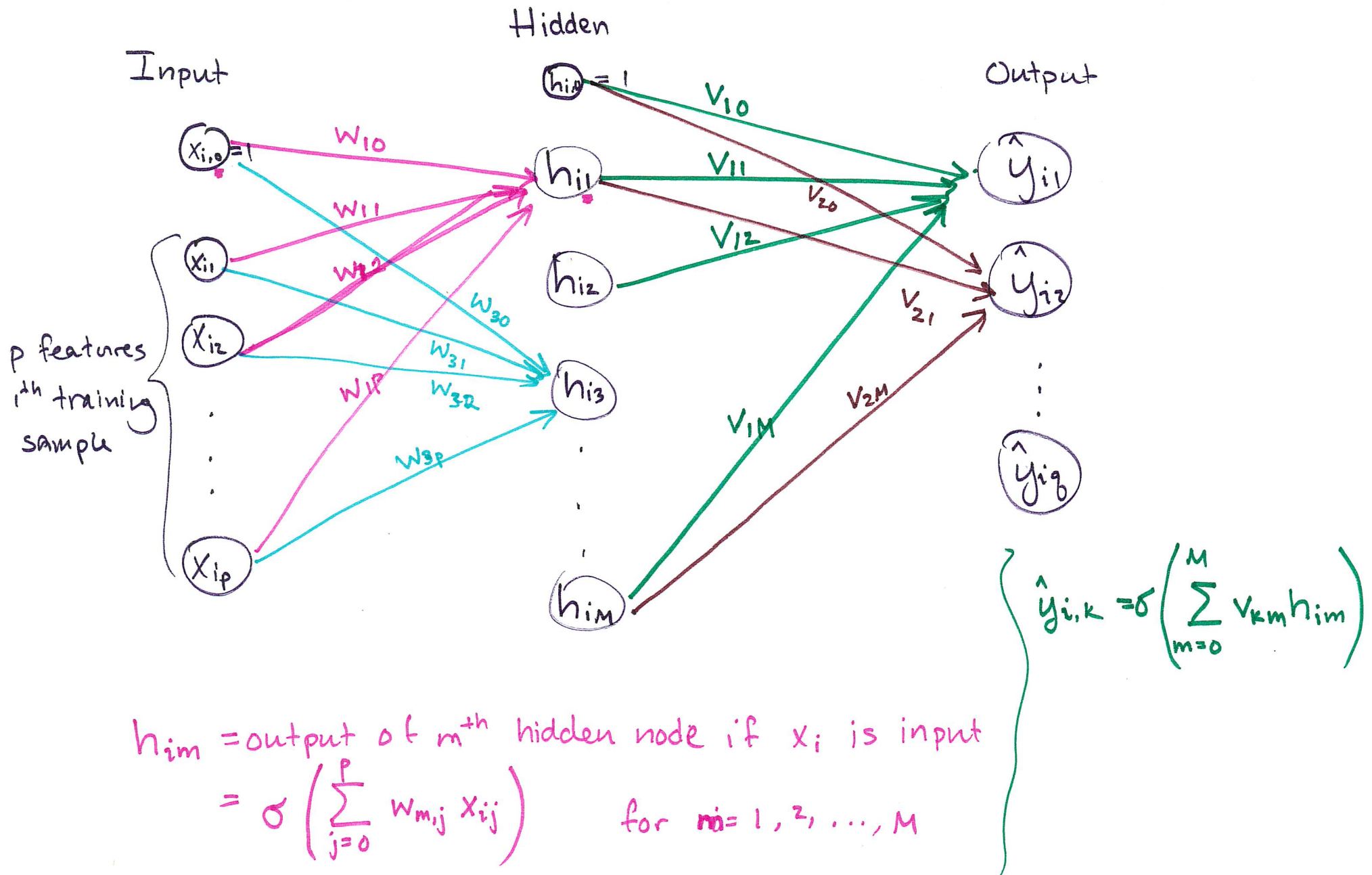


Lecture 23 - Backpropagation in Neural Networks

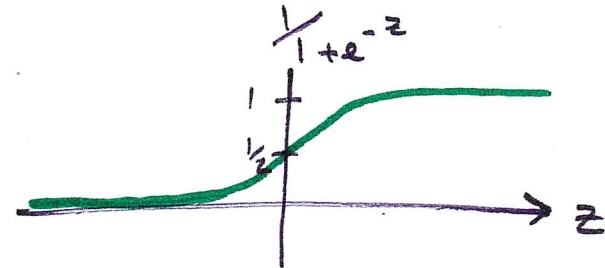


Common activation functions:

