

Lecture 7: Orthogonal Bases

①

$$\underline{y}^T X \underline{w} = \underline{w}^T X^T \underline{y} \iff \langle \underline{b}, \underline{y} \rangle = \underline{y}^T \underline{b} = \sum_{i=1}^n y_i b_i = \underline{b}^T \underline{y}$$

let $\underline{b} = X \underline{w}$

$$\underline{y}^T X \underline{w} = (X \underline{w})^T \underline{y} = \underline{w}^T X^T \underline{y}$$

$$\underline{b} = A \underline{x}$$



$$\underline{y} = X \underline{w}$$



Calories

↑ ← weights
fat, carbs, etc

$$X = \begin{bmatrix} | & & | \\ \underline{x}_1 & \dots & \underline{x}_p \\ | & & | \end{bmatrix}$$

model $\hat{\underline{y}} = \underline{w}_1 \underline{x}_1 + \underline{w}_2 \underline{x}_2 + \dots + \underline{w}_p \underline{x}_p$

what if $\underline{x}_1 = \underline{x}_2 + \underline{x}_3$? $\underline{x}_2 = \underline{x}_1 - \underline{x}_3$

$$\underline{w}_1 \underline{x}_1 = \underline{w}_1 \underline{x}_2 + \underline{w}_1 \underline{x}_3$$

$$\underline{w}_2 \underline{x}_2 = \underline{w}_2 \underline{x}_1 - \underline{w}_2 \underline{x}_3$$

model : $y = w_1 x_1 + w_2 x_2 + w_3 x_3 + \dots$

$= \underline{0 \cdot x_1} + \underline{(w_1 + w_2) x_2} + \underline{(w_1 + w_3) x_3} + \dots$

$= \underline{(w_1 + w_2) x_1} + 0 x_2 + (w_3 - w_2) x_3 + \dots$

$\hat{w} = (X^T X)^{-1} X^T y$ ← if cols of X are linearly dep. then $X^T X$ is not invertible

impossible to tell which features are "significant" predictors of y .

what if $\tilde{X} = [\frac{x_1}{10^3} \quad \frac{x_2}{1} \quad \frac{x_3}{1} \quad \dots \quad \frac{x_p}{1}]$

when choose weights \underline{w} , w_1 to be 10^3 times as big

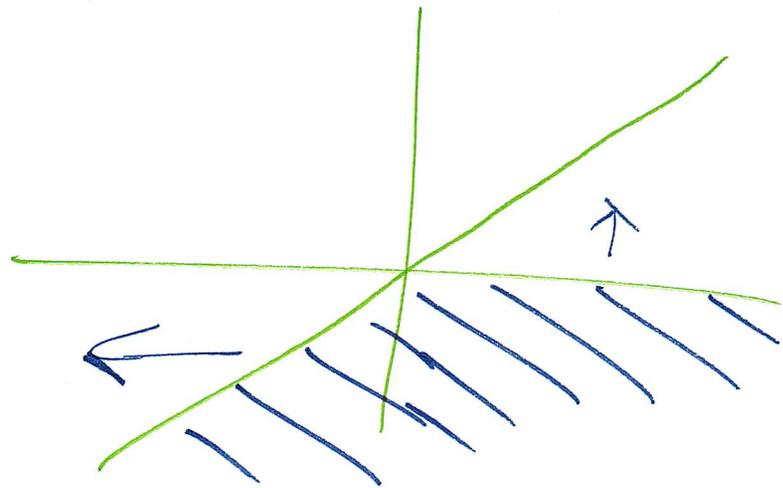
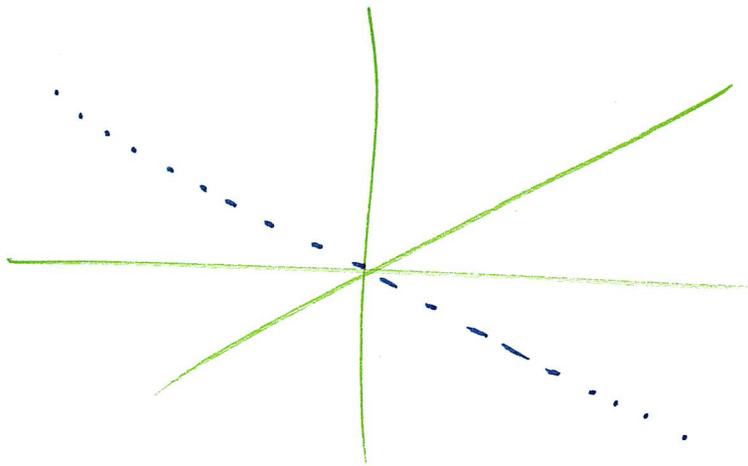
$\underline{x}, w_1 = \frac{x_1}{10^3} (w_1 \cdot 10^3)$

