dx \int_{-\infty}^{\infty} f_Y(y) dy = E[X]E[Y]$$

$$f_{X|Y}(x|y) = \frac{f_{X,Y}(x,y)}{f_Y(y)} = f_X(x), \quad f_{Y|X}(y|x) = \frac{f_{X,Y}(x,y)}{f_X(x)} = f_Y(y)$$

Another way to see independence – if the joint probability density function can be factored into product of a function of  $x$  only and a function of  $y$  only, then the two r.v.s are statistically independent.

E.g., if  $f_{X,Y}(x,y) = u(x)u(y)xe^{-x(y+1)}$ , can  $X$  and  $Y$  be independent?

## Exercise 3-3.1

Two random variables,  $X$  and  $Y$ , have a joint probability density function of the form

$$f_{X,Y}(x,y) = \begin{cases} ke^{-(x+ay-1)}, & 0 \leq x \leq \infty, 1 \leq y \leq \infty \\ 0, & \text{elsewhere} \end{cases}$$

Find

a) values of  $k$  and  $a$  for which the random variables are statistically independent; b) the expected value of  $XY$ .

Since the joint pdf is separable, the two r.v.s are independent. We need to find  $a$  and  $k$  such that the function is a legitimate joint pdf.

$$\int_0^{\infty} \int_1^{\infty} f_{X,Y}(x,y) dy dx = \int_0^{\infty} \int_1^{\infty} ke^{-(x+ay-1)} dy dx = ke \int_0^{\infty} e^{-x} dx \int_1^{\infty} e^{-ay} dy$$

$$= ke \left[ -e^{-x} \right]_{x=0}^{\infty} \left[ -\frac{e^{-ay}}{a} \right]_{y=1}^{\infty} = ke \cdot 1 \cdot \frac{e^{-a}}{a} = 1, \quad \rightarrow \quad a = 1, \text{ and } k = 1$$

$$E[XY] = e \int_0^{\infty} xe^{-x} dx \int_1^{\infty} ye^{-y} dy = e \cdot 1 \cdot 2e^{-1} = 2$$

## More on Statistical Independence

- Random variables  $X_1, X_2, \dots, X_N$  are independent,

$$\text{iff } \Pr\{X_1 \leq x_1, X_2 \leq x_2, \dots, X_N \leq x_N\} \\ = \Pr\{X_1 \leq x_1\} \Pr\{X_2 \leq x_2\} \dots \Pr\{X_N \leq x_N\}$$

Similarly, they are independent iff

$$f_{X_1, X_2, \dots, X_N}(x_1, x_2, \dots, x_N) = f_{X_1}(x_1) f_{X_2}(x_2) \dots f_{X_N}(x_N)$$

- If  $X_1, X_2, \dots, X_N$  are independent, then any subgroup of the random variables are independent. (Why?)
- However, generalization is not guaranteed: e.g., pair-wise independence does not immediately imply overall independence.