Lecture 10 SVD in Least Squares

Principal Components Regression

1 Reduce dimension of each sample from p to K<p.

Let
$$X \in \mathbb{R}^{n \times p} = + \text{raining features}$$
 and $U \subseteq V^T = \text{SVD}(X)$. Let $V_k = 1^{s^k} \times \text{columns} \delta_k V$.
Let $Z_k = V_k \times_k = (i^{+k} \text{col} \delta_k Z_k U_k^T)$

2 Train ML model on Z,2s

$$\frac{1}{b} = \underset{b}{\operatorname{argmm}} \|y - Zb\|_{z}^{z} = (Z^{T}Z)^{T}Z^{T}y \quad \text{where} \quad Z \begin{bmatrix} -z \\ -z \end{bmatrix} \in \mathbb{R}^{n \times k}$$

3 Predict for new sample Xno

usually k is selected so k features are linearly independent (i.e. all k σ_i 's in Σ_k are > 0)

4. (Optional) Find equivalent w so that Xw = Zb

$$Z_{1}^{T} = i^{th} \text{ now of } U_{k} \Sigma_{k} \iff Z = U_{k} \Sigma_{k} \implies Z_{0} = U_{k} \Sigma_{k} b = U_{k} \Sigma_{k} V_{k}^{T} V_{k} b - X_{k} V_{k} b$$

$$\Rightarrow Z_{0}^{L} - X_{k} \hat{w} \quad \text{where } \hat{w} = V_{k} \hat{0}$$

$$\text{also, } \hat{b} = (Z_{1}^{T} Z_{1}^{T} Z_{1}^{T} Y_{k} Y_{k}^{T} Y_{k} Y_{k}^{T} Y_{k} Y_$$

⇒ w = V_k I_k Uk y ← PCR same as projecting each x, onto best k-dim subspace, then taking pseudoinverse

Principal Components Crime

Broke

I Run PCA on all n training samples, mapping $X_i = V_k^{T} \frac{Z_i}{cR^k}$, i=1,...,n

Specifically. Vx is 1st k cols of V matrix from SVD of X & Roup

- Z Spit data into train set and dest set.
- 3. Train me model on (Zi, yi), i=1, , ntain
- 4 Measure accuracy on (zi, yi), i nani, n

Problem Ve depends on test data.

Learned model depends on test data

Estimated accuracy artificially large

This really happens, ospecially in large organizations with different leams doing data prep vs training

Woke

- 1. Split dala into train and test sets
- 2. Run PCA on n_{train} training samples,

 mapping $x_i \longrightarrow z_i = V_x \underline{x}_i$ for $i=1,...,n_{tain}$

Now Vz is 1st k cols of V matrix from SVD

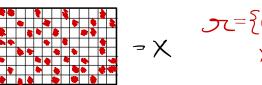
- 3. Train me model on (Zi, yi), i=1, ntrain
- 4 Measure accuracy on (zi, yi), 1, n, n, n, n

Where Z, V Xi

→ much more reliable predictor of accuracy

Matrix Completion

X \in \text{R}^{n \times p} (e.g. n movies, p custamers) assume X is low rank only observe subset of entries of X, want to fill in remainder



intractable

$$rank(X) = \# \{i : \sigma_i > o\}$$

$$\|X\|_{\star} = \sum_{i} \sigma_i$$

$$= trace norm$$

$$= nuclear norm$$

Tractable alternative

$$\hat{X} = \arg\min_{x \in \mathcal{X}} \|M\|_{+}$$
 s.t. $M_{ij} = X_{ij} \ \forall (i_{ij}) \in \mathbb{R}$ of, if data is noisy

$$\hat{X} = \operatorname{argmin} \| X_{x} - M_{x} \|_{2}^{2} + \lambda \| M \|_{x}$$

Algorithm

end

I terative Singular Value Thresholding

initialize:
$$\hat{X} = \text{Zeros}(n, p)$$

 $\hat{X}_{X} = X_{X} \iff \text{fill in obs. entries}$
set threshold

for
$$k = 1, 2, ...$$

 $\hat{X}_{old} = \hat{X}_{old}$
 $[U, S, V] = svd(\hat{X})_{j}$
 $\hat{S} = S * (S > threshold)$
 $\hat{X} = U.\hat{S}.V^{T}_{j}$
 $\hat{X} = Xz_{j}$
 $\hat{Y} = \hat{Y}_{old} ||_{F} < \varepsilon_{j} + \varepsilon_{j}$