If we are handed a matrix $X \in \mathbb{R}^{n \times p}$, how can we prevent this scenario? ③

Recall, $\hat{y} =$ weighted sum of cols of X

$$\in \text{span}(\underline{x}_1, \underline{x}_2, \dots, \underline{x}_p)$$

this is a subspace



④

Give $X = [\underline{x}_1, \dots, \underline{x}_p]$, how can we represent the corresponding subspace?

Option 1: use $X \Rightarrow$ LS can be hard to interpret

Option 2: use an orthonormal basis for subspace.

o.n. basis = $\{\underline{u}_1, \dots, \underline{u}_r\}$ s.t. subspace $S = \text{span}\{\underline{u}_1, \dots, \underline{u}_r\}$

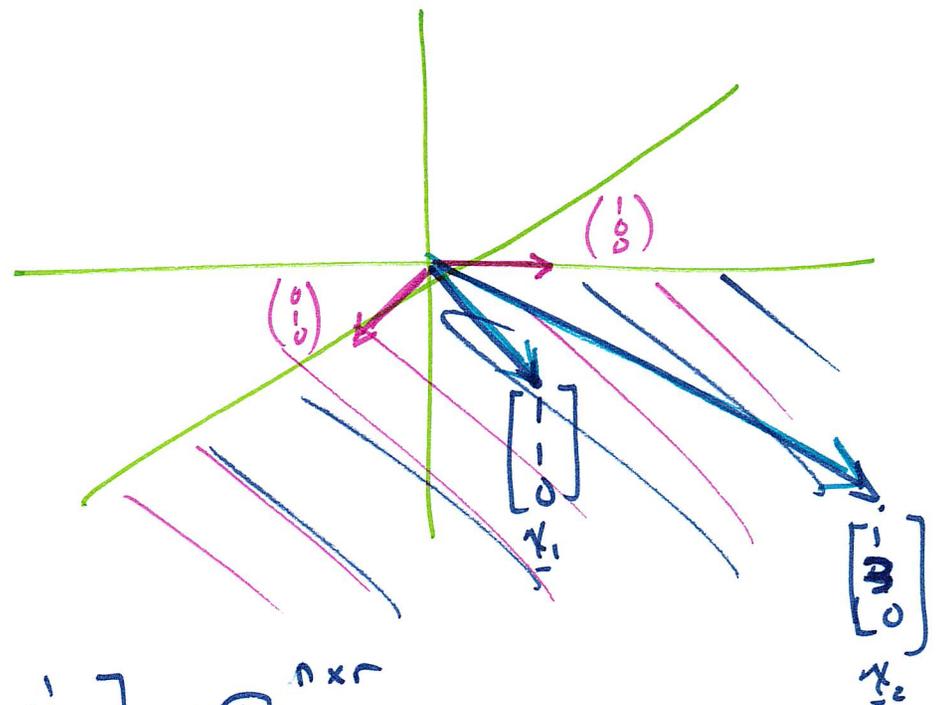
$$\text{and } \underline{u}_i^T \underline{u}_j = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$$

$$\text{span}(\underline{u}_1, \dots, \underline{u}_r) = \text{span}(\underline{x}_1, \dots, \underline{x}_p)$$

$$r \leq \min(n, p)$$

↑ rank of subspace
= # Lin. Indep. cols of X

$$\text{let } U = \text{basis matrix} = [\underline{u}_1 \quad \underline{u}_2 \quad \dots \quad \underline{u}_r] \in \mathbb{R}^{n \times r}$$



