

## ECE 7251: Signal Detection and Estimation

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Lecture 8, 1/23/02:  
Nonrandom Parameter Estimation

### What Can We Do?

- No prior!  $\mathbf{q}$  is not a random variable.
- How about “conditional” MSE?

$$MSE_{\mathbf{q}} = E_{\mathbf{q}} [(\hat{\mathbf{q}}(Y) - \mathbf{q})^2]$$

- Trivial estimator:  $Y \sim p(y; \mathbf{q})$

$$\hat{\mathbf{q}}(Y) = \mathbf{q}_0$$

- Does really well if  $\mathbf{q} = \mathbf{q}_0$ ,  
but might suck otherwise

### Consistency

- Consistency: for all  $\mathbf{q}$  for any  $\epsilon > 0$

$$\lim_{n \rightarrow \infty} \Pr_{\mathbf{q}} (|\underbrace{\hat{\mathbf{q}}(Y)}_{\text{func. of } n} - \mathbf{q}| > \epsilon) = 0$$

“convergence  
in probability”

- Useful result: If
  - $\mathbf{a} = g(\mathbf{q})$ , where  $g$  is a continuous func., and
  - $\hat{\mathbf{q}}$  is consistent for  $\mathbf{q}$ ,

*then*

$\hat{\mathbf{a}} = g(\hat{\mathbf{q}})$  is consistent for  $\mathbf{a}$

### More Definitions

- Estimator Bias:  $b_{\mathbf{q}}(\hat{\mathbf{q}}) = E_{\mathbf{q}}[\hat{\mathbf{q}}(Y)] - \mathbf{q}$

- Unbiasedness: for all  $\mathbf{q}$ ,

$$b_{\mathbf{q}}(\hat{\mathbf{q}}) = 0, \text{ i.e. } E_{\mathbf{q}}[\hat{\mathbf{q}}(Y)] = \mathbf{q}$$

- Estimator Variance:

$$\text{var}_{\mathbf{q}}(\hat{\mathbf{q}}) = E_{\mathbf{q}} [(\hat{\mathbf{q}}(Y) - E_{\mathbf{q}}[\hat{\mathbf{q}}(Y)])^2]$$

### Decomposition of MSE

$$\begin{aligned} MSE_{\mathbf{q}}(\hat{\mathbf{q}}) &= E_{\mathbf{q}} [(\hat{\mathbf{q}}(Y) - \mathbf{q})^2] \\ &= E_{\mathbf{q}} [(\underbrace{\hat{\mathbf{q}}(Y) - E_{\mathbf{q}}[\hat{\mathbf{q}}(Y)]}_{\text{var}(\hat{\mathbf{q}})} + \underbrace{(E_{\mathbf{q}}[\hat{\mathbf{q}}(Y)] - \mathbf{q})}_{b_{\mathbf{q}}(\hat{\mathbf{q}})})^2] \\ &= E_{\mathbf{q}} [(\hat{\mathbf{q}}(Y) - E_{\mathbf{q}}[\hat{\mathbf{q}}(Y)])^2] + (E_{\mathbf{q}}[\hat{\mathbf{q}}(Y)] - \mathbf{q})^2 \\ &\quad + 2E_{\mathbf{q}}[\hat{\mathbf{q}}(Y) - E_{\mathbf{q}}[\hat{\mathbf{q}}(Y)](E_{\mathbf{q}}[\hat{\mathbf{q}}(Y)] - \mathbf{q})] \\ &= \text{var}_{\mathbf{q}}(\hat{\mathbf{q}}) + b_{\mathbf{q}}^2(\hat{\mathbf{q}}) \end{aligned}$$

Often have a “bias-variance tradeoff”

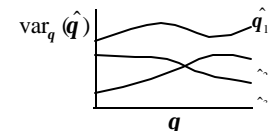
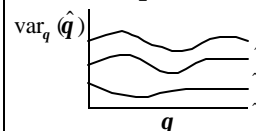
### MVU Estimators

