

A New Family of Algebraically Defined Graphs With Small Automorphism Group

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Abstract

Let p be an odd prime, $q = p^e$, $e \geq 1$, and $\mathbb{F} = \mathbb{F}_q$ denote the finite field of q elements. Let $f : \mathbb{F}^2 \rightarrow \mathbb{F}$ and $g : \mathbb{F}^3 \rightarrow \mathbb{F}$ be functions, and let P and L be two copies of the 3-dimensional vector space \mathbb{F}^3 . Consider a bipartite graph $\Gamma_{\mathbb{F}}(f, g)$ with vertex partitions P and L and with edges defined as follows: for every $(p) = (p_1, p_2, p_3) \in P$ and every $[l] = [l_1, l_2, l_3] \in L$, $\{(p), [l]\} = (p)[l]$ is an edge in $\Gamma_{\mathbb{F}}(f, g)$ if

$$p_2 + l_2 = f(p_1, l_1) \quad \text{and} \quad p_3 + l_3 = g(p_1, p_2, l_1).$$

The following question appeared in Nassau [9]: Given $\Gamma_{\mathbb{F}}(f, g)$, is it always possible to find a function $h : \mathbb{F}^2 \rightarrow \mathbb{F}$ such that the graph $\Gamma_{\mathbb{F}}(f, h)$ with the same vertex set as $\Gamma_{\mathbb{F}}(f, g)$ and with edges $(p)[l]$ defined in a similar way by the system

$$p_2 + l_2 = f(p_1, l_1) \quad \text{and} \quad p_3 + l_3 = h(p_1, l_1),$$

is isomorphic to $\Gamma_{\mathbb{F}}(f, g)$ for infinitely many q ? In this paper we show that the answer to the question is negative and the graphs $\Gamma_{\mathbb{F}_p}(p_1 \ell_1, p_1 \ell_1 p_2 (p_1 + p_2 + p_1 p_2))$ provide such an example for $p \equiv 1 \pmod{3}$. Our argument is based on proving that the automorphism group of these graphs has order p , which is the smallest possible order of the automorphism group of graphs of the form $\Gamma_{\mathbb{F}}(f, g)$.

1 Introduction

For a set A , let $|A|$ denote the cardinality of A . Let p be an odd prime, $q = p^e$, $e \geq 1$, $\mathbb{F} = \mathbb{F}_q$ denote the finite field of q elements, $\mathbb{F}^\times = \mathbb{F} \setminus \{0\}$, and $\mathbb{F}[X]$, $\mathbb{F}[X, Y]$, $\mathbb{F}[X, Y, Z]$ denote the rings of polynomials of indeterminates X, Y, Z over \mathbb{F} . A polynomial $f \in \mathbb{F}[X]$, defines a polynomial function $\mathbb{F} \rightarrow \mathbb{F}$ via $a \mapsto f(a)$. We will use the same notation f for this function, and write $f = f(x)$. It is well known that over \mathbb{F} , every function can be represented uniquely by a polynomial function of degree at most $q - 1$, e.g., one can use the Lagrange interpolating polynomial for this. All undefined terms and facts that we use without proofs related to finite fields can be found in Lidl and Niederreiter [7] or in Mullen and Panario [8].

For all missing definitions related to graphs, we refer the reader to Bollobás [1]. Our primary object of study in this paper is defined as follows. Let $f \in \mathbb{F}[X, Y]$ and $g \in \mathbb{F}[X, Y, Z]$. Let P and L be two copies of the 3-dimensional vector space \mathbb{F}^3 . We will refer to vertices of P as *points*, and to those of L as *lines*. To distinguish between vectors from P and L , we will use parentheses and brackets, respectively. Consider a bipartite graph $\Gamma_{\mathbb{F}}(f, g)$ with vertex partitions P and L and with edges defined as follows: for every $(p) = (p_1, p_2, p_3) \in P$ and every $[l] = [l_1, l_2, l_3] \in L$, $\{(p), [l]\} = (p)[l]$ is an edge in $\Gamma_3 = \Gamma_3(f, g) = \Gamma_{\mathbb{F}}(f(p_1, l_1), g(p_1, p_2, l_1))$ if

$$p_2 + l_2 = f(p_1, l_1) \quad \text{and} \quad p_3 + l_3 = g(p_1, p_2, l_1).$$

This graph has $2q^3$ vertices, and it is easy to see that a neighbor of any vertex is completely determined by the neighbor's first component. Hence, the degree of each vertex is q .

Graphs $\Gamma_{\mathbb{F}}(f, g)$ were studied recently due to a close relation of the graph $\Gamma_{\mathbb{F}}(p_1 l_1, p_1 l_1^2)$ to remarkable graphs called generalized quadrangles, whose definition we omit. For the details of this connection, generalizations of these graphs to other dimensions, and applications in finite geometries, extremal graph theory, and cryptography, see surveys by Lazebnik and Woldar [5], a more recent one by Lazebnik, Sun and Wang [6], and many references therein. For recent results not discussed in [6], see Nassau [9]; Kodess, Kronenthal, Manzano-Ruiz and Noe [4]; Xu, Cheng, and Tang [12].

The main question considered in this paper appeared in Nassau [9].

Question 1 ([9]) *Given a graph $\Gamma_3 = \Gamma_{\mathbb{F}}(f(p_1, l_1), g(p_1, p_2, l_1))$, is there a polynomial*

$h \in \mathbb{F}[X, Y]$, such that the graph $\Gamma_2 = \Gamma_{\mathbb{F}}(f(p_1, l_1), h(p_1, l_1))$:

$$p_2 + l_2 = f(p_1, l_1) \quad \text{and} \quad p_3 + l_3 = h(p_1, l_1),$$

is isomorphic to graph Γ_3 for infinitely many q ?

Here the indices 2 and 3 in the notation for introduced graphs reflect the number of variables present in functions g and h . There are many examples where the answer to Question 1 is affirmative. Moreover, given g , the polynomial h can be found in many ways. For example, it is easy to verify that the following graphs are isomorphic:

$$\Gamma_{\mathbb{F}}(p_1 l_1, p_1^2 l_1 - p_1 p_2) \simeq \Gamma_{\mathbb{F}}(p_1 l_1, p_2 l_1) \simeq \Gamma_{\mathbb{F}}(p_1 l_1, p_1 l_1^2) \simeq \Gamma_{\mathbb{F}}(p_1 l_1, p_1^2 l_1).$$

On the other hand, it is not clear how to exhibit an infinite family of graphs Γ_3 for which the answer to Question 1 is *negative*.

Another motivation for establishing that the family of all graphs Γ_2 is a proper subset of the family of all graphs Γ_3 (up to isomorphism) is related to the study of graphs with many edges and high girth. The *girth* of a graph containing cycles is the minimum length of all of its cycles. For odd $q \geq 3$, the only known graphs of the form Γ_3 of girth 8 are isomorphic to $\Gamma_{\mathbb{F}}(p_1 l_1, p_1 l_1^2)$, which is of the form Γ_2 . In particular, for infinitely many odd q and several classes of polynomials f and h , it has been proven that $\Gamma_2(f(p_1, l_1), h(p_1, l_1))$ has girth 8 only when it is isomorphic to $\Gamma_{\mathbb{F}}(p_1 l_1, p_1 l_1^2)$ (see references preceding Question 1). This suggests to focus the search for graphs Γ_3 with girth 8 to those that are not of the form Γ_2 (up to isomorphism).

Similarly to graphs Γ_2 or Γ_3 , we define a graph $\Gamma(f) = \Gamma_{\mathbb{F}}(f)$ in the following way. Let A and B be two copies of \mathbb{F}^2 . For $f \in \mathbb{F}[X, Y]$, consider a bipartite graph $\Gamma(f) = \Gamma_{\mathbb{F}}(f)$ with vertex partitions A and B and with edges defined as follows: for every $(a) = (a_1, a_2) \in A$ and every $[b] = [b_1, b_2] \in B$, $\{(a), [b]\} = (a)[b]$ is an edge in $\Gamma(f)$ if

$$a_2 + b_2 = f(a_1, b_1).$$

Consider a surjective q -to-1 map γ of the vertex set of graph $\Gamma_3(f, g)$ to the vertex set of graph $\Gamma(f)$ defined by deleting the third component of each vertex. It is obvious that if $(p)[l]$ is an edge in $\Gamma_3(f, g)$, then $\gamma((p))\gamma([l])$ is an edge of $\Gamma(f)$, i.e., γ is a *graph homomorphism*. Moreover, γ is a covering homomorphism, meaning that here the image of the neighborhood of every vertex v of $\Gamma_3(f, g)$ is the neighborhood of $\gamma(v)$ in $\Gamma(f)$. In this case, we will also say that $\Gamma_3(f, g)$ is a *cover* of $\Gamma(f)$ or a *q -lift* of $\Gamma(f)$. Let $Aut(\cdot)$ denote the automorphism group of a graph. It follows from our work that even when

$|Aut(\Gamma(f))|$ is large, it is possible to find a g such that $|Aut(\Gamma_3(f, g))|$ is much smaller than $|Aut(\Gamma(f))|$, and actually is as small as possible for graphs $\Gamma_3(f, g)$.

