

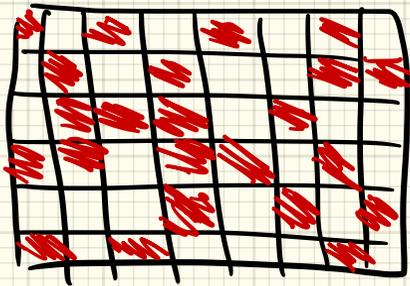
Lecture 15: Matrix
Completion, Correlated
Random Variables, and
Deconvolution

A. Matrix Completion

$X \in \mathbb{R}^{n \times p}$ (eg. n movies, p customers)

assume X is low rank

only observe subset of entries of X
want to fill in remainder



$= X$

$\mathcal{I} = \{(i,j) \text{ s.t.}$

X_{ij} is observed}

$$\hat{X} = \underset{M}{\operatorname{arg\,min}} \quad \underline{\operatorname{rank}(M)} \quad \text{s.t.} \quad M_{ij} = X_{ij} \quad \forall (i,j) \in \mathcal{I}$$

intractable

alternative

$$\Rightarrow \hat{X} = \underset{M}{\operatorname{arg\,min}} \quad \|M\|_*$$

s.t. $\underline{M}_{ij} = X_{ij} \quad \forall (i,j) \in \mathcal{I}$

Computationally tractable

$$\operatorname{rank}(X) = \#\{i : \sigma_i > 0\}$$

$$\|X\|_* = \sum_i \sigma_i$$

= trace norm

= nuclear norm

Iterative Singular Value Thresholding

initialize: $\hat{X} = \text{zeros}(n, p)$

$\hat{X}_{\mathcal{X}} = X_{\mathcal{X}} \leftarrow$ fill in obs. entries

set threshold or r

for $k = 1, 2, \dots$

$[U, S, V] = \text{svd}(\hat{X});$

$\hat{S} = S \cdot * (S \geq \text{threshold})$
 $\quad \quad \quad \cup$

$\hat{S} = \text{zeros}(n, p);$ for $l = 1, \dots, r, \hat{S}(l, l) = S(l, l);$

$\hat{X} = U \cdot \hat{S} \cdot V^T;$

$\hat{X}_{\mathcal{X}} = X_{\mathcal{X}};$

if converged, stop

$$\|\hat{X} - \hat{X}_{\text{old}}\|_F < \epsilon$$

end

define $X \in \mathbb{R}^{p \times p}$ s.t. $y = Xw + \varepsilon$

eg. $m = 3$

$$X = \frac{1}{3} \begin{bmatrix} 1 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

X is "circulant"
each row is
shifted version of
previous row

To est w , $\hat{w} = (X^T X)^{-1} X^T y$

More general formulation:

$$y_i = \sum_{j=1}^p h_j w_{i+j \pmod{p}} + \varepsilon_i$$

Convolution

define $X \in \mathbb{R}^{p \times p}$
s.t. $y = Xw + \varepsilon$

$$X = \begin{bmatrix} h_1 & h_2 & h_3 & \dots & h_p \\ h_p & h_1 & h_2 & \dots & h_{p-1} \\ h_{p-1} & h_p & h_1 & \dots & h_{p-2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ h_2 & h_3 & h_4 & \dots & h_1 \end{bmatrix}$$