- Minimum variance unbiased estimator:

$$E_{\mathbf{q}}[\hat{\mathbf{q}}(Y)] = \mathbf{q}$$

$$\text{var}_{\mathbf{q}}(\hat{\mathbf{q}}) \leq \text{var}_{\mathbf{q}}(\tilde{\mathbf{q}}) \text{ for all } \tilde{\mathbf{q}}$$

where  $\tilde{\mathbf{q}}$  is any other unbiased estimator



### Stuff about MVU Estimators

- No easy way to know if they exist
- No easy way to find them if they do exist
- Closest thing to a turn -the-crank procedure:
  1. Find some (not necessarily so great) unbiased estimator  $\hat{q}$
  2. Find a complete sufficient statistic  $T(Y)$
  3. Apply Rao-Blackwell-Lehmann-Scheffe theorem:

$$\hat{q} = E[\hat{q} | T(Y)]$$

Best (?) explanation: Kay, Vol. I, Ch. 5

### Useful Recipes

#### Method of Moments



Karl Pearson

#### Maximum Likelihood



Sir R.A. Fisher

Pics from MacTutor History of Mathematics Archive  
(<http://www-groups.dcs.st-andrews.ac.uk/~history>)

### Maximum Likelihood Estimators

- Likelihood:  $p(y; \mathbf{q})$
- Loglikelihood:  $l(\mathbf{q}) = \ln p(y; \mathbf{q})$   
(often drop terms which are constant with respect to  $\mathbf{q}$ )

- ML estimator:

$$\hat{\mathbf{q}}_{ML}(y) = \underset{\mathbf{q}}{\operatorname{argmax}} p(y; \mathbf{q}) = \underset{\mathbf{q}}{\operatorname{argmax}} l(\mathbf{q})$$

- Sometimes cannot be found in closed form
- Most commonly used nonrandom parameter estimator in engineering literature

### Some Properties of ML Estimators

- Consistent
- Asymptotically unbiased: As  $n \rightarrow \infty$ ,

$$E_q[\hat{\mathbf{q}}(Y)] \rightarrow \mathbf{q}$$

- Asymptotically MVUE
- Invariant to functional transformations:  
If  $\mathbf{a} = g(\mathbf{q})$ ,  
then  $\hat{\mathbf{a}}_{ML} = g(\hat{\mathbf{q}}_{ML})$
- Asymptotically efficient (to be discussed later)

### Method of Moments

- Quick, cheap & dirty
- Define moments:

$$m_k(\mathbf{q}) = E[Y^k] = \int y^k p(y; \mathbf{q}) d\mathbf{q}$$

- Find  $K$  moments such that

$$g(\mathbf{q}) = [m_1(\mathbf{q}), \dots, m_k(\mathbf{q})]$$

can be inverted for  $\mathbf{q}$

$$\mathbf{q} = g^{-1}([m_1(\mathbf{q}), \dots, m_k(\mathbf{q})])$$

### Method of Moments Con't.

- Just replace moments with empirical estimates:

$$\hat{\mathbf{q}}_{MoM}(y) = g^{-1}([\hat{m}_1(\mathbf{q}), \dots, \hat{m}_k(\mathbf{q})])$$

$$\hat{m}_k(\mathbf{q}) = \frac{1}{n} \sum_{i=1}^n y_i^k$$

- If moments are smooth functions of  $\mathbf{q}$ , MoM estimator is
  - Asymptotically unbiased
  - Consistent
  - No other grand wonderful properties in general

### Comments on Method of Moments

- If regular moments don't exist (i.e. Cauchy, other heavy-tailed distributions) can use "fractional" moments
- MoM often used to get initial value for iterative likelihood maximization techniques
- MoM doesn't always give unique estimator (different choices of moments gives different answers!)
- More details: Kay, Vol. I, Ch. 9