

Lecture 13

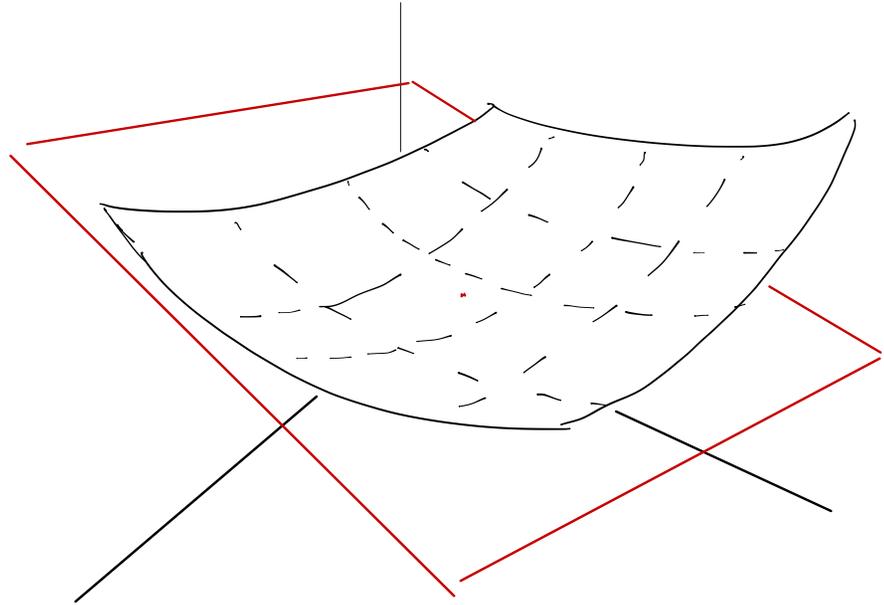
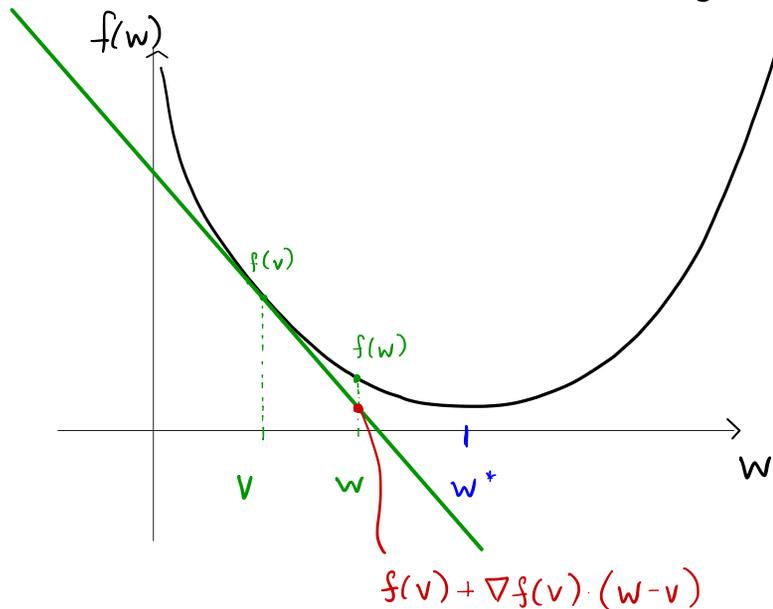
(Stochastic) Gradient Descent

Basic convex optimization

Goal: find $\underline{w}^* = \underset{\underline{w}}{\operatorname{argmin}} f(\underline{w})$ when f is a convex function.

A function is convex if $f(\underline{w}) \geq f(\underline{v}) + \nabla f(\underline{v})^\top (\underline{w} - \underline{v})$

- i.e. if it's \geq all its tangents



Ex. $f(\underline{w}) = \|\underline{y} - X\underline{w}\|_2^2$. We know $\underline{w}^* = (X^\top X)^{-1} X^\top \underline{y}$

Gradient descent finds this point iteratively.

- avoids computing matrix inverse
- generalizes to many other problems.