• $\sigma(z) = \max(z, 0)$ (ReLU = rectified Linear unit)

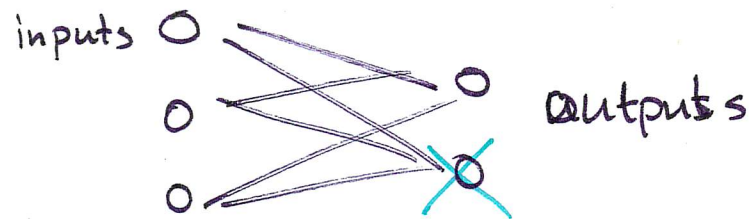
• $\sigma(z) = \text{sign}(z)$

• $\sigma(z) = \frac{1}{1+e^{-z}}$ = logistic function



Learning weights:

1st pass: 2-layer network:



$$\hat{y}_{ik} = \sigma \left(\sum_{j=0}^P w_{kj} x_{ij} \right)$$

We can learn weights w/ Stochastic Gradient Descent (SGD)

③

loss function $f(\underline{w}) = \sum_{i=1}^n \frac{1}{2} (y_i - \hat{y}_i)^2 \leftarrow$ want to minimize

$$(a-b)^2 = (b-a)^2$$

$$= \sum_{i=1}^n \frac{1}{2} \underbrace{\left[\sigma \left(\sum_{j=0}^P w_j x_{ij} \right) - y_i \right]^2}_{f_i(\underline{w})}$$

$$f(\underline{w}) = \sum_{i=1}^n f_i(\underline{w})$$

Today: $\sigma(z) = \frac{1}{1+e^{-z}}$

$$\sigma'(z) = \frac{d\sigma}{dz} = \sigma(z)(1 - \sigma(z))$$

algorithm

@ iteration t :

· choose i_t uniformly at random.

· set $\underline{w}^{(t+1)} = \underline{w}^{(t)} - \alpha_t \nabla f_{i_t}(\underline{w}^{(t)})$

, $\alpha_t =$ step size (e.g. $\alpha_t = 1/\sqrt{t}$)

recall:

$$\hat{y}_i = \sigma \left(\sum_{j=0}^P w_j x_{ij} \right)$$

$$\nabla f_i(w^{(t)})$$

(drop i_t , ^{use} i)

(4)

$$\underbrace{\frac{df_i}{dw_j}}_{j\text{th weight}} \bigg|_{\underline{w}^{(t)}} = \frac{df_i}{d\hat{y}_i} \cdot \frac{d\hat{y}_i}{dw_j} \bigg|_{\underline{w}^{(t)}}$$

$$= (\hat{y}_i - y_i) \sigma' \left(\sum_{j'=0}^P w_{j'} x_{ij'} \right) x_{ij} \bigg|_{\underline{w}^{(t)}}$$

$$= (\hat{y}_i - y_i) \underbrace{\sigma \left(\sum_{j'} w_{j'} x_{ij'} \right)}_{\hat{y}_i} \underbrace{\left[1 - \sigma \left(\sum_{j'} w_{j'} x_{ij'} \right) \right]}_{1 - \hat{y}_i} x_{ij} \bigg|_{\underline{w}^{(t)}}$$

$$= \underbrace{(\hat{y}_i - y_i) \hat{y}_i (1 - \hat{y}_i)}_{\text{scalar, independent of } j} x_{ij}$$

scalar, independent
of $j = S_i$

$$\Rightarrow \nabla f_{i_t}(\underline{w}^{(t)}) = \delta_{i_t} \underline{x}_{i_t}$$