In the next section we describe an infinite family of graphs that furnish such an example.

2 Automorphisms of graphs Γ_2 and Γ_3

We note that every graph of the form $\Gamma_2 = \Gamma_{\mathbb{F}}(f(p_1, l_1), g(p_1 l_1))$ has the following automorphisms: For all $a, b \in \mathbb{F}$, consider the map $t_{a,b}$ on the vertex set of the graph Γ_2 , such that $t_{a,b}((p_1, p_2, p_3)) = (p_1, p_2 + a, p_3 + b)$ and $t_{a,b}([l_1, l_2, l_3]) = [l_1, l_2 - a, l_3 - b]$. We call these automorphisms *translations* of Γ_2 . It is obvious that all q^2 of $t_{a,b}$ form a subgroup of $Aut(\Gamma_2)$ that is isomorphic to the additive group $(\mathbb{F}^2, +)$ of the vector space \mathbb{F}^2 . Therefore, the order of $Aut(\Gamma_2)$ must be divisible by q^2 .

We note that every graph of the form $\Gamma_3 = \Gamma_{\mathbb{F}}(f(p_1, l_1), g(p_1, p_2, l_1))$ has the following automorphisms: For each $b \in \mathbb{F}$, consider a map t_b on the vertex set of Γ_3 , such that $t_b((p_1, p_2, p_3)) = (p_1, p_2, p_3 + b)$ and $t_b([l_1, l_2, l_3]) = [l_1, l_2, l_3 - b]$. We call these automorphisms *translations* of Γ_3 . It is obvious that all q of t_b form a group that is isomorphic to the additive group $(\mathbb{F}, +)$ of the field \mathbb{F} . Hence, the order of $Aut(\Gamma_2)$ must be divisible by q .

Suppose $q = p$. If we can exhibit a graph Γ_3 such that $|Aut(\Gamma_3)|$ is not divisible by p^2 , it will provide a negative answer to Question 1. Several of such graphs were found by computer, see [9]. One of them was simplified to the form

$$R = \Gamma_{\mathbb{F}_p}(p_1 l_1, p_1 p_2 l_1 (p_1 + p_2 + p_1 p_2)).$$

It was checked by computer that $|Aut(R)| = p$ for all prime p , $3 \leq p \leq 41$, but the proof that it holds for all odd p was based on several assumptions which are proven in this paper. Our notation R for the graph relates to the adjective “rigid”, and it reflects the fact that R has the smallest possible automorphism group for graphs of type Γ_3 . It was shown in [9], that the diameter of R is 6 for all odd q , $q > 3$, and for $q = 3$, the diameter is 7. It is also easy to check that R contains no 4-cycles.

The main result of this paper is the following.

Theorem 2.1. *For $p \equiv 1 \pmod{3}$, and $R = \Gamma_{\mathbb{F}_p}(p_1 l_1, p_1 p_2 l_1 (p_1 + p_2 + p_1 p_2))$. Then $|Aut(R)| = p$, and R cannot be presented in the form $\Gamma_{\mathbb{F}_p}(p_1 l_1, h(p_1, l_1))$.*

It is known that $|Aut(\Gamma_{\mathbb{F}_p}(p_1\ell_1))| = 2p^3(p-1)^2$, two different proofs can be found in Viglione [10]. As R is a p -lift of $\Gamma_{\mathbb{F}_p}(p_1\ell_1)$, by Theorem 2.1, it provides an example of our comment at the end of the previous section.

The idea of our proof of Theorem 2.1 is based on exhibiting two sets of vertices fixed by any automorphism of R (see Section 3), and then using these sets to conclude that $Aut(R) \simeq (\mathbb{F}_p, +)$ (see Section 4). We collect final remarks and state several open questions in Section 5. In the appendix we present code of simple programs mentioned in the text.

3 Special subsets of lines in R

In this section we consider graphs $R = \Gamma_{\mathbb{F}_q}(p_1l_1, p_1p_2l_1(p_1+p_2+p_1p_2))$, where q is a power of an odd prime and $q \geq 7$.

For $i \geq 1$, let $R^i(v)$ denote the set of vertices of R at distance i from a vertex v . $R^i(v)$ is often referred to as the i -neighborhood of v in R . Let $r_i(v) = |R^i(v)|$. It is clear that for every vertex v of R , $r_1(v) = q$, and, as R contains no 4-cycles, $r_2(v) = q(q-1)$. It is easy to check that the value of $r_3(v)$ is not the same for all vertices. The question we wish to ask is: For which lines $[l] = [l_1, l_2, l_3]$ of R $r_3([l])$ is maximum? As the size of a 3-neighborhood of a vertex of R is preserved by any automorphisms of a graph, answering this question will be helpful to us.

Due to the translation automorphisms on the third components of vertices of R , it is sufficient to consider lines $[A, B, 0]$ only.

Proposition 3.1. (*[9]*) *For $q \geq 7$, in graph R*

$$r_3([0, 1, 0]) = q^3 - 4q^2 + 9q - 8 \quad \text{and} \quad r_3([0, 0, 0]) = q^3 - 4q^2 + 8q - 6.$$

Our interest in $r_3([0, 1, 0])$ and $r_3([0, 0, 0])$ is due to the fact that they are the maximum and the second maximum, respectively, of the sizes of 3-neighbourhoods of lines in R . For completeness of the exposition, a rephrased proof of Proposition 3.1 appears as a part of our proof of Theorem 3.2 below, and it will exhibit the notions needed for the proof of the theorem.

Theorem 3.2. *Let $q \geq 7$, and $q \equiv 1 \pmod{3}$. Then*

(i) *For any line $[A, B, C]$ of R such that $(A, B) \neq (0, 0), (0, 1)$,*

$$r_3([A, B, C]) < r_3([0, 0, 0]) < r_3([0, 1, 0]).$$

(ii) For any point $(p) = (p_1, p_2, p_3)$ of R ,

$$r_3((p_1, p_2, p_3)) < r_3([0, 0, 0]).$$

Proof. For all odd prime powers q , $7 \leq q \leq 41$, the statement has been verified by computer. Therefore in all our arguments, we can assume $q \geq 43$, even if a smaller lower bound of q suffices.

We write $x \sim y$, if $\{x, y\}$ is an edge of R . Let

$$[A, B, 0] \sim (a, *, *) \sim [x, *, *] \sim (b, Aa - ax + bx - B, *)$$

be a path of length 3 starting at a line $[A, B, 0]$. Here $*$ represents expressions whose explicit form is not important to us. Hence, $A \neq x$ and $a \neq b$, as otherwise the corresponding vertices coincide. In what follows we use a Maple program to facilitate straightforward symbolic computations, the code can be found in the appendix. Let $c = Aa - ax + bx - B$. Then $x = (c - Aa + B)/(b - a)$, and the condition $x \neq A$ is equivalent to $(c \neq Ab - B$ and $a \neq b)$. Substituting this expression for x to $(b, Aa - ax + bx - B, *)$, we obtain the following representation of $R^3([A, B, 0])$:

$$R^3([A, B, 0]) = \left\{ \left(b, c, \frac{P_{A,B}(b, c; a)}{b - a} \right) : a, b, c, \in \mathbb{F}, c \neq Ab - B, a \neq b \right\}, \quad (1)$$

where $P_{A,B}(b, c; a)$, viewed as a polynomial of a , is

$$P_{A,B}(b, c; a) = A^2(Ab - B - c)a^4 + A(A - 2B + 1)(Ab - B - c)a^3 - B(2A - B + 1)(Ab - B - c)a^2 + (-Ac^2b^2 + AB^2b - Ac^2b - ACb^2 - B^3 - B^2c)a + cb(cb + c + b)(c + B). \quad (2)$$

Specializing $(A, B) = (0, 0)$ and $(A, B) = (0, 1)$, we obtain

$$R^3([0, 0, 0]) = \left\{ \left(b, c, \frac{bc^2(bc + b + c)}{b - a} \right) : a, b, c, \in \mathbb{F}, c \neq 0, a \neq b \right\} \quad (3)$$

and

$$R^3([0, 1, 0]) = \left\{ \left(b, c, \frac{(bc(bc + c + b) - b)(c + 1)}{b - a} + (c + 1) \right) : a, b, c, \in \mathbb{F}, b \neq a, c \neq -1 \right\}. \quad (4)$$

The representations (1) and (3) allow us to compare $r_3([0, 0, 0])$ and $r_3([A, B, 0])$ by going over all $q(q - 1)$ choices of (b, c) , and, for each fixed (b, c) , by comparing the sizes of ranges of the functions defining the 3rd components of the vertices from the corresponding 3-neighborhoods, namely

$$\frac{bc^2(bc + b + c)}{b - a} \quad \text{and} \quad \frac{(bc(bc + c + b) - b)(c + 1)}{b - a} + (c + 1),$$

where these functions are viewed as functions of a on $\mathbb{F} \setminus \{b\}$.