Gradient:

$$\text{if } f(\underline{w}) = \underline{y}^T \underline{y} - 2\underline{w}^T X^T \underline{y} + \underline{w}^T X^T X \underline{w}, \text{ then } \nabla_{\underline{w}} f = 0 - 2X^T \underline{y} + 2X^T X \underline{w}$$

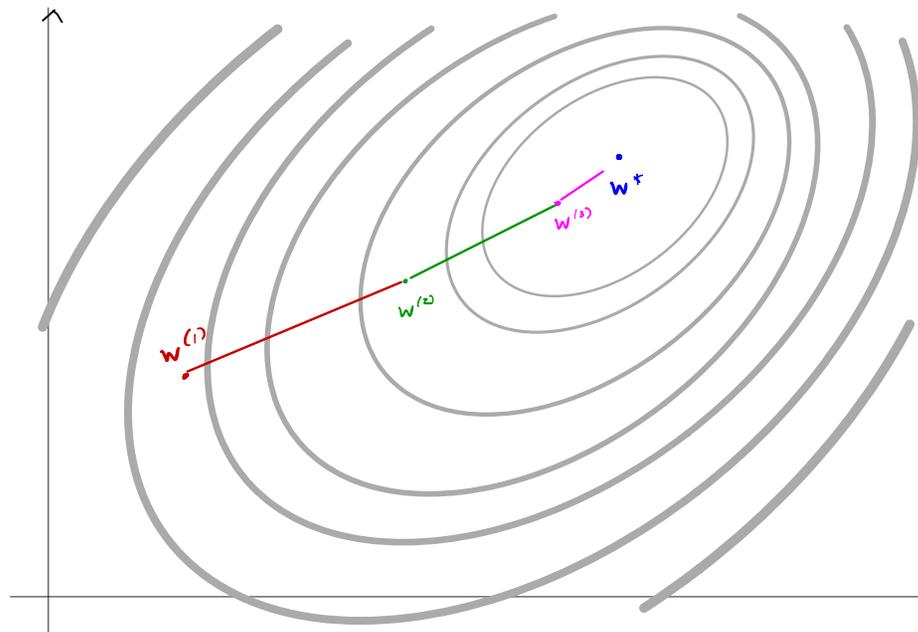
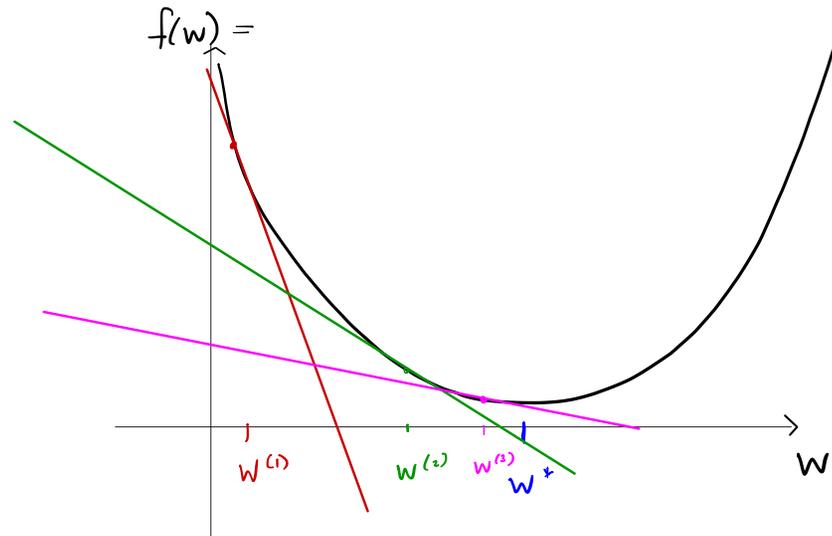
Gradient descent starts with initial guess $\underline{w}^{(1)}$, and then repeatedly takes steps in the direction of the negative gradient.

for $k = 1, 2, 3, \dots$

$$\begin{aligned} \underline{w}^{(k+1)} &= \underline{w}^{(k)} - 2\tau (X^T X \underline{w}^{(k)} - X^T \underline{y}) \\ &= \underline{w}^{(k)} - 2\tau X^T (X \underline{w}^{(k)} - \underline{y}) \end{aligned}$$

if $\| \underline{w}^{(k+1)} - \underline{w}^{(k)} \|_2 < \epsilon$, then BREAK

$\tau > 0$ is step size (sometimes called learning rate)