X
Circulant

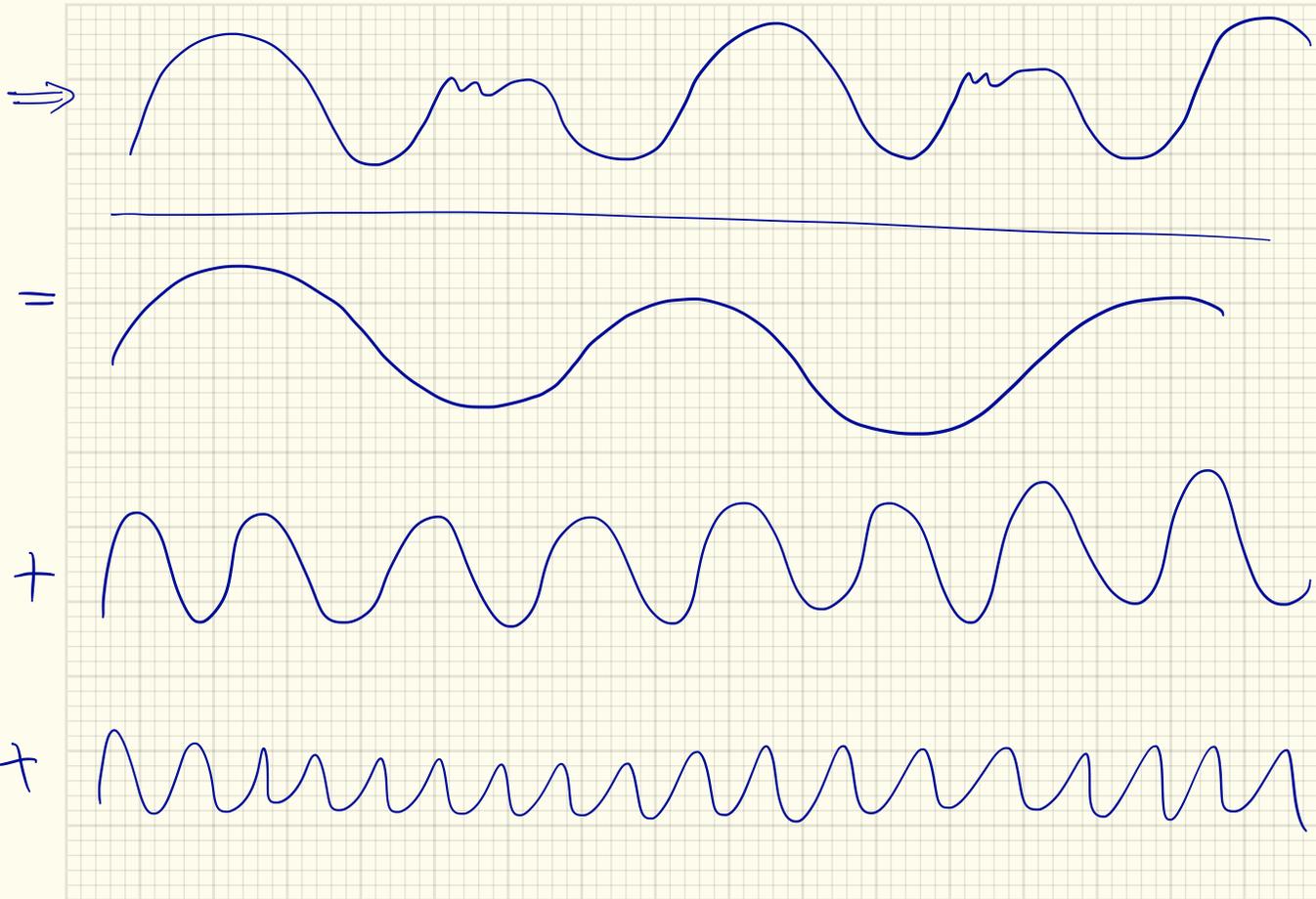
$$X = V \Lambda V^H$$

(V^H means "Hermitian"
transpose $V^H = (V^T)^*$
 $V^H V = I$)

when X circulant,
then

- diagonal elts of Λ = Fourier transform coeffs of h
- V is Fourier transform matrix

Fourier transform: represent signals as
weighted sums of sinusoids



Fourier transform of h

$$\lambda_1 = \frac{1}{\sqrt{P}} \sum_{i=1}^P h_i e^{-j2\pi(i-1)0/P} \rightarrow \text{zero freq sine wave} \\ = \text{constant}$$

$$\lambda_2 = \frac{1}{\sqrt{P}} \sum_{i=1}^P h_i e^{-j2\pi(i-1)1/P}$$

$$\underline{\lambda_k} = \frac{1}{\sqrt{P}} \sum_{i=1}^P h_i e^{-j2\pi(i-1)\frac{(k-1)}{P}} \rightarrow \text{freq } \frac{k-1}{P}$$

$$\Rightarrow h_i = \frac{1}{\sqrt{P}} \sum_{k=1}^P \lambda_k e^{+j2\pi \underbrace{(i-1)}_{\text{sample}} \underbrace{(k-1)/P}_{\text{frequency}}}$$

(write h as weighted sum of sinusoids)

These sinusoids correspond to the columns of V !