Case 1 (i): Suppose $A = B = 0$. We will use equality (3). If $bc^2(bc + b + c) \neq 0$, then $bc^2(bc + b + c)/(b - a)$ takes $q - 1$ distinct values, one for each a distinct from b , i.e., the greatest possible number of values for any function of a with domain of size $q - 1$. On the contrary, when $bc^2(bc + b + c) = 0$, then $0/(b - a) = 0$ for each a distinct from b . This corresponds to the least possible number of values, namely 1, that any (non-empty) function of a can have.

Note that $bc^2(bc + b + c) = 0$ and $c \neq 0$ imply that $b \neq -1$. Therefore all solutions of the system ($c \neq 0$ and $bc^2(bc + b + c) = 0$) can be describe as

$$Z = \{(0, c) : c \neq 0\} \cup \{(b, -b/(b + 1)) : b \neq 0, b \neq -1\}.$$

Hence, $|Z| = q - 1 + q - 2 = 2q - 3$. Therefore, the part of $R^3([0, 0, 0])$ formed by points $(b, c, 0)$ with $(b, c) \in Z$ contains $2q - 3$ points, and the remaining part, consisting of points of the form $(b, c, bc^2(bc + b + c)/(b - a))$, with $(b, c) \notin Z$ contains

$$[q(q - 1) - (2q - 3)](q - 1) = (q^3 - 3q^2 + 3)(q - 1) = q^3 - 4q^2 + 6q - 3$$

points. This proves that $r_3([0, 0, 0]) = (q^3 - 4q^2 + 6q - 3) + (2q - 3) = q^3 - 4q^2 + 8q - 6$, as stated in Proposition 3.1.

Case 2 (i): Suppose $A = 0, B = 1$.

We will use equality (4). Note that the system $((bc(bc + b + c) - b)(c + 1) = 0$ and $c \neq -1$) is equivalent to $(bc(bc + b + c) - b = 0$ and $c \neq -1)$, which is equivalent to

$$(b = 0 \text{ and } c \neq -1) \text{ or } [(b \neq 0 \text{ and } c(bc + b + c) - 1 = 0)].$$

The first system gives $q - 1$ points of the form $(0, c, c + 1)$. The second system is equivalent to $(b(c + 1)c = (1 - c)(1 + c)$ and $b \neq 0$ and $c \neq -1)$, or to just $(bc = (1 - c)$ and $b \neq 0$ and $c \neq -1)$. For $c = 1$, it has no solution. For $c \neq 1, -1$, it has a unique solution $b = (1 - c)/c$. Therefore the second system gives $q - 2$ points of the form $((1 - c)/c, c, c + 1)$, $c \neq 0, -1$. Hence, there are $(q - 1) + (q - 2) = 2q - 3$ pairs (b, c) such that each contributes 1 point to $R^3([0, 1, 0])$. They are of the form $(b, c, c + 1)$. Of the remaining possible pair (b, c) , $c \neq -1$, each contributes $q - 1$ points of the form $(b, c, (bc(bc + c + b) - b)(c + 1)/(b - a) + (c + 1))$, when a runs over all elements of \mathbb{F} except b . As there are $q(q - 1) - (2q - 3) = q^2 - 3q + 3$ of those pairs, they all contribute $(q^2 - 3q + 3)(q - 1)$

points. Therefore, $r_3([0, 1, 0]) = (q^2 - 3q + 3)(q - 1) + (2q - 3) = q^4 - 4q^2 + 9q - 8$. This proves the remaining case of Proposition 3.1.

Case 3 (i): Suppose $A = 0, B \neq 0, 1$.

Using formula (2), for $A = 0$, we obtain:

$$P_{0,B}(b, c; a) = -B(B + c)[(B - 1)a^2 + Ba] + cb(cb + c + b)(B + c).$$

Setting $t = b - a$, it is each to check we can rewrite $P_{0,B}(b, c; a)/(b - a)$ in the form

$$\frac{P_{0,B}(b, c; a)}{b - a} = \alpha_1 t + \alpha_0 + \frac{\alpha_{-1}}{t} =: f(t),$$

where $\alpha_1 = (B - 1)B(B + c)$, $\alpha_0 = B(B + c)(2(B - 1)b + B)$, and $\alpha_{-1} = b(B + c)^2(Bb - bc + B - b - c)$. Note that the condition $c \neq 0 \cdot b - B$, is equivalent to $B + c \neq 0$. When a changes over $\mathbb{F} \setminus \{b\}$, t changes over \mathbb{F}^\times , and for fixed $B \neq 0, 1, b$ and c , $B + c \neq 0$, the function f takes as many values as the function g , which is obtained from f by dropping α_0 and dividing by $\alpha_1 \neq 0$:

$$g(t) := t + \frac{b(Bb - bc + B - b - c)}{t} = t + \frac{\gamma}{t}, \quad t \neq 0,$$

where $\gamma = b(Bb - bc + B - b - c)$. For $\gamma = 0$, g takes $q - 1$ values. This happens when $b = 0$, or $b = -(B^2 - c^2)/(2B^2 - c^2 - 2B - c)$, provided $2B^2 - c^2 - 2B - c \neq 0$. Hence, $\gamma = 0$ for at most $2q - 1$ pairs (b, c) , which are of the form $\{(0, c), c \neq -B\}$, or $\{(-(B^2 - c^2)/(2B^2 - c^2 - 2B - c), c), c \neq -B, 2B^2 - c^2 - 2B - c \neq 0\}$. For other pairs (b, c) , i.e., for at least $q(q - 1) - (2q - 1) = q^2 - 3q + 1$ pairs, $\gamma \neq 0$, and g takes equal values for every $t_1 \neq 0$ and $t_2 = \gamma/t_1$. Hence, for these (b, c) , g takes at most $(q - 1)/2$ distinct values. Therefore,

$$r_3([0, B, 0]) \leq (2q - 1)(q - 1) + (q^2 - 3q + 1)(q - 1)/2 < q^3 - 4q^2 + 8q - 6 = r_3([0, 0, 0]),$$

for all $q \geq 5$. This proved the second inequality of part (i) of Theorem 3.2 in this case.

Case 4 (i): Suppose $A \neq 0$.

We will show that in this case, for fixed $A, B, b, c \in \mathbb{F}_q$, $A \neq 0$, $c \neq Ab - B$, the expression $P_{A,B}(b, c; a)/(b - a)$, considered as a rational function of a on $\mathbb{F}_q \setminus \{b\}$, takes at most $q - 3$ distinct values. Then, by (8),

$$r_3([A, B, C]) \leq q(q - 1)(q - 3) = q^3 - 4q^2 + 3q < q^3 - 4q^2 + 8q - 6 = r_3([0, 0, 0]),$$

and this will end the proof of part (i) of Theorem 3.2.

Using (2), and $x = b - a$, it is easy to check that we can rewrite $P_{A,B}(b, c; a)/(b - a)$ in the form

$$\frac{P_{A,B}(b, c; a)}{b - a} = \alpha_3 x^3 + \alpha_2 x^2 + \alpha_1 x + \alpha_0 + \frac{\alpha_{-1}}{x} =: h(x),$$

where $\alpha_3 = A^2(Ab - B - c) \neq 0$, as $A \neq 0$ and $c \neq Ab - B$. The explicit expressions for α_i , $i = 2, 1, 0, -1$, as functions of A, B, b, c will not matter to us.