More generally:

want to minimize $f(\underline{w})$
initialize with $\underline{w}^{(1)}$
for $k = 1, 2, 3, \dots$

$$\underline{w}^{(k+1)} = \underline{w}^{(k)} - \tau \nabla_{\underline{w}} f |_{\underline{w} = \underline{w}^{(k)}}$$

if $\| \underline{w}^{(k)} - \underline{w}^{(k+1)} \| < \epsilon$, then
BREAK

Convergence of gradient descent for least squares

$$\begin{aligned}w^{(k+1)} &= w^{(k)} + \tau (X^T y - X^T X w^{(k)}) \\&= w^{(k)} + \tau X^T X [(X^T X)^{-1} X^T y - w^{(k)}] \\&= w^{(k)} - \tau X^T X (w^{(k)} - w^*)\end{aligned}$$

Optional

Subtract w^* from both sides:

$$\begin{aligned}\underbrace{w^{(k+1)}}_{\underline{e}^{(k+1)}} - w^* &= \underbrace{w^{(k)}}_{\underline{e}^{(k)}} - w^* - \tau X^T X (\underbrace{w^{(k)}}_{\underline{e}^{(k)}} - w^*) \\ \underline{e}^{(k+1)} &= \underline{e}^{(k)} - \tau X^T X \underline{e}^{(k)} \\ \Rightarrow \underline{e}^{(k+1)} &= (\mathbf{I} - \tau X^T X) \underline{e}^{(k)} = (\mathbf{I} - \tau X^T X) (\mathbf{I} - \tau X^T X) \underline{e}^{(k-1)} \\ &= (\mathbf{I} - \tau X^T X)^{k-1} \underline{e}^{(1)}\end{aligned}$$

We want $\underline{e}^{(k)} \rightarrow 0$ (ie $w^{(k)} \rightarrow w^*$) as $k \rightarrow \infty$

$$\|\underline{e}^{(k)}\| = \|(\mathbf{I} - \tau X^T X) \underline{e}^{(k-1)}\| \leq \underbrace{\sigma_{\max}(\mathbf{I} - \tau X^T X)}_{\text{this must be } < 1} \|\underline{e}^{(k-1)}\|$$

if $X = U \Sigma V^T$, then $(\mathbf{I} - \tau X^T X) = V V^T - \tau V \Sigma^T \Sigma V^T = V (\mathbf{I} - \tau \Sigma^T \Sigma) V^T$

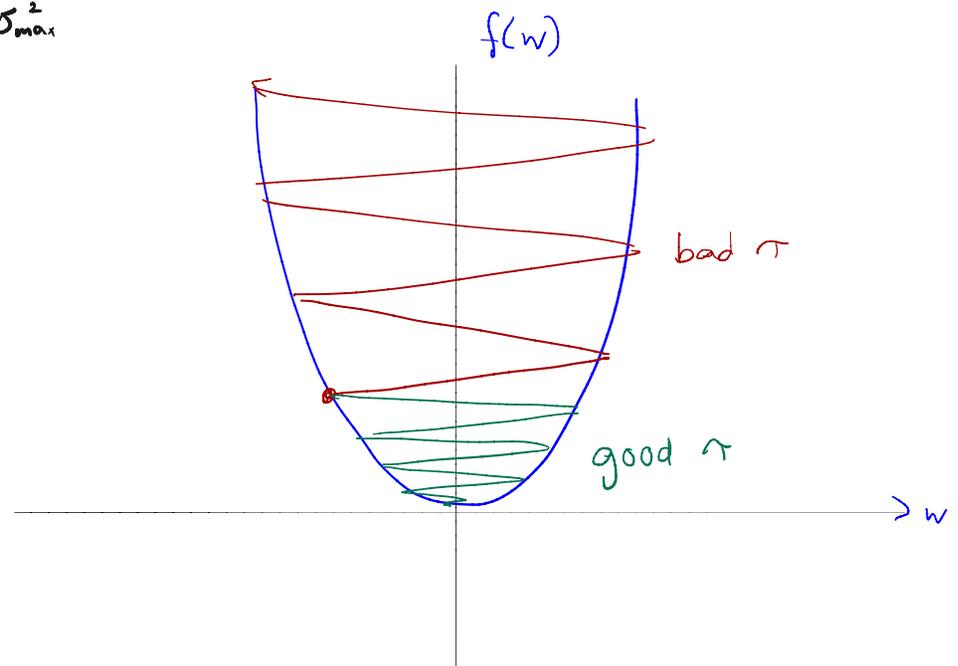
so max singular value of $\mathbf{I} - \tau X^T X$ is $\max_i |1 - \tau \sigma_i^2|$