$$v_k = k^{\text{th}} \text{ col of } V = \frac{1}{\sqrt{p}} \begin{bmatrix} e^{j2\pi(k-1) \cdot 0/p} & e^{j2\pi(k-1) \cdot 1/p} & \dots & e^{j2\pi(k-1) \cdot (p-1)/p} \end{bmatrix}^T$$

$$\Rightarrow h = V \lambda, \quad \lambda = [\lambda_1, \lambda_2, \dots, \lambda_p]^T$$

note

$$v_k^H = k^{\text{th}} \text{ row of } V^H = \frac{1}{\sqrt{p}} \begin{bmatrix} e^{-j2\pi(k-1) \cdot 0/p} & e^{-j2\pi(k-1) \cdot 1/p} & \dots & e^{-j2\pi(k-1) \cdot (p-1)/p} \end{bmatrix}$$

$$\lambda_k = v_k^H h$$

$$\underline{\lambda} = V^H h$$

$$y = Xw = \underline{V\Lambda V^H} w$$

eigen decomposition of $X = V\Lambda V^H$

diag elts of $\Lambda = \lambda_k$'s.

Consider LS est of w :

$$\begin{aligned}\hat{w} &= (X^H X)^{-1} X^H y \\ &= (V\Lambda V^H V\Lambda V^T)^{-1} V\Lambda V^H y \\ &= V\Lambda^{-1} V^H y\end{aligned}$$

interp:

1. $V^H y = \text{DFT } y$
2. scale DFT coeffs
by dividing by DFT
coeff of h
3. inverse DFT

Signal processing
perspective:

$$y = w * h \quad \neq \varepsilon$$

$$Y = W \cdot H$$

$$\Rightarrow \hat{W} = Y ./ H$$

1. $Y = \text{dft}(y)$

2. $H = \text{dft}(h)$, $\hat{W} = Y ./ H$

3. $\hat{w} = \text{idft}(\hat{W})$

Consider Ridge Regression

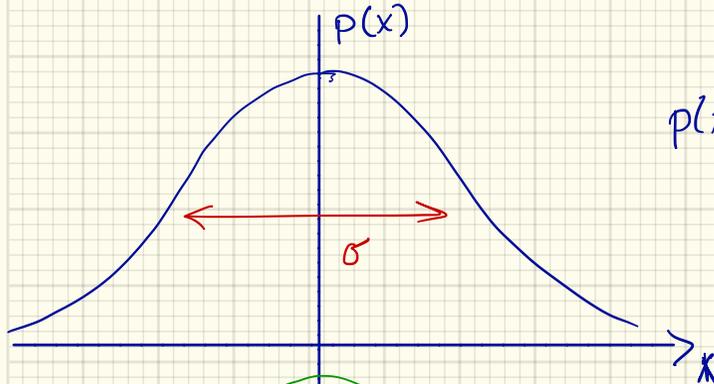
$$\begin{aligned}\hat{w} &= (V\Lambda^2 V^H + \lambda I)^{-1} V\Lambda V^H y \\ &= (V(\Lambda^2 + \lambda I)V^H)^{-1} V\Lambda V^H y \\ &= V \underbrace{\frac{\Lambda}{\Lambda^2 + \lambda I}}_{\text{}} V^H y\end{aligned}$$

1. dft (y)
2. resealing
dft coeffs
(avoid dividing
by zeros)
3. inverse dft

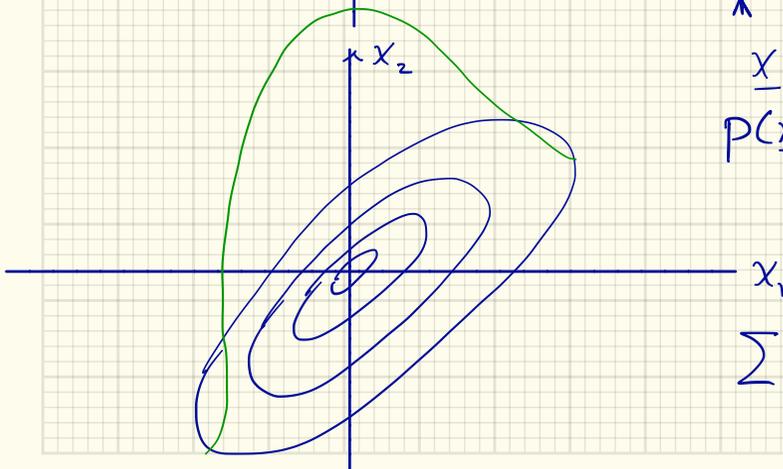
Some λ_k 's close to zero

$$\begin{bmatrix} \frac{\lambda_1}{\lambda_1^2 + \lambda} & & & \\ & \frac{\lambda_2}{\lambda_2^2 + \lambda} & & \\ & & \dots & \\ & & & \frac{\lambda_p}{\lambda_p^2 + \lambda} \end{bmatrix}$$