It is clear that the function h takes as many distinct values on \mathbb{F}^\times as the function j , obtained from h by dropping the constant term α_0 , and dividing all coefficients by the nonzero coefficient α_3 :

$$j(x) := x^3 + c_2 x^2 + c_1 x + \frac{c_{-1}}{x},$$

where, again, the explicit expressions for c_i , $i = 2, 1, -1$, will not matter to us.

As for each $t \in \mathbb{F}^\times$, $1/t = t^{q-2}$, the rational function $j : \mathbb{F}^\times \rightarrow \mathbb{F}$, can be represented by a polynomial function $j(x) = x^3 + c_2 x^2 + c_1 x + c_{-1} x^{q-2}$. The same polynomial $J = j = X^3 + c_2 X^2 + c_1 X + c_{-1} X^{q-2}$ can be used to define a function J on \mathbb{F} , by assuming that $J(0) = 0$ and $J(t) = j(t)$ for all $t \in \mathbb{F}^\times$. Hence, function j is a restriction of function J to \mathbb{F}^\times . For any function $f : \mathbb{F} \rightarrow \mathbb{F}$, let V_f denote the range of f , and $\#V_f = |V_f|$. Then $\#V_j \leq \#V_J$, and the inequality is strict if only if $0 \notin V_j$.

Our goal now is to prove that under certain conditions on q , $\#V_j \leq q - 3$. As was remarked at the beginning of Case 4, this will suffice to finish the proof of part (i) of Theorem 3.2.

If $f : \mathbb{F} \rightarrow \mathbb{F}$ is a bijection, then $V_f = \mathbb{F}$, $\#V_f = q$, and f is called a *permutation polynomial* (or PP) in \mathbb{F} .

Lemma 3.3. *Let $q \geq 17$, $q \equiv 1 \pmod{3}$, and $J = X^3 + c_2 X^2 + c_1 X + c_{-1} X^{q-2} \in \mathbb{F}[X]$. Then the following holds.*

1. J is not a PP.
2. $\#V_j \leq \#V_J \leq q - 2$. If, in addition, $0 \notin V_j$, then $\#V_j \leq q - 3$.

Proof. 1. We will need the following fact, often referred to as Hermite-Dickson Criterion (see Hermite [3], Dickson [2] or [7], [8]).

Proposition 3.4. (Hermite-Dickson) *Let p be the characteristic of $\mathbb{F} = \mathbb{F}_q$. A polynomial $f \in \mathbb{F}[X]$ is PP if and only if the following two conditions hold: (i) f has exactly one root in \mathbb{F} , and, (ii) for each integer t with $1 \leq t \leq q-2$ and $t \not\equiv 0 \pmod{p}$, the reduction of $(f(X))^t$ modulo $(X^q - X)$ has degree at most $q-2$.*

Let us show that the condition (ii) of Proposition 3.4 fails for our polynomial J . We can equate the coefficients at X^{q-1} in J^n modulo $(X^q - X)$, $n = 2, 3, 4$, to zero. This leads to the following system of equations:

$$2c_1c_{-1} = 0 \quad (\text{using } J^2) \quad (5)$$

$$3c_2c_{-1}^2 = 0 \quad (\text{using } J^3) \quad (6)$$

$$4c_{-1}^3 + 6c_1^2c_{-1}^2 = 0 \quad (\text{using } J^4) \quad (7)$$

We wish to remark that for $q < 17$, the coefficient at X^{q-1} in J^4 modulo $(X^q - X)$ takes different forms than in (7). This explains the condition $q \geq 17$.

For $p \geq 5$, if $c_{-1} \neq 0$, then (5) gives $c_1 = 0$ and (7) gives $c_{-1} = 0$, a contradiction. Therefore $c_{-1} = 0$ and $J = c_1X + c_2X^2 + X^3$ is a monic cubic polynomial. It is well known, see Dickson [2] or [7], [8], that for $q \equiv 1 \pmod{3}$, a cubic polynomial cannot be a PP. (Moreover, if $d > 1$ is a divisor of $q-1$, q being any prime power, then there is no PP of degree d .) Hence, J is not a PP.

Remark. If $q \equiv 0, 2 \pmod{3}$, there exist cubic PP's. In this case Theorem 3.2 still holds, but the proof becomes more subtle. As it does not affect our main Theorem 2.1, we decide not to pursue it here.

2. If J is not a PP, then $\#V_J \leq q-1$. The following result allows us to decrease the upper bound by 1.

Proposition 3.5. (Wan [11]) *If a polynomial f of degree $n \geq 1$ is not a PP of \mathbb{F} , then*

$$\#V_f \leq q - \left\lceil \frac{q-1}{n} \right\rceil.$$

As J has degree $q-2$ or 3 , and is not a PP of \mathbb{F} , Proposition 3.5, implies

$$\#V_J \leq q - \left\lceil \frac{q-1}{q-2} \right\rceil = q-2.$$

As $\#V_j \leq \#V_J$, if $0 \notin V_j$, then $\#V_j = \#V_J - 1 \leq q-3$. This ends the proof of Lemma 3.3. \square

What left is to analyze the case $\#V_j = q - 2$, as for $\#V_j \leq q - 3$ the theorem has been proven. So we assume that $\#V_j = q - 2$. Then $0 \in V_j = V_J$, and function j , having domain \mathbb{F}^\times , takes some value c exactly twice, and each other value exactly ones. Let $j(x_1) = j(x_2) = c$, $x_1 \neq x_2$. Then $\mathbb{F} \setminus V_j = \{a, b\}$, where a, b are distinct, and none of a or b is equal to c or to 0. Consider the following three polynomial functions on \mathbb{F} :

$$J_{a-c}(x) = \frac{\prod_{t \in \mathbb{F}^\times, t \neq x_1} (x - t)}{\prod_{t \in \mathbb{F}^\times, t \neq x_1} (x_1 - t)} (a-c) + J(x) - c, \quad J_{b-c}(x) = \frac{\prod_{t \in \mathbb{F}^\times, t \neq x_2} (x - t)}{\prod_{t \in \mathbb{F}^\times, t \neq x_2} (x_2 - t)} (b-c) + J(x) - c,$$

$$J_{a-c, b-c}(x) = \frac{\prod_{t \in \mathbb{F}^\times, t \neq x_1} (x - t)}{\prod_{t \in \mathbb{F}^\times, t \neq x_1} (x_1 - t)} (a - c) + \frac{\prod_{t \in \mathbb{F}^\times, t \neq x_2} (x - t)}{\prod_{t \in \mathbb{F}^\times, t \neq x_2} (x_1 - t)} (b - c) + J(x) - c.$$

As the product of all elements of \mathbb{F}^\times is -1 , we have:

$$J_{a-c}(x_1) = a - c, \quad J_{a-c}(x_2) = 0, \quad J_{a-c}(0) = (c - a)/x_1 - c,$$

$$J_{b-c}(x_1) = 0, \quad J_{b-c}(x_2) = b - c, \quad J_{b-c}(0) = (c - b)/x_2 - c,$$

$$J_{a-c, b-c}(x_1) = (c - a)/x_1, \quad J_{a-c, b-c}(x_2) = (c - b)/x_2, \quad J_{a-c, b-c}(0) = (c - a)/x_1 + (c - b)/x_2 - c.$$

The degrees of polynomials J_{a-c} , J_{b-c} , and $J_{a-c, b-c}$ are at most $q - 2$. If one of them takes exactly $q - 1$ values, then it is not a PP, and we get a contradiction with Theorem 3.5. Therefore each of these polynomials must take either $q - 2$ or q values.

For $t \notin \{0, x_1\}$, $J_{a-c}(t) = J(t) - c = j(t) - c$. This gives already $q - 2$ distinct values of J_{a-c} , each different from $a - c$. Hence, $\#V_{J_{a-c}} \geq q - 1$. So we must have $\#V_{J_{a-c}} = q$. This is possible if and only if $J_{a-c}(0) = (c - a)/x_1 - c = b - c$, or equivalently, $(c - a)/x_1 = b$.