This is < 1 if $|1 - \tau \sigma_{\max}^2(X)| < 1$ or if $\tau < \frac{1}{\sigma_{\max}^2(X)}$

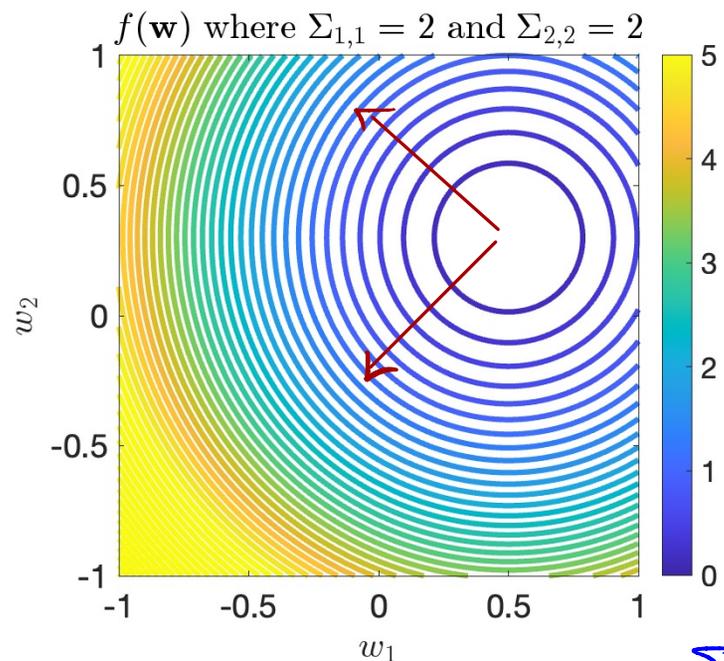
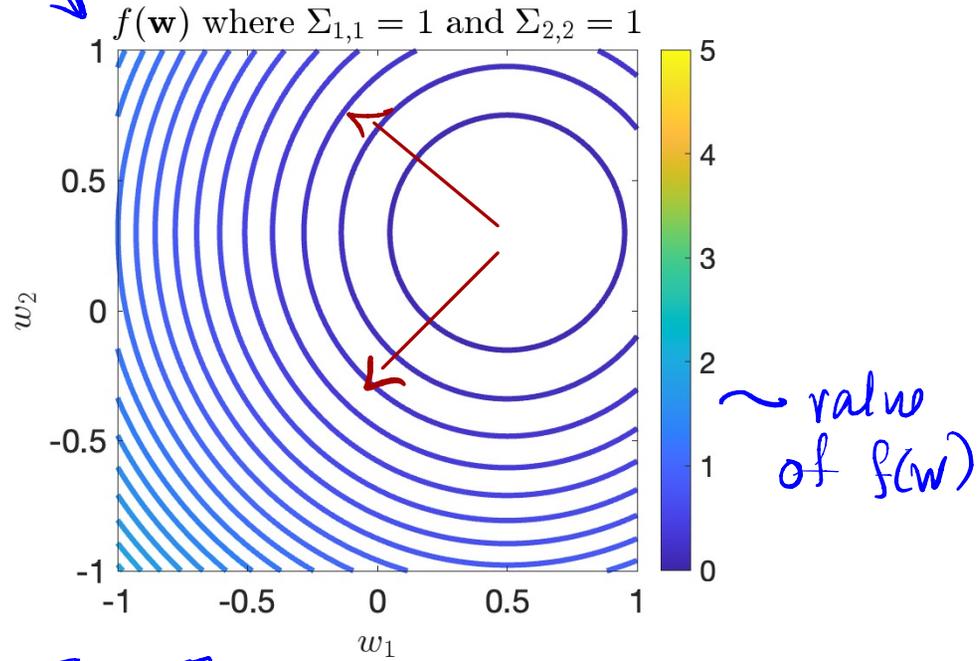
Step size τ needs to be small enough to ensure we find the minimum but not so small that it takes forever.