Multivariate normal / Gaussian distribution



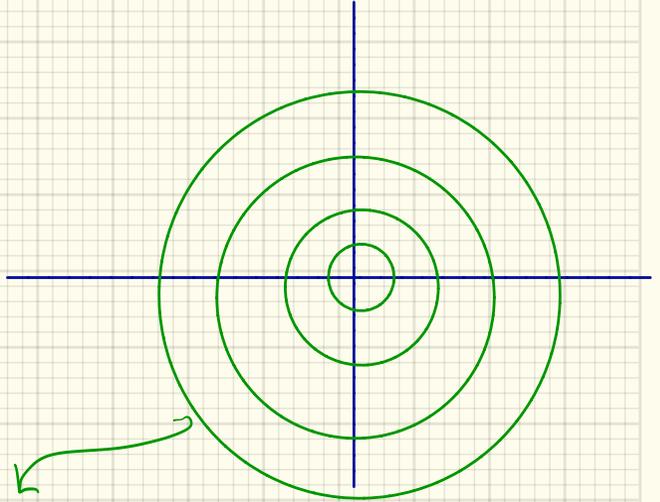
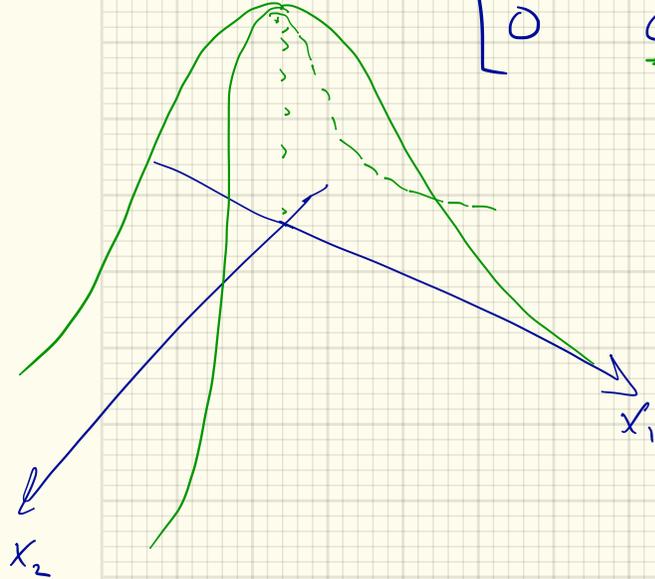
$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2} x^2}$$



$$\underline{x} \in \mathbb{R}^p$$
$$p(\underline{x}) = \frac{1}{(2\pi)^{p/2} |\Sigma|^{1/2}} e^{-\frac{1}{2} \underline{x}^T \Sigma^{-1} \underline{x}}$$

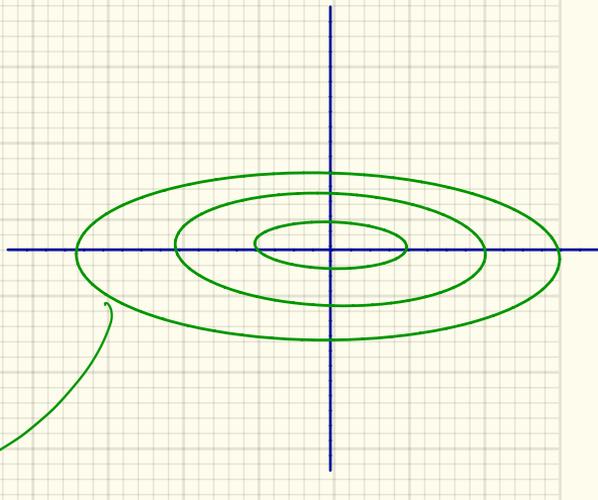
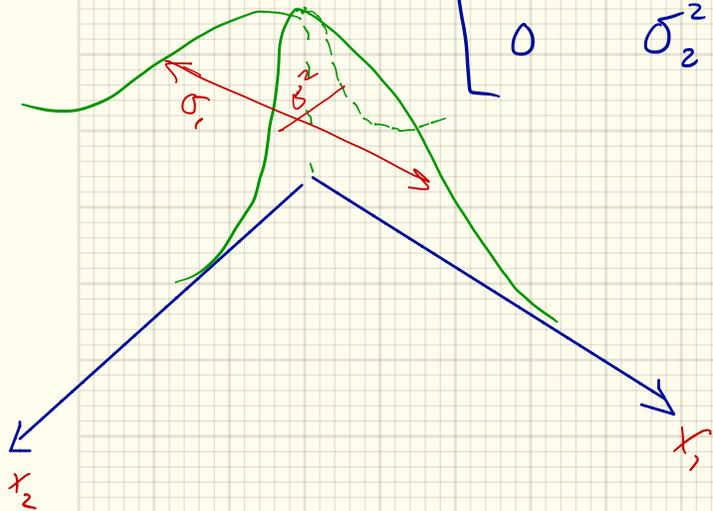
$$\Sigma = \mathbb{E}[\underline{x} \underline{x}^T] = \text{covariance matrix}$$