Similarly we conclude that $\#V_{J_{b-c}} = \#V_{J_{a-c, b-c}} = q$, which happens if and only if $J_{b-c}(0) = (c - b)/x_2 = a$, and $J_{a-c, b-c}(0) = (c - a)/x_1 + (c - b)/x_2 - c = 0$. Therefore, the following three equalities must be satisfied simultaneously:

$$(c - a)/x_1 = b, \quad (c - b)/x_2 = a, \quad (c - a)/x_1 + (c - b)/x_2 - c = 0.$$

From the first and the third equalities, we obtain $(c - b)/x_2 = c - b$, and from the second and the third equalities, we get $(c - a)/x_1 = c - a$. As c is distinct from a and from b , we obtain $x_1 = x_2 = 1$, which contradicts the assumption that $x_1 \neq x_2$. Hence, $\#V_j \leq q - 3$. This ends the proof of part (i) of Theorem 3.2.

Our proof of part (ii) of Theorem 3.2 is very similar to the one of part (i), and so we will proceed through it a bit faster. In order to prove part (ii), due to the translation

automorphisms on the third coordinates of vertices of R , it is sufficient to consider points $(A, B, 0)$ only. Let

$$(A, B, 0) \sim [x, *, *] \sim (a, *, *) \sim [y, Ax - ax + ay - B, *]$$

be a path of length 3 from the the point $(A, B, 0)$. Hence, $A \neq a$ and $x \neq y$. Let $z = Ax - ax + ay - B$. Then $a = (Ax - B - z)/(x - y)$, and the condition $A \neq a$ is equivalent to $(z \neq Ay - B$ and $x \neq y)$. Substituting this expression for a to $[y, Ax - ax + ay - B, *]$, and then setting $x = y + 1/t$, $t \neq 0$, we obtain the following representation of $R^3((A, B, 0))$:

$$R^3((A, B, 0)) = \left\{ [y, z, Q_{A,B}(y, z; t)] : y, z, t \in \mathbb{F}, z \neq Ay - B, t \neq 0 \right\}, \quad (8)$$

where $Q_{A,B}(y, z; t)$, viewed as a function of t with the constant addend dropped, is of the form $j(t) = c_3 t^3 + c_2 t^2 + c_1 t + c_{-1}/t$, with

$$c_3 = -y^2(Ay - B - z)^4 \quad \text{and} \quad c_{-1} = A(Ay - B - z)((A^2 + A)y + (B - z + 1)A + B - z).$$

As $z \neq Ay - B$, we continue our analysis by considering cases: $A = 0$ and $A \neq 0$.

Case 5 (ii): $A = 0$

For $y = 0$ and $z \neq B$, we arrive to considering $\#V_j$ for $j(t) = z(1 - z)t$. For $z(1 - z) \neq 0$ and $z \neq B$, j takes at most $q - 1$ values. As there are at most $q - 3$ such values of z , there at most $q - 3$ pairs $(0, z)$ for which j takes $q - 1$ values. Their total contribution to $r_3((0, B, 0))$ is at most $(q - 1)(q - 3)$.

If $z(1 - z) = 0$, and $z \neq B$, then z can take at most 2 values, and so each of the corresponding pairs $(0, z)$ contributes at most 1 to $r_3((0, B, 0))$.

Therefore, the contribution of pairs $(0, z)$ to $r_3((0, B, 0))$ is at most

$$(q - 1)(q - 3) + 2 = q^2 - 4q + 5.$$

Suppose now that $y \neq 0$. Then we need to estimate $\#V_j$, where j is a monic cubic polynomial of $t \in \mathbb{F}^\times$. As it is not a PP ($q \equiv 1 \pmod{3}$), $\#V_j \leq (2q + 1)/3$. As there are at most $q(q - 1)$ pairs (y, z) , their total contribution in $r_3((0, B, 0))$ is at most at most $q(q + 1)(2q + 1)/3$,

Therefore,

$$r_3((0, B, 0)) \leq q^2 - 4q + 5 + q(q + 1)(2q + 1)/3 < q^3 - 4q^2 + 8q - 6 = r_3([0, 0, 0]),$$

for any $q \geq 5$, and part (ii) of Theorem 3.2 is proven in this case.

Case 6 (ii): $A \neq 0$

If $y = 0$, we arrive to the investigation of $\#V_j$ for

$$j(t) = -z(z-1)t + (AB + A + B - (A+1)z)/t.$$

For $z(z-1) \neq 0$, it is reduced to investigating the range of the function of the form $j(t) = t + \gamma/t$, with $\gamma = (AB + A + B - (A+1)z)/((B+z)z(1-z))$. In this case we proceed as in Case 3, noting that for $\gamma \neq 0$, the values of j at t and at γ/t are equal. There are at most $q-2$ values of z such that $z+B \neq 0$ and $\gamma \neq 0$. For each of them there are at most $(q-1)/2$ values of j . Now, $\gamma = 0$ for at most 1 value of z , and for this z , j takes at most $q-1$ values. Hence, the contribution of all such pairs $(0, z)$ to $r_3((A, B, 0))$ is at most $(q-2)(q-1)/2 + (q-1)$.

If $z(z-1) = 0$, then $z = 0$ (and so $B \neq 0$) or $z = 1$ (and so $B+1 \neq 0$). In these cases, we obtain that $j(t) = (AB + A + B)/t$ or $(AB + B - 1)/t$, and so it takes either 1 or at most $q-1$ values, depending on the numerators being 0 or not. This contributes to at most $2 + 2(q-1)$ lines in $R^3((A, B, 0))$.

If $y \neq 0$, then dividing $j(t)$ by c_3 and dropping the constant term, leads to estimating $\#V_j$ of the form $j(t) = t^3 + c_2t^2 + c_1t + c_{-1}/t$, $t \neq 0$, with

$$c_{-1} = A(A^2y + AB + Ay - Az + A + B - z)/((Ay - B - z)^3y^2).$$

If $c_{-1} = 0$, then j is a monic cubic polynomial of t . If $c_{-1} \neq 0$, we proceed as we did in Case 4, and conclude that $\#V_j \leq q-3$. Hence, the contribution of at most $(q-1)^2$ pairs (y, z) into $r_3((A, B, 0))$ is at most $(q-1)^2(q-3)$.

Combining all our findings, we obtain

$$\begin{aligned} r_3((A, B, 0)) &\leq (q-2)(q-1)/2 + (q-1) + 2 + 2(q-1) + (q-1)^2(q-3) < \\ &q^3 - 4q^2 + 8q - 6 = r_3([0, 0, 0]), \end{aligned}$$

for all $q \geq 3$. This ends the proof of part (ii) of Theorem 3.2, and so of the theorem. \square

An immediate corollary of part (ii) of Theorem 3.2 is that a line (point) of R cannot be mapped to a point (line) of R by any automorphism of R . It will be used in the next section.

Corollary 3.6. *Let $q \equiv 1 \pmod{3}$. For every automorphism ϕ of R , $\phi(P) = P$ and $\phi(L) = L$.*

4 Proof of Theorem 2.1

Though Theorem 2.1 is stated for q prime, the requirement for q to be prime is only utilized at the end for the conditions of Corollary 4.11 to be met. At the same time, many of the statements we prove to establish Theorem 2.1 are true for odd prime powers $q \equiv 1 \pmod{3}$. Therefore, in all of the following statements we assume that q satisfies these conditions without repeating it each time and R is defined over \mathbb{F}_q . In the following lemma, we collect some observations about the distance between specified vertices.

Lemma 4.1. *The following holds in R :*

- (i) *Any two vertices of R at distance 2, have distinct first components.*
- (ii) *For $b \neq c$, the points $(0, b, r)$ and $(0, c, s)$ in R are at distance 4.*
- (iii) *For $r \neq s$, the lines $[x, y, r]$ and $[x, y, s]$ (or points (x, y, r) and (x, y, s)) are at distance at least 6.*

Proof. (i) If two vertices are at distance 2, then they are distinct neighbors of another vertex. If their first components are equal, then the definition of the adjacency in R implies that the second and third components are equal, a contradiction.

(ii) By part (i), the points $(0, b, r)$ and $(0, c, s)$, where $b \neq c$, cannot be at distance 2. Choose m such that $m \neq 0, -1$ and $m^2 \neq (s - r)/(c - b)$. As $q \geq 5$, such an m is guaranteed to exist. Then it is easy to verify that the following adjacencies define a path of length 4 between the given points:

$$(0, b, r) \sim [(m - b)/z, -b, -r] \sim (z, m, (m - b)m((m + 1)z + m) + r) = \\ (z, m, (m - c)m((m + 1)z + m) + s) \sim [(m - c)/z, -c, -s] \sim (0, c, s),$$

where

$$z = \left(\frac{s - r}{b - c} - m^2 \right) / (m^2 + m)$$

makes the third component of the middle points equal and guarantees $z \neq 0$.