If f has more curvature, we need a smaller step size.

For convex problems like least squares, best $\tau \approx \frac{1}{\sigma_{\max}^2}$

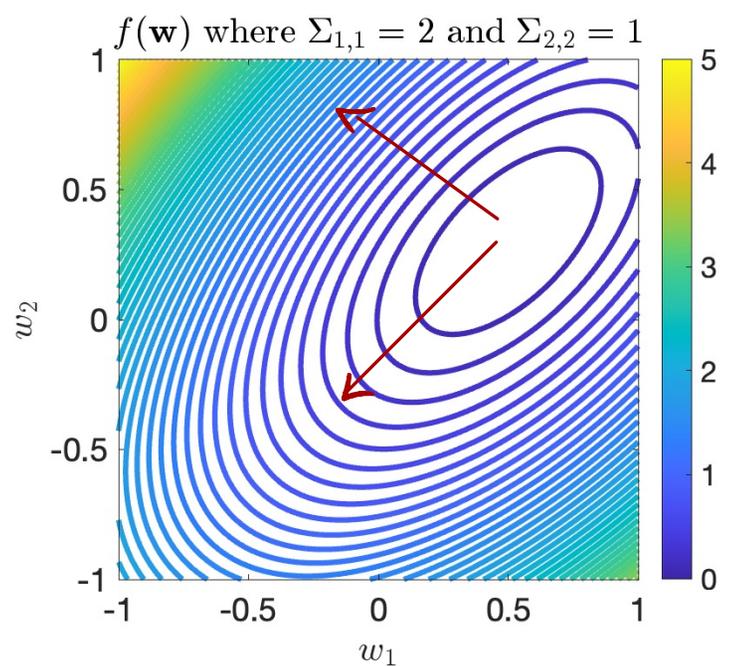
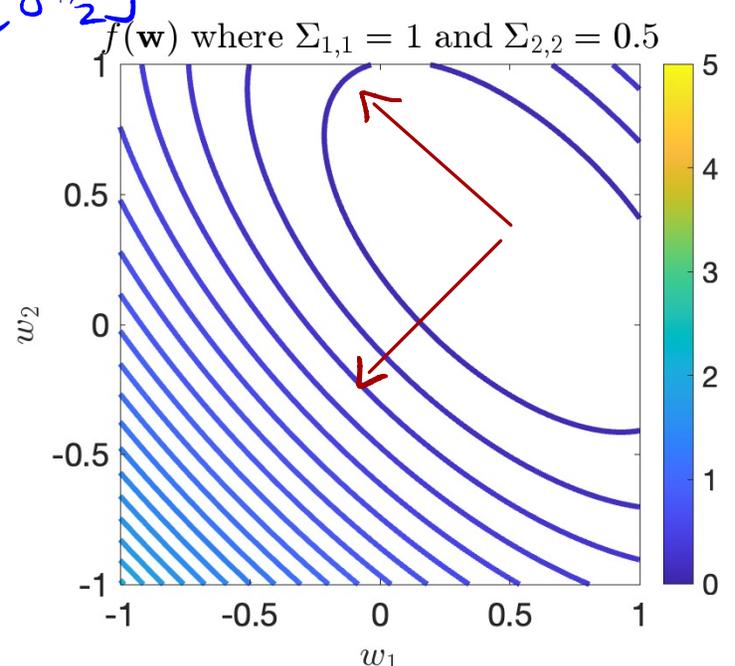


$$\Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \quad f(\mathbf{w}) = \| \mathbf{y} - \mathbf{X}\mathbf{w} \|_2^2, \quad \mathbf{X} = \mathbf{U}\Sigma\mathbf{V}^\top$$