Eigendecomposition and Page Rank

Given a matrix A, we say a nonzero vector v is a eigenvector of $A = \lambda V$ where λ is a scalar

Let $V = [v_1, v_2, ..., v_n]$ be a matrix whose columns are all eigenvectors of A. $AV = A[v_1, v_2, ..., v_n] = [A_{v_1}, A_{v_2}, ..., A_{v_n}] = [\lambda_1 v_1, \lambda_2 v_2, ..., \lambda_n v_n]$

$$\Rightarrow | \forall \wedge - \sqrt{\nabla}$$

If the eigenvectors are Linearly independent

Take a matrix X with SVD X = UZV

elgenvalues of A are the squared singular values of X

Then $A = X^TX = (U\Sigma V^T)^T(U\Sigma V^T) = V\Sigma U^TU\Sigma V^T = V\Sigma \Sigma V^T = V\Sigma^T V^T$

Recall that V is orthogonal >> V = V

 $\Rightarrow A = X^{T}X = V \sum_{n=1}^{\infty} V^{-1}$ ⇒ A = VNV = agendecomposition of A \Rightarrow eigenvectors of A are the right singular vectors of X

for general A, if A is real and symmetric, then we can ensure the eigenvectors are real and orthonormal $\Rightarrow V^{-1} = V^{T}$

If we can write A as X'X for some X, then A is real + symmetric

Eigenvalues + Eigenvectors

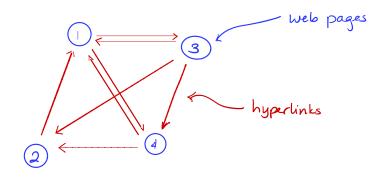
a vector \underline{V}_{ic} (with $\|V_{k}\|_{2}$) is an eigenvector of Δ if allow is a scalar λ_{ic} such that $\Delta \underline{V}_{k} = \lambda_{k} \underline{V}_{k}$

Let $V=[v, v, v_n]$ be allen eigenvectors of A. Then

SVD: $X = U \sum V^T \in \mathbb{R}^{P \times n}$ Let $A = X^T X = V \sum U^T U \sum V^T$ $= V \sum^z V^T = : V \wedge V^T$

⇒ eigenvalus are real and eigenvectors are orthonormal

Page Rank



Imagine surfing web by randomly clicking on links at each page at which you arrive.

You will visit more "important" Web pages more frequently.

If you do this long enough, you'll reach a steady state where Ti is the probability you're at page i at any given time

Let M be adjacency matrix of links and A its column normalized version

(Markov matrix)

O 1 1/3 1/2

O 0 1/3 1/2

1/2 0 0 0

1/2 0 1/3 0

Mij = { 1 if page | links to page i

Think about

A j = Prob (Visit site i next given we're at site j now)

We want to find a vector of probabilities $[\Pi_1, \Pi_2, \Pi_3, \Pi_4]'$ so that $\Pi = A \Pi$ → IT is simply the leading elgenvector of A! Markov matrices are special we know $\lambda_1 = 1$ and $\lambda_1 > \lambda_2 > \lambda_3 > \cdots > \lambda_n$ We can find this vector using Power Iterations: for k = 1, 2, ...Compute $\underline{T}^{(k)} = \underline{A}\underline{\pi}^{(k-1)}$ $\|\underline{A}\underline{\pi}^{(k-1)}\|_{2}$ 1 11 (b) = A T (k-1) / AT (c-1) |

To see this, let m= v, (1st col. of V). Then न = A न ⇒ ν, π = ν, Α π = ν, ∨∧∨ π ⇒ ν', ν, = 1 = e, Λ e, = λ,

Let IT (0) be an initial guess of IT using the 2-norm is other denominator is standard; it ensures the final $\pi^{(k)}$ has norm $\|\pi^{(k)}\|_2=1$ for page rank, we might prefer $\|\pi^{(i)}\|_1 = \sum_i \pi_i^{(i)} = 1$; we can manage this 3 ways

> 2. Use 2-norm in denominator; at end, take $\frac{\pi(K)}{||\pi^{(K)}||}$ as final ust 3 stort with 117" 11 = 1 and A column normalized; when don't need denominator at all