(iii) We will show that these two lines (two points) are not at distance two or distance four from each other. Clearly, they are not at distance 2 by part (i).

Suppose the two lines are at distance 4. Then

$$[x, y, r] \sim (z, zx-y, *) \sim [\alpha, \alpha z - zx + y, *] = [\alpha, \alpha w - wx + y, *] \sim (w, wx-y, *) \sim [x, y, s],$$

with $w \neq z$ and $x \neq \alpha$. Then $\alpha z - zx + y = \alpha w - wx + y$, which is equivalent to $(z - w)(\alpha - x) = 0$, a contradiction. Thus $[x, y, r]$ and $[x, y, s]$ are at distance at least 6. Since $f_2(p_1, \ell_1) = p_1 \ell_1$ is symmetric with respect to p_1 and ℓ_1 , then the same exact argument works for points of the same form. This ends the proof. We wish to comment again that in [9] the diameter of R was shown to be 6 for odd $q \geq 5$. \square

Denote $\text{Aut}(R)$ by G , and let $\phi \in G$. To simplify notation, instead of $\phi([x, y, z])$ we will just write $\phi[x, y, z]$, similarly $\phi((x, y, z)) = \phi(x, y, z)$. By Corollary 3.6, G acts on the set of lines and the set of points of R , so then we may write,

$$\begin{aligned} \phi[x, y, z] &= [\lambda_1(x, y, z), \lambda_2(x, y, z), \lambda_3(x, y, z)], \\ \phi(x, y, z) &= (\pi_1(x, y, z), \pi_2(x, y, z), \pi_3(x, y, z)), \end{aligned}$$

where λ_i and π_i are component functions of ϕ . The notation λ_i and π_i will remind us that they correspond to the action of ϕ on lines and on points. From here on, we will assume that λ_i and π_i implicitly depend on ϕ .

For a fixed $a \in \mathbb{F}$, the following sets will play an important role in our arguments:

$$L_a = \{[0, a, r] : r \in \mathbb{F}\} \quad \text{and} \quad P_a = \{(0, a, r) : r \in \mathbb{F}\}.$$

An immediate corollary of Theorem 3.2 is as follows.

Lemma 4.2. *G acts on L_0 and L_1 .*

The goal of the following statements is to ultimately prove that the action of any $\phi \in G$ on any component is determined only by that component. Meaning, that λ_i and π_i for $1 \leq i \leq 3$, can be reduced to a single variable function. For these new single variable functions, we will use the same notation, that is $\lambda_i(v_1, v_2, v_3) = \lambda_i(v_i)$ and $\pi_i(v_1, v_2, v_3) = \pi_i(v_i)$.

Lemma 4.3. *G acts on P_0 .*

Proof. Let $r \in \mathbb{F}$. For each $x \in \mathbb{F}^\times$, consider the path

$$[0, 1, r] \sim (x, -1, -r) \sim [-x^{-1}, 0, r - 1] \sim (0, 0, -r + 1) \sim [0, 0, r - 1]. \quad (9)$$

Let ϕ be in G . By Lemma 4.2, we have that $\phi[0, 1, r] = [0, 1, w]$ and $\phi[0, 0, r-1] = [0, 0, s]$ for some $w, s \in \mathbb{F}$. Then applying ϕ to (9) yields

$$[0, 1, w] \sim (x', -1, -w) \sim [y', x'y' + 1, x'y' + w] = [y', zy', s] \sim (z, 0, -s) \sim [0, 0, s], \quad (10)$$

where $y' \in \mathbb{F}^\times$.

As $\phi(0, 0, -r+1) = (z, 0, -s)$, then ϕ maps $R^1((0, 0, -r+1))$ to $R^1((z, 0, -s))$. As $-x^{-1}$ ranges over \mathbb{F}^\times in (9), then y' ranges over \mathbb{F}^\times . Comparing the second and the third components in the equality in (10) we obtain that

$$zy' = x'y' + 1 \quad \text{and} \quad zy' - 1 + w = s, \quad (11)$$

which implies $zy' - 1 + w - s = 0$ for every $y' \in \mathbb{F}^\times$. As z, w, s here are fixed, this implies that $z = 0$ and consequently $s = w - 1$, so $\phi[0, 0, r-1] = [0, 0, w-1]$. \square

The following is an immediate corollary of the proof above.

Corollary 4.4. *Let $r \in \mathbb{F}$. If $\phi[0, 1, r] = [0, 1, w]$, then $\phi[0, 0, r-1] = [0, 0, w-1]$.*

Using the fact that G acts on P_0 , we now demonstrate that the action of any $\phi \in G$ on the second component of points $(0, a, r) \in P_a$ independent of r .

Lemma 4.5. *Let $\phi \in G$. Then for every $a \in \mathbb{F}$, there exists $b \in \mathbb{F}$ such that $\phi(P_a) = P_b$.*

Proof. Let $r \in \mathbb{F}$ and $\psi = \psi_r$ belong to the stabilizer of $[0, 0, -r]$ in G . Since G acts on P_0 and ψ fixes $[0, 0, -r]$, then ψ must fix $(0, 0, r) \in R^1([0, 0, -r])$. This implies that ψ fixes

$$F_r = \{(x, 0, r) : x \in \mathbb{F}^\times\} = R^1([0, 0, -r]) \setminus \{(0, 0, r)\}.$$

In order to prove our assertion, we will use the intersection of the 2-neighborhoods of every point in F_r . Namely,

$$N_r = \bigcap_{v \in F_r} R^2(v).$$

Let $v = (x, 0, r) \in F_r$. Any point in $R^2(v)$ cannot have its first component equal to x . As x ranges over \mathbb{F}^\times , then N_r can only have points whose first component is 0. This immediately implies that the third component of any point in N_r must be r . The second component can take any value in \mathbb{F} , since for any $x, a \in \mathbb{F}$, we have a 2-path

$$(x, 0, r) \sim [-a/x, -a, -r] \sim (0, a, r).$$

Thus

$$N_r = \{(0, a, r) : a \in \mathbb{F}\}.$$

Since ψ fixes F_r , then ψ fixes N_r . Therefore, for any $a \in \mathbb{F}$, there exists $b \in \mathbb{F}$ such that $\psi(0, a, r) = (0, b, r)$.

Now, let $\phi \in G$ and $r \in \mathbb{F}$. As ϕ fixes L_0 , then $\phi[0, 0, -r] = [0, 0, -r']$. Therefore, $t_{r-r'}\phi[0, 0, -r] = [0, 0, -r]$, i.e. $t_{r-r'}\phi$ stabilizes $[0, 0, -r]$. Thus, from the above we have that for any $a \in \mathbb{F}$, there exists $b \in \mathbb{F}$ such that $t_{r-r'}\phi(0, a, r) = (0, b, r)$. Therefore, $\phi(0, a, r) = (0, b, r')$. It is conceivable that b may depend on both a , and r , but the following argument demonstrates this is not the case.

Recall that Lemma 4.1 states that $(0, a, r)$ and $(0, a, s)$ are at distance at least 6 from one another when $r \neq s$. Therefore, their images under ϕ must also be at distance at least 6. Suppose that

$$\phi(0, a, r) = (0, b, r') \quad \text{and} \quad \phi(0, a, s) = (0, c, s').$$

According to Lemma 4.1(ii), $(0, b, r')$ and $(0, c, s')$ are at distance 4 if $b \neq c$, and so we must have $b = c$. Thus $\phi(P_a) \subset P_b$ and as $|P_a| = |P_b|$, we must have $\phi(P_a) = P_b$. \square

Lemma 4.6. *Let $\phi \in G$. Then λ_i and π_i where $i = 2, 3$ depend only on the i th component of a vertex. Furthermore, $\lambda_1(0) = 0$, $\pi_2(-a) = -\lambda_2(a)$, and $\pi_3(-r) = -\lambda_3(r)$ for all $a, r \in \mathbb{F}$.*

Proof. The logic of the proof is as follows. First we show that $\pi_3(0, a, r) = \pi_3(r)$ for all $a, r \in \mathbb{F}$. Then we use this fact to demonstrate our assertion for λ_2 and λ_3 . This will imply that $\lambda_1(0, a, r) = \lambda_1(0) = 0$ for all $a, r \in \mathbb{F}$, which in turn will allow us to prove the assertion for π_2 and π_3 .