Before

$$\hat{\underline{w}} = \arg \min_{\underline{w}} \|y - X\underline{w}\|_2^2$$

$\hat{\underline{w}}$ can be hard to interpret

if we get a new sample $\underline{x} \in \mathbb{R}^p$ and want to predict y , then

$$\hat{y} = \langle \underline{x}, \hat{\underline{w}} \rangle$$

$$\hat{\underline{w}} = \underbrace{(X^T X)^{-1}} X^T y$$

↳ can be hard to compute

Now

$$\hat{\underline{v}} = \arg \min_{\underline{v}} \|y - U\underline{v}\|_2^2$$

$\hat{\underline{v}}$ can be easier to interpret

- how to ~~compute~~ compute $\hat{\underline{v}}$?
- how to get U given X
- if we get a new sample $\underline{x} \in \mathbb{R}^p$, how do we predict y ?

(5)

Some properties of basis matrix $U = [\underline{u}_1, \dots, \underline{u}_r] \in \mathbb{R}^{n \times r}$ (6)

i) $U^T U = I$

$$\underline{u}_i^T \underline{u}_j = \begin{cases} 0 & \text{if } i \neq j \\ 1 & \text{if } i = j \end{cases}$$

$$TW = \begin{bmatrix} t_1^T w_1 & t_1^T w_2 & \dots \\ t_2^T w_1 & \vdots & \dots \\ \vdots & \vdots & \dots \end{bmatrix}$$

ii) if $\underbrace{U}_{n \times r}$ and $\underbrace{V}_{r \times p}$ are both orthogonal, then

UV is also orthogonal

iii) "length preserving" $\|Uv\|_2 = \|v\|_2$

$$\|Uv\|_2^2 = (Uv)^T (Uv) = v^T U^T U v = v^T v = \|v\|_2^2$$

$$\hat{v} = \arg \min_v \|y - Uv\|_2^2$$

need \hat{v} to satisfy

$$\underbrace{U^T U}_{=I} \hat{v} = U^T y \implies \hat{v} = U^T y$$

easy!

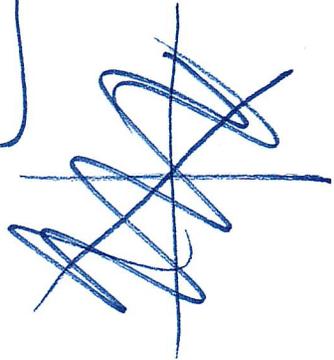
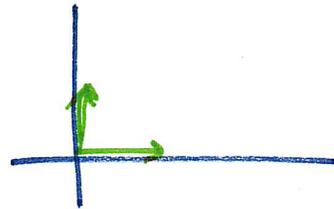
how to take X and get orthonormal basis U?

Gram-Schmidt Orthogonalization

ex. $\underline{x}_1 = \begin{bmatrix} 2 \\ 0 \end{bmatrix}, \underline{x}_2 = \begin{bmatrix} a \\ b \end{bmatrix}$

$$U = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\underline{u}_1 = \frac{\underline{x}_1}{\|\underline{x}_1\|_2} = \frac{\underline{x}_1}{2} = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$



write \underline{x}_2 as weighted sum of u_1 + ~~resid~~ residual

$$\underline{x}_2 = a \cdot \underbrace{\begin{bmatrix} 1 \\ 0 \end{bmatrix}}_{\underline{u}_1} + \begin{bmatrix} 0 \\ b \end{bmatrix} \implies \text{resid } \underline{x}'_2 = \begin{bmatrix} 0 \\ b \end{bmatrix} \implies \underline{u}_2 = \frac{\underline{x}'_2}{\|\underline{x}'_2\|_2} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

ex. $\underline{x}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \quad \underline{x}_2 = \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix}$

$$\underline{u}_1 = \frac{\underline{x}_1}{\|\underline{x}_1\|_2} = \frac{\underline{x}_1}{\sqrt{2}} = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{bmatrix}$$

write $\underline{x}_2 = \text{weighted } \underline{u}_1 + \text{residual}$
 make as small as possible

what is the least-squares fit of \underline{u}_1 to \underline{x}_2 ?