$$P=2, \quad \Sigma = \begin{bmatrix} \underline{\sigma^2} & 0 \\ 0 & \underline{\sigma^2} \end{bmatrix}$$



$$\{x \in \mathbb{R}^2 \text{ s.t. } \|x\| = \gamma\}$$

$$p=2, \quad \Sigma = \begin{bmatrix} \sigma_1^2 & 0 \\ 0 & \sigma_2^2 \end{bmatrix}$$



$$\left\{ x \in \mathbb{R}^2 : x^T \Sigma^{-1} x = \gamma \right\}$$

$$\frac{x_1^2}{\sigma_1^2} + \frac{x_2^2}{\sigma_2^2} = \gamma$$

$p=2$, Σ arbitrary positive definite matrix.

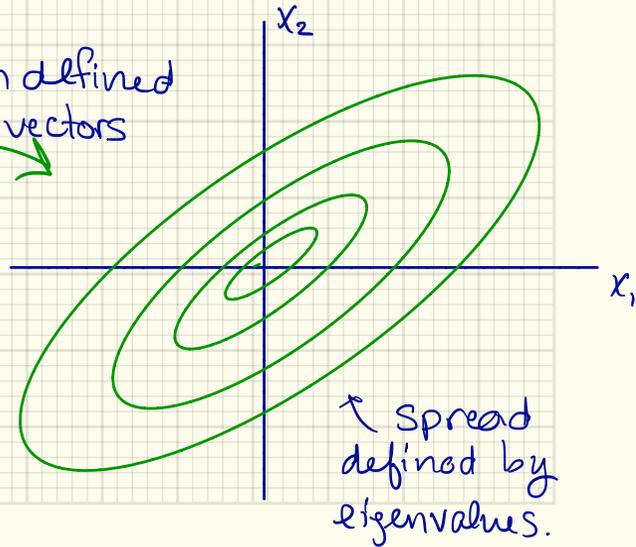
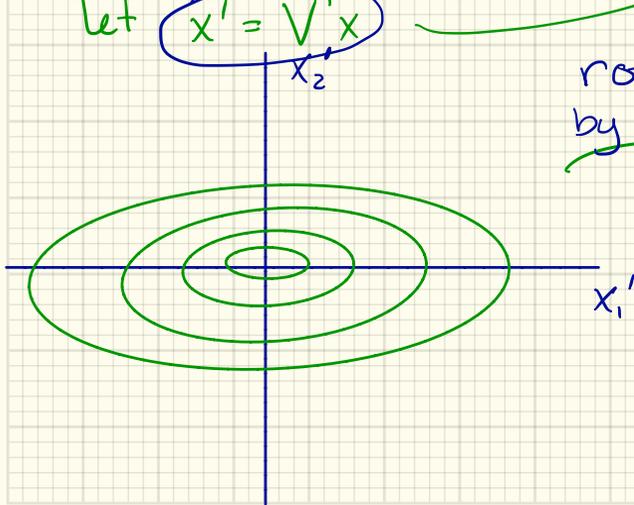
$$\{x \in \mathbb{R}^2 : x^T \Sigma^{-1} x = \gamma\}$$

$$\Sigma = V \Lambda V^T$$

$$x^T \Sigma^{-1} x = x^T V \Lambda^{-1} V^T x = x' \Lambda^{-1} x' = \gamma$$

let $x' = V^T x$

rotation defined
by eigenvectors



↑ Spread
defined by
eigenvalues.