In the proof of Lemma 4.5 we demonstrated that if $\phi[0, 0, -r] = [0, 0, -r']$ (which is true by Lemma 4.2), then for every $a \in \mathbb{F}$, there exists $b \in \mathbb{F}$ such that $\phi(0, a, r) = (0, b, r')$. Note that here r' does not depend on a , which demonstrates that $\pi_3(0, a, r) = r' = \pi_3(r)$, for any $a \in \mathbb{F}$.

By Lemma 4.5, $\pi_2(0, a, r) = \pi_2(a)$, and by the paragraph above $\pi_3(0, a, r) = \pi_3(r)$. Since $[x, -a, -r] \sim (0, a, r)$, then $\phi[x, -a, -r] \sim \phi(0, a, r) = (0, \pi_2(a), \pi_3(r))$. This adjacency implies that for any $x, a, r \in \mathbb{F}$, $\lambda_2(x, -a, -r) = -\pi_2(a)$ and $\lambda_3(x, -a, -r) = -\pi_3(r)$. This proves the assertion about λ_2 and λ_3 . Hence, from here on we can write $\lambda_2(x, a, r)$ as $\lambda_2(a)$ and $\lambda_3(x, a, r)$ as $\lambda_3(r)$.

Now we show that $\lambda_1(0, a, r) = 0$. By Lemma 4.1(ii) We know that $[0, 0, r]$ and $[0, a, r]$ for $a \neq 0$ are at distance 4. Since G acts on L_0 by Lemma 4.2, then $\phi[0, 0, r] = [0, 0, \lambda_3(r)]$. Hence, $\phi[0, a, r] = [\lambda_1(0, a, r), \lambda_2(a), \lambda_3(r)]$ must be at distance 4 from $[0, 0, \lambda_3(r)]$. If $\lambda_1(0, a, r) = x' \neq 0$, then the following path shows that $\phi[0, 0, r]$ and $\phi[0, a, r]$ are at distance 2:

$$[0, 0, \lambda_3(r)] \sim (\lambda_2(a)/x', 0, -\lambda_3(r)) \sim [x', \lambda_2(a), \lambda_3(r)].$$

Thus $\lambda_1(0, a, r) = x' = 0$.

We now have that $\phi[0, a, r] = [0, \lambda_2(a), \lambda_3(r)]$ for any $a, r \in \mathbb{F}$. As $(x, -a, -r) \sim [0, a, r]$ for any $x \in \mathbb{F}$, $\phi(x, -a, -r) \sim \phi[0, a, r] = [0, \lambda_2(a), \lambda_3(r)]$. Thus by the adjacency relations, $\pi_2(x, -a, -r) = -\lambda_2(a)$ and $\pi_3(x, -a, -r) = -\lambda_3(r)$. Hence, from here on we can write $\pi_2(x, a, r)$ as $\pi_2(a)$ and $\pi_3(x, a, r)$ as $\pi_3(r)$. Furthermore, we obtain

$$\pi_3(-a) = -\lambda_3(a) \quad \text{and} \quad \pi_3(-r) = -\lambda_3(r). \quad (12)$$

□

We now show some consequences of these results. In particular, we will demonstrate that $\lambda_2(a) = a = \pi_2(a)$ for all $a \in \mathbb{F}_p \subset \mathbb{F}$.

Lemma 4.7. *Let $\phi \in G$. Suppose there exists an $r \in \mathbb{F}$ such that $\lambda_3(r) = r$. Then $\lambda_3(r - k) = r - k$ for all $k \in \mathbb{F}_p$.*

Proof. Corollary 4.4 states that if $\phi[0, 1, r] = [0, 1, r]$, then $\phi[0, 0, r - 1] = [0, 0, r - 1]$. But since λ_3 is only dependent on r , this implies that if $\lambda_3(r) = r$, then $\lambda_3(r - 1) = r - 1$. Therefore, by applying this iteratively, we obtain that $\lambda_3(r - k) = r - k$ for any $k \in \mathbb{F}_p$. □

Lemma 4.8. *Let $\phi \in G$. Then, $\lambda_2(a) = \pi_2(a) = a$ for any $a \in \mathbb{F}_p \subset \mathbb{F}$.*

Proof. The entire proof rests on observing that for a fixed $b \in \mathbb{F}_p$, the lines $[0, 0, b]$ and $[0, 1, 0]$ have a special intersection of their 2-neighborhoods, namely, $\{[x, b+1, b] : x \in \mathbb{F}^\times\}$.

Without loss of generality, we will assume that $\pi_3(0) = 0$. If not, we may consider an alternate automorphism by composing ϕ with t_m for some $m \in \mathbb{F}$. Since t_m has no effect on the second component, then the claimed result holds for ϕ if and only if it holds for $t_m\phi$.

By Lemma 4.7, ϕ fixes $[0, 1, 0]$ and $[0, 0, b]$ since $b \in \mathbb{F}_p$. Note that

$$R^2[0, 0, b] = \{[x, xy, b] : x, y \in \mathbb{F}, x \neq 0\} \quad \text{and} \quad R^2[0, 1, 0] = \{[x, xz+1, xz] : x, z \in \mathbb{F}, x \neq 0\}.$$

Let $I_b = R^2[0, 1, 0] \cap R^2[0, 0, b]$. For any line in I_b with first component x , we must have $xz + 1 = xy$ and $xz = b$. Therefore

$$I_b = \{[x, b + 1, b] : x \in \mathbb{F}^\times\}.$$

Since ϕ fixes both $[0, 0, b]$ and $[0, 1, 0]$, then $\phi(I_b) = I_b$. Thus $\lambda_2(b + 1) = b + 1$ by Lemma 4.6. Consequently, ϕ fixes $(0, -(b + 1), -b)$ because ϕ fixes its neighborhood

$$R^1(0, -(b + 1), -b) = I_b \cup \{[0, b + 1, b]\}.$$

Thus, by Lemma 4.6 and the above, we have $\pi_2(-b - 1) = -b - 1 = -\lambda_2(b + 1)$. As b was an arbitrary element of $\mathbb{F}_p \subset \mathbb{F}$, we obtain the claimed result. \square

Lemma 4.9. *Let $\phi \in G$ such that $\lambda_2(a) = a$ for all $a \in \mathbb{F}$. Then $\pi_2(a) = a$ for all $a \in \mathbb{F}$, and there exists $b \in \mathbb{F}$ such that $\lambda_3(r) = r + b = \pi_3(r)$ for all $r \in \mathbb{F}$.*

Proof. If $\lambda_2(a) = a$ for all $a \in \mathbb{F}$, then $\pi_2(a) = -\lambda_2(-a) = -(-a) = a$ by (12). If $\lambda_3(0) = b$, then consider $\phi' = t_{-b}\phi$, so that $\lambda'_3(0) = 0$. By Lemma 4.7, we have that $\lambda'_3(r) = r$ for all $r \in \mathbb{F}_p$. Then for $x \neq 0$ and $r \notin \mathbb{F}_p$ (so $r \neq 1$), consider the path:

$$[0, 0, 0] \sim (x, 0, 0) \sim [(-r + 1)/x, -r + 1, 0] \sim (xr/(r - 1), -1, -r) \sim [0, 1, r]. \quad (13)$$

Keeping in mind that λ'_2 is the identity map (as t_{-b} does not affect the first two components) and $\lambda'_3(0) = 0$, we apply ϕ' to (13). Then $\phi'[0, 0, 0] = [0, 0, \lambda'_3(0)] = [0, 0, 0]$ and $\phi'[0, 1, r] = [0, 1, s]$ by Lemma 4.2. Hence, the image of the path in (13) is:

$$[0, 0, 0] \sim (x', 0, 0) \sim [y', -r + 1, 0] \sim (z', -1, -s) \sim [0, 1, s],$$

where the existence of x', y', z' is guaranteed as ϕ' is an automorphism. Hence,

$$(-r + 1) - 1 = y'z' \quad \text{and} \quad y'z' = -s.$$

This implies $r = s$. Thus $\phi'[0, 1, r] = [0, 1, r]$ for every $r \in \mathbb{F}$. Therefore $\lambda'_3(r) = r$ for every $r \in \mathbb{F}$. If $\lambda'_3(r) = r$ for all $r \in \mathbb{F}$, then $\pi_3(r) = r$ for all $r \in \mathbb{F}$ again by (12). Since $\phi = t_b\phi'$, then $\lambda_3(r) = \lambda'_3(r) + b = r + b$ and $\pi_3(r) = \pi'_3(r) - b = r + b$. \square

Lemma 4.10. *Let $\phi \in G$ such that $\lambda_2(a) = a$ for all $a \in \mathbb{F}$. Then $\lambda_1(x) = x = \pi_1(x)$ for all $x \in \mathbb{F}$.*

Proof. By Lemma 4.9, we may assume that there exists $b \in \mathbb{F}$ such that $\phi' = t_{-b}\phi$ has $\lambda_2'(a) = a = \pi_2'(a)$ for all $a \in \mathbb{F}$ and $\lambda_3'(r) = r = \pi_3'(r)$ for all $r \in \mathbb{F}$. We will demonstrate that as a result ϕ' is the identity automorphism, and therefore $\phi = t_b$.

