

EE 6082 HW1

1. Identity element is unique.

Suppose not: $\Rightarrow \exists e' \neq e$ s.t. $\forall g \in G, e' * g = g$.

Let $e = g, \Rightarrow e = e' * e = e',$ a contradiction. Q.E.D.

2. Inverse a^{-1} of a is unique.

Suppose not: $\Rightarrow \exists a_1^{-1} \neq a_2^{-1}$ s.t. $\forall a \in G$

$$a_1^{-1} * a = a_2^{-1} * a = e.$$

By associativity, $(a_1^{-1} * a) * a_2^{-1} = a_1^{-1} * (a * a_2^{-1})$

$$\Rightarrow e * a_2^{-1} = a_1^{-1} * e, \text{ or } a_2^{-1} = a_1^{-1}, \text{ a contradiction. Q.E.D.}$$

(2) 6. The element 2 has no inverse, otherwise $2 * 2^{-1} = 1$
and $4 = 4 * (2 * 2^{-1}) = (4 * 2) * 2^{-1} = 0 * 2^{-1} = 0.$

(3) 16. Since there are only 4 linearly independent vectors over $GF(2)$, dimension = 4.

$GF(2)$ is embedded in $GF(4)$, therefore the dimension does not change, so dimension = 4.

Since there are 5 linearly independent vectors over $GF(3)$, dimension = 5 in this case.

17. We need solutions y to $Gy = 0$, where

$$G = \begin{bmatrix} 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 \end{bmatrix}. \text{ We use row reduction on } G;$$

$$(5) \quad G \rightarrow \begin{bmatrix} 1 & 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 & 1 \end{bmatrix} = [I_3 \mid P]. \text{ We then perform}$$

$$\begin{bmatrix} -P^T \\ I_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 & 1 \end{bmatrix}, \text{ which gives a basis as } \{(10110), (01101)\}.$$

19. $(11010) = (10000) + (01000) + (00010)$

20. $(10111) = (10101) + (00010).$

21. We essentially have the system

$$\begin{bmatrix} y_1^T & y_2^T & \dots & y_n^T \end{bmatrix} \begin{bmatrix} a_1^T \\ a_2^T \\ \vdots \\ a_n^T \end{bmatrix} = y^T \text{ where } a = (a_1, a_2, \dots, a_n)$$

and each $y_i = (y_{i1}, y_{i2}, \dots, y_{in})$. We can thus use

Cramer's rule to solve for the $\{a_i\}$ by

$$a_i = \frac{\begin{vmatrix} y_1^T & \dots & y_{i-1}^T & y_{i+1}^T & \dots & y_n^T \\ y_1^T & \dots & y_1^T & y_2^T & \dots & y_n^T \end{vmatrix}}{\begin{vmatrix} y_1^T & \dots & y_n^T \\ y_1^T & \dots & y_n^T \end{vmatrix}}$$