$$\arg \min_w \|\underline{x}_2 - \underline{u}_1 w\|_2^2$$

$$\hat{w} = \underline{u}_1^T \underline{x}_2$$

$$\begin{aligned} \underline{x}_2 &= \hat{w} \underline{u}_1 + \text{resid} \\ &= \underline{u}_1 (\underline{u}_1^T \underline{x}_2) + \text{resid} \end{aligned}$$

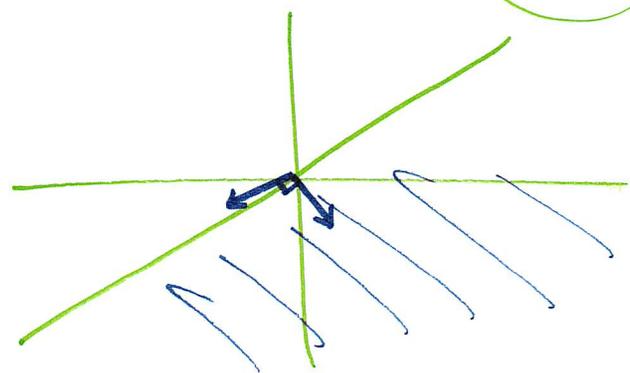
$$\text{resid} = \underline{x}'_2 = \underline{x}_2 - \underline{u}_1 (\underline{u}_1^T \underline{x}_2)$$

$$\underline{u}_1^T \underline{x}_2 = 1/\sqrt{2} + 3/\sqrt{2} = 4/\sqrt{2}$$

$$\underline{x}'_2 = \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix} - 4/\sqrt{2} \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} -1 \\ -1 \\ 0 \end{bmatrix}$$

$$\underline{u}_2 = \frac{\underline{x}'_2}{\|\underline{x}'_2\|_2} = \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{bmatrix}$$



Gram-Schmidt Orthogonalization Algorithm

⑨

input: $X = [\underline{x}_1 \quad \underline{x}_2 \quad \dots \quad \underline{x}_p] \in \mathbb{R}^{n \times p}$

output: $U = [\underline{u}_1 \quad \underline{u}_2 \quad \dots \quad \underline{u}_r] \in \mathbb{R}^{n \times r}$

$$r = \text{rank}(X) \\ \leq \min(n, p)$$

initialize: $\underline{u}_1 = \underline{x}_1 / \|\underline{x}_1\|_2$

for $j = 2, 3, \dots, p$

$\underline{x}'_j =$ all ~~the~~ components of \underline{x}_j not represented by

$$\underline{u}_1, \dots, \underline{u}_{j-1} \\ = \underline{x}_j - \sum_{i=1}^{j-1} (\underline{u}_i^T \underline{x}_j) \underline{u}_i$$

least squares weight
for \underline{u}_i

$$\underline{u}_j = \begin{cases} \frac{\underline{x}_j'}{\|\underline{x}_j'\|_2} & \text{if } \underline{x}_j' \neq 0 \\ 0 & \text{if } \underline{x}_j' = 0 \end{cases}$$

~~end for~~

end

ex. $X = \begin{bmatrix} -1 & 1 & 2 \\ 1 & -1 & 2 \end{bmatrix}$

$\underline{x}_1 \quad \underline{x}_2 \quad \underline{x}_3$

$$\underline{u}_1 = \frac{\underline{x}_1}{\|\underline{x}_1\|_2} = \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$$

$$\begin{aligned} \underline{x}_2' &= \underline{x}_2 - (\underline{u}_1^T \underline{x}_2) \underline{u}_1 \\ &= \begin{bmatrix} 1 \\ -1 \end{bmatrix} + (+2/\sqrt{2}) \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix} + \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \underline{u}_2 = 0 \end{aligned}$$

$$\begin{aligned} \underline{x}_3' &= x_3 - (u_1^T x_3) u_1 - (u_2^T x_3) u_2 \\ &= x_3 - 0 \cdot u_1 - 0 \\ &= x_3 \end{aligned}$$

$$u_3 = \frac{x_3}{\|x_3\|_2} = \begin{bmatrix} 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}$$