Consider the following path for every $x, z \in \mathbb{F}^\times$:

$$(0, a, r) \sim [x, -a, -r] \sim (z, zx + a, xz(zx + a)(z + zx + a + z(zx + a)) + r)$$

As $\phi'(0, a, r) = (0, a, r)$, then applying ϕ' to this path yields:

$$(0, a, r) \sim [x', -a, -r] \sim (z', z'x' + a, x'z'(z'x' + a)(z' + z'x' + a + z'(z'x' + a)) + r).$$

Our goal is to prove that $x' = x$. This will imply that ϕ' fixes $[x, -a, -r]$ and therefore acts as the identity on the set of lines of R .

Since the second and the third components of every vertex are fixed by ϕ' , we obtain

$$\begin{aligned} zx &= z'x' \\ x'z'(z'x' + a)(z' + z'x' + a + z'(z'x' + a)) &= xz(zx + a)(z + zx + a + z(zx + a)). \end{aligned}$$

As $zx \neq 0$, then for $z \neq -a/x$, the above equation can be reduced to

$$z'(1 + zx + a) = z(1 + zx + a). \quad (14)$$

If $1 + zx + a \neq 0$, then (14) implies $z = z'$. Clearly, this inequality holds if $z \neq -(a+1)/x$. Thus $z = z'$ when $z \neq 0, -a/x, -(a+1)/x$. Therefore, for $q \geq 4$, there is at least one value of z for which $z = z' \neq 0$. Since we know $zx = z'x'$, then $x = x'$. Therefore, ϕ' must fix $[x, -a, -r]$. Since the choice of x was arbitrary, as was the choice of a and r , then $\lambda_1(x, a, r) = x$, so that ϕ' acts as the identity on the lines of R . Since ϕ' fixes every line in R , clearly it must fix every point, so that ϕ' is the identity automorphism. Therefore, $\pi_1(x, a, r) = x$. Thus $\phi = t_b\phi' = t_b$ as claimed. \square

The last sentence in the proof above implies the following corollary.

Corollary 4.11. *Let $\phi \in G$, and $\lambda_2(a) = a$ for all $a \in \mathbb{F}$, then $\phi = t_b$ for some $b \in \mathbb{F}$.*

When q is prime, then $\mathbb{F} = \mathbb{F}_p$. By Lemma 4.8, we have that $\lambda_2(a) = a$ for all $a \in \mathbb{F}$. Therefore, all the conditions of Corollary 4.11 are satisfied in this case, and the proof of Theorem 2.1 is complete. \square

5 Concluding remarks

We would like to note that for odd prime powers $q = p^e$, each of the groups $Aut(\Gamma_i)$, $i = 2, 3$, contains a cyclic subgroup of order e related to the Frobenius automorphism of the field \mathbb{F} , namely $\phi_p : (p_1, p_2, p_3) \mapsto (p_1^p, p_2^p, p_3^p)$ and $[l_1, l_2, l_3] \mapsto [l_1^p, l_2^p, l_3^p]$. This implies that $Aut(\Gamma_i)$ contains a subgroup of order eq^{4-i} , that is a semidirect product of $(\mathbb{F}^{4-i}, +)$ and $\langle \phi_p \rangle$. In fact, this subgroup seems to be the whole $Aut(\Gamma_i)$, and this was verified by computer for all odd prime powers q , $q \leq 41$.

Conjecture 5.1. ([9]) *For all odd prime powers q , $|Aut(R)| = eq$.*

We would like to conclude this paper with the following problem that is analogous to Question 1 in the case where \mathbb{F} is infinite. Clearly, methods used in this paper will not work in this case. For example, if $\mathbb{F} = \mathbb{R}$ – the field of real numbers, additive groups $(\mathbb{R}, +)$ and $(\mathbb{R}^2, +)$ are isomorphic, which can be shown by using a Hamel basis of the vector space \mathbb{R} over the field of rational numbers \mathbb{Q} .

Problem 5.2. *Let \mathbb{F} be an infinite field. Is there a graph $\Gamma_3 = \Gamma_{\mathbb{F}}(f(p_1, l_1), g(p_1, p_2, l_1))$ that is not isomorphic to a graph $\Gamma_2 = \Gamma_{\mathbb{F}}(f(p_1, l_1), h(p_1, l_1))$, where f , g and h are polynomial functions? Does the answer to this question change if we allow the functions f , g and h to be arbitrary functions on \mathbb{F} ?*

Let $q = p^e$ be an odd prime power, $q \geq 5$. The graph $\Gamma = \Gamma_{\mathbb{F}_q}(p_1 l_1)$ is sometimes referred to as the bi-affine part of the point-line incidence graph of the classical projective plane of order q . The graph $\Gamma_3 = \Gamma_{\mathbb{F}_q}(p_1 l_1, g(p_1, l_1, p_2))$ is a q -lift of $\Gamma_{\mathbb{F}_q}(p_1 l_1)$. Sometimes $|Aut(\Gamma_3)|$ is larger than $|Aut(\Gamma)| = 2eq^3(q-1)^2$, see [10]. For example, when $g = p_1 l_2$, $|Aut(\Gamma_3)| = eq^4(q-1)^2$, see [10]. In this paper we showed that when $q = p$ and $p \equiv 1 \pmod{3}$, $|Aut(R)| = p$, demonstrating that at other times, a q -lift of Γ can have an automorphism group with much smaller order. This motivates the following problem.

Problem 5.3. *Let \mathbb{F}_q be the finite field of q elements. Describe all possible groups $Aut(\Gamma_{\mathbb{F}_q}(p_1 l_1, g(p_1, l_1, p_2)))$.*

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7 Appendix

Maple Code for finding the 3-neighborhood of a vertex of R

```
#This program builds a path from a vertex of graph R using the first
#components of the vertices in the path.

restart;

#Given a line, this procedure finds the neighbor of the line with given first component.

nl := proc (line::list, b::algebraic) local nbl, f2, f3, p, l, l1, l2, l3, p1, p2, p3;
l1 := line[1]; l2 := line[2]; l3 := line[3];
f2 := (x1, y1) → x1*y1;
f3 := (x1, x2, y1, y2) → x1*x2*l1*(x1+x2+x1*x2);
nbl := solve({p2+l2 = f2(p1, l1), p3+l3 = f3(p1, p2, l1, l2), p1 = b}, {p1, p2, p3});
p := [subs(nbl, p1), subs(nbl, p2), subs(nbl, p3)];
end:

#Given a point, this procedure finds the neighbor of the point with given first component.

np := proc (point::list, a::algebraic) local nbp, f2, f3, p, l, l1, l2, l3, p1, p2, p3;
p1 := point[1]; p2 := point[2]; p3 := point[3];
f2 := (x1, y1) → x1*y1;
f3 := proc (x1, x2, y1, y2) → x1*x2*l1*(x1+x2+x1*x2);
nbp := solve({p2+l2 = f2(p1, l1), p3+l3 = f3(p1, p2, l1, l2), l1 = a}, {l1, l2, l3});
l := [subs(nbp, l1), subs(nbp, l2), subs(nbp, l3)];
end:

#A 3-Path the begins at line [A, B, 0]
#
L1 := [A, B, 0];
P1 := nl(L1, a);
L2 := factor(np(P1, x));
P2 := factor(nl(L2, b));
print();
```

```

#A 3-Path the begins at point (A, B, 0)
#
#P1 := [A, B, 0];
#L1 := np(P1, x);
#P2 := factor(nl(L1, a));
#L2 := factor(np(P2, y));
#print();

#PAB below stands for P_{A, B}(b, c; a)
#
PAB := simplify(subs({x = (-A*a+B+c)/(b-a)}, P2));

#3-neighborhoods of lines [0, 0, 0] and [0, 1, 0]
#
subs({A=0,B=0},PAB);
subs({A = 0, B = 1}, PAB);

```

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