$\Rightarrow$ SGD:

$$w^{(t+1)} = w^{(t)} - \alpha_t \delta_{i_t} x_{i_t}$$

$$\nabla f_{i_t} = \begin{bmatrix} df_{i_t}/dw_0 \\ df_{i_t}/dw_1 \\ \vdots \\ df_{i_t}/dw_P \end{bmatrix} = \begin{bmatrix} \delta_{i_t} x_{i_t0} \\ \delta_{i_t} x_{i_t1} \\ \vdots \\ \delta_{i_t} x_{i_tP} \end{bmatrix} = \delta_{i_t} \underline{x}_{i_t} \quad (5)$$

3-layer network (1 hidden layer)

$$\hat{y}_{i,k} = \sigma \left(\sum_{m=0}^M v_{k,m} h_{i,m} \right) = \sigma \left(\sum_{m=0}^M v_{k,m} \cdot \sigma \left[\sum_{j=0}^P w_{m,j} x_{ij} \right] \right)$$

again, write i instead of i_t

Backpropagation Algorithm

- choose initial weights $\{V_{k,m}^{(1)}\}_{k,m}$ and $\{W_{m,j}^{(1)}\}_{m,j}$
- for $t=1, 2, 3, \dots$
 - choose i_t
 - calculate $\hat{y}_{i_t,k}$ and $h_{i_t,m}$ using $\{V_{k,m}^{(t)}\}_{k,m}$,
 $\{W_{m,j}^{(t)}\}_{m,j}$
 - update weights for each layer, starting w/
deepest layer (closest to output) and working back
to shallowest layer

to update $V_{k,m}$'s :

$$\frac{df_i}{dV_{km}} = \frac{df_i}{d\hat{y}_i} \cdot \frac{d\hat{y}_i}{dV_{k,m}}$$

$$= (\hat{y}_{ik} - y_{ik}) \sigma' \left(\sum_{m'=0}^M V_{k,m'} h_{i,m'} \right) h_{i,m}$$

$$= \underbrace{(\hat{y}_{ik} - y_{ik}) \hat{y}_{ik} (1 - \hat{y}_{ik})}_{\delta_{ik}} h_{i,m}$$

$$= \delta_{ik} \cdot h_{i,m}$$

$$\Rightarrow V_{k,m}^{(t+1)} = V_{k,m}^{(t)} - \alpha_t \delta_{ik} h_{i,t}$$

$$\Rightarrow \underline{V}_k^{(t+1)} = \underline{V}_k^{(t)} - \alpha_t \delta_{i_t, k} \underline{h}_{i_t}$$

for $k=1, \dots, q, m=0, \dots, M$

for $k=1, \dots, q$

To update $w_{m,j}$'s :

$$\begin{aligned}
 \frac{df_i}{dw_{m,j}} &= \sum_{k=1}^q \frac{df_i}{d\hat{y}_{ik}} \cdot \frac{d\hat{y}_{ik}}{dh_{i,m}} \cdot \frac{dh_{i,m}}{dw_{m,j}} \\
 &= \sum_{k=1}^q \underbrace{(\hat{y}_{ik} - y_{ik}) \sigma' \left(\sum_{m'=0}^M v_{k,m'} h_{i,m'} \right) v_{k,m}}_{S_{ik}} \underbrace{\sigma' \left(\sum_{j'=0}^P w_{m,j'} x_{ij'} \right) x_{ij}}_{\text{scalar, indep. of } j,} \\
 &= \sum_{k=1}^q (\hat{y}_{ik} - y_{ik}) \hat{y}_{ik} (1 - \hat{y}_{ik}) v_{k,m} h_{i,m} (1 - h_{i,m}) x_{ij} \\
 &= \underbrace{\sum_{k=1}^q S_{ik} v_{k,m} h_{i,m} (1 - h_{i,m})}_{\gamma_{i,m}} x_{ij} = \gamma_{m,i} x_{i,j}
 \end{aligned}$$

SGD update :

$$W_{m,j}^{(t+1)} = W_{m,j}^{(t)} - \alpha_t \gamma_{i_t, m} X_{i_t, j}$$

for $j=0, \dots, p$

$m=0, \dots, M$

$$\underline{W}_m^{(t+1)} = \underline{W}_m^{(t)} - \alpha_t \gamma_{i_t, m} \underline{X}_{i_t}$$

for $m=0, \dots, M$