$Recall:$ ¹

- 1. Some facts:
	- (a) For a differentiable function f, curl(∇f) = 0
	- (b) If \vec{F} is conservative, then curl $\vec{F} = 0$.
	- (c) If \vec{F} is a vector field defined on all of \mathbb{R}^3 and curl $\vec{F} = 0$, then \vec{F} is a conservative vector field.
	- (d) If $\vec{F} = P\vec{i} + Q\vec{j} + R\vec{k}$ is a vector field on \mathbb{R}^3 , then

$$
\operatorname{div}(\operatorname{curl} \vec{F}) = 0
$$

2. The **curl** of a vector field $F = P\vec{i} + Q\vec{j} + R\vec{k}$ is given as

$$
\operatorname{curl} \vec{F} = \nabla \times \vec{F} = \det \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ P & Q & R \end{bmatrix} =
$$

$$
= \left(\frac{\partial R}{\partial y} - \frac{\partial Q}{\partial z}\right)\vec{i} + \left(\frac{\partial P}{\partial z} - \frac{\partial R}{\partial x}\right)\vec{j} + \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y}\right)\vec{k}
$$

3. The **divergence** of a vector field $\vec{F} = P\vec{i} + Q\vec{j} + R\vec{k}$ is given as

$$
\mathrm{div}\vec{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} = \nabla \cdot \vec{F}
$$

4. (Surface Integrals of a vector field) If \vec{F} is a continuous vector field defined on an oriented surface S with unit normal \vec{n} , then the surface integral of \vec{F} over \boldsymbol{S} is

$$
\int \int_{S} \vec{F} \cdot d\vec{S} = \int \int_{S} \vec{F} \cdot \vec{n} dS
$$

This integral (on the left side of the equality) is also called the $\hat{H}ux$ of \vec{F} across S. Remember that flux means the rate at which \vec{F} flows through S.

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5. (Surface Integrals of a vector field continued) If we parameterize S by $\vec{r}(u, v)$ with parameter domain D, then the unit normal \vec{n} is given by $\vec{n} = \frac{\vec{r}_u \times \vec{r}_v}{|\vec{r}_v \times \vec{r}_v|}$ $|\vec{r}_u \times \vec{r}_v|$ and the surface integral of a vector field F over a surface S is then given by

$$
\int \int_S \vec{F} \cdot d\vec{S} = \int \int_D \vec{F}(\vec{r}(u,v)) \cdot (\vec{r}_u \times \vec{r}_v) dA.
$$

THIS IS THE FORMULA YOU WANT TO USE TO COMPUTE SURFACE INTEGRALS OF VECTOR FIELDS.

6.

Theorem 1. (Stokes' Theorem) Let S be an oriented piecewise-smooth surface that is bounded by a simple, closed, piecewise-smooth boundary curve C with positive orientation. Let \vec{F} be a vector field whose components have continuous partial derivatives on an open region in \mathbb{R}^3 that contains S. Then

$$
\int_C \vec{F} \cdot d\vec{r} = \int \int_S curl \vec{F} \cdot d\vec{S}
$$

7.

Theorem 2. (Divergence Theorem) Let D be a simple solid region and let S be the boundary surface of D, given with positive outward orientation. Let \vec{F} be a vector field whose component functions have continuous partial derivatives on an open region that contains D. Then

$$
\int \int_S \vec{F} \cdot d\vec{S} = \int \int \int_D \operatorname{div} \vec{F} dV
$$

1 Stokes' and Divergence Theorem Examples:

Problem 1. Evaluate

$$
\int_C \vec{F} \cdot d\vec{r}
$$

where $\vec{F}(x, y, z) = (x + y^2)\vec{i} + (y + z^2)\vec{j} + (z + x^2)\vec{k}$ and C is the triangle with vertices $(1, 0, 0), (0, 1, 0), \text{ and } (0, 0, 1).$

Problem 2. Use Stokes' Theorem to evaluate

$$
\int\int_S \text{curl}\vec{F} \cdot d\vec{S}
$$

where $\vec{F}(x, y, z) = y\vec{i} - x\vec{j} + yx^3\vec{k}$ and S is the part of the part of the sphere $x^2 + y^2 + y^3 = 0$ $z^2 = 4$ for $z > 0$, with upwards orientation. Assume that C is the circle $x^2 + y^2 = 4$ $(in \mathbb{R}^3)$, with counterclockwise orientation.

Problem 3. Verify that Stokes' Theorem is true for the vector field $\vec{F}(x, y, z) =$ $y^2\vec{i} + x\vec{j} + z^2\vec{k}$ and S is the part of the paraboloid $z = x^2 + y^2$ that lies strictly below the plane $z = 1$, oriented upwards. Furthermore, C is the curve in which the the surface of the paraboloid $z = x^2 + y^2$ intersects the plane $z = 1$, oriented counterclockwise.

Problem 4. Use Stoke's Theorem to evaluate

$$
\int_C \vec{F} \cdot d\vec{r}
$$

where $\vec{F}(x, y, z) = e^{-x}\vec{i} + e^{x}\vec{j} + e^{z}\vec{k}$. Here, C is the boundary of the part of the plane $2x + y + 2z = 2$ in the first octant, and is oriented counterclockwise as viewed from above.

Problem 5. Verify that the Divergence theorem is true for the vector field $\vec{F}(x, y, z) =$ $xy\vec{i} + yz\vec{j} + zx\vec{k}$ and S is the part of the cylinder $x^2 + y^2 = 1$ for $0 \le z \le 1$.

Problem 6. Use Divergence theorem to evaluate

$$
\int \int_S \vec{F} \cdot d\vec{S}
$$

where $\vec{F}(x, y, z) = x^2 \vec{i} + xy \vec{j} + z \vec{k}$ and S is the part of the paraboloid $z = 4 - x^2 - y^2$ that lies above the xy plane.

Problem 7. Use the Divergence Theorem to evaluate

$$
\int\int_S \vec{F} \cdot d\vec{S}
$$

where $\vec{F}(x, y, z) = z \tan^{-1}(y^2)\vec{i} + z^3 \ln(x^2 + 1)\vec{j} + z\vec{k}$ and S is the part of the cone $z = 2 - \sqrt{x^2 + y^2}$ that lies above the plane $z = 1$, oriented upwards.

2 Vector Identities:

Problem 8. Prove the following identity

$$
\int \int_S \text{curl}\vec{F} \cdot d\vec{S} = 0
$$

assuming S satisfies the conditions of Divergence Theorem.

Problem 9. Suppose that S and C satisfies the condition of Stokes' Theorem and f and g are smooth functions. Use Stokes' Theorem to prove the following identity.

$$
\int_C (f\nabla g) \cdot d\vec{r} = \int \int_S (\nabla f \times \nabla g) \cdot d\vec{S}
$$

Problem 10. Assume that S and D satisfy the conditions of Divergence Theorem \bar{F} is a smooth funtion such that $\vec{F}(x, y, z) = x\vec{i} + y\vec{j} + z\vec{k}$. Use the Divergence Theorem to prove the following identity:

$$
\text{Vol}(D) = \frac{1}{3} \int \int_{S} \vec{F} \cdot d\vec{S}
$$

Problem 11. Assume that S and E satisfy the conditions of Divergence Theorem and both f and g are smooth functions. Use the Divergence Theorem to prove the following identity:

$$
\int \int_{S} (f \nabla g) \cdot \vec{n} dS = \int \int \int_{D} (f \nabla^2 g + \nabla f \cdot \nabla g) dV
$$

where ∇^2 is the differential operator (called the **Laplacian**)

$$
\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}.
$$