Why does this work? We show this under the assumption that the eigenvectors are orthonormal (Otherwise proof is more complex)

We can write $\underline{\tau}^{(0)} = C_1 \underline{\nu}_1 + C_2 \underline{\nu}_2 + \cdots + C_n \underline{\nu}_n$ for some $C_{1,n}, C_n, \omega$; with $C_1 \neq 0$, where $\underline{\nu}_1 = i^{\pm h}$ col of V $\underline{\pi}^{(k)} \propto A \underline{\pi}^{(k-1)} \propto A^2 \underline{\pi}^{(k-1)} \propto A^k \underline{\pi}^{(k)}$

$$= (V \wedge V^{\intercal})^{k} \underline{\mathcal{T}}^{(0)} = V \wedge^{k} V^{\intercal} \underline{\mathcal{T}}^{(0)} = V \wedge^{k} V^{\intercal} (c_{1} \underline{v}_{1} + \cdots + c_{n} \underline{v}_{n}) = V \wedge^{k} (c_{1} \underline{e}_{1} + \cdots + c_{n} \underline{e}_{n})$$

$$= c_{1} \lambda_{1}^{k} \underline{v}_{1} + \cdots + c_{n} \lambda_{n}^{k} \underline{v}_{n} = c_{1} \lambda_{1}^{k} (\underline{v}_{1} + \frac{c_{2} \lambda_{1}^{k}}{c_{1} \lambda_{1}^{k}} \underline{v}_{2} + \cdots + \frac{c_{n} \lambda_{n}^{k}}{c_{1} \lambda_{1}^{k}} \underline{v}_{n})$$

as $k \to \infty$, $\frac{\lambda^{i}}{\lambda^{i}} \to 0$ for $i \neq 1$

so
$$A^{k} \underline{\pi}^{(0)} \rightarrow c_{i} \lambda_{i}^{k} \underline{\nu}_{i}$$

$$\underline{\underline{T}^{(k)}} = \frac{A^{k}\underline{\underline{T}^{(k)}}}{\|A^{(k)}\underline{\underline{T}^{(k)}}\|_{2}} \longrightarrow \frac{c_{i}\lambda_{i}^{k}\underline{\nu}_{i}}{\|c_{i}\lambda_{i}^{k}\underline{\nu}_{i}\|} = \underline{\nu}_{i} \quad (\sigma_{i} - \underline{\nu}_{i})$$

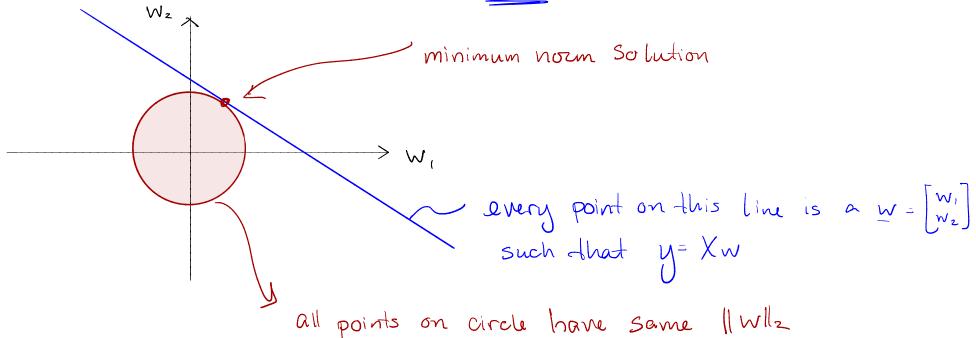
Extra Notes on Background (not for in-class Lectures)

We want to find w so that y=Xw. Imagina columns of X are linearly dependent > X has some

Singular values = 0. \Rightarrow so many w so that y=Xw

→ Minimum norm solution: min || w||2 such that y=Xw





Connection to Ridge Regression

If data had a little noise, we might choose min ||w||2 Such that ||y-Xw|| < small threshold

(2

Using optimization theory and Lagrange multipliers, we can show that

$$\min_{w} \|w\|_{2}^{2} + \frac{1}{\lambda} \|y - X_{w}\|^{2}$$

(3)

- 3 has the same solution as ((for the right choice of)
- 3 is Ridge regression