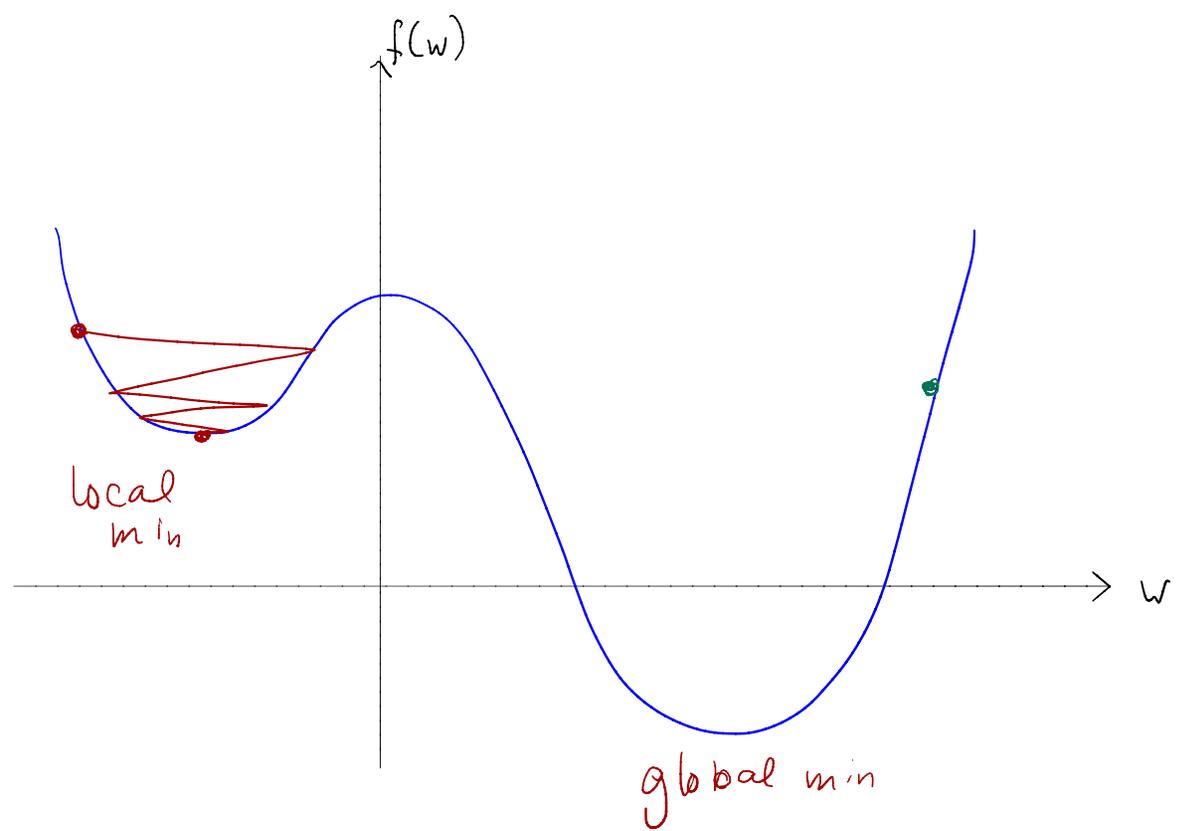
$$\Sigma = \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix}$$

$$\Sigma = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$$



$$\Sigma = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$$

gradient descent will find a global minimizer of a convex f no matter what we choose for $w^{(1)}$ — guaranteed. But if f is non-convex, the result of gradient descent will depend heavily on where we place $w^{(1)}$.



Gradient Descent for SVM - more efficient methods exist!

$$\hat{\underline{\alpha}} = \underset{\underline{\alpha}}{\operatorname{argmin}} \sum_{i=1}^n (1 - y_i \sum_j \alpha_j K(\underline{x}_i, \underline{x}_j))_+ + \lambda \sum_i \sum_j \alpha_i \alpha_j K(\underline{x}_i, \underline{x}_j)$$

$$= \underset{\underline{\alpha}}{\operatorname{argmin}} \underbrace{\sum_i (1 - y_i \underline{k}_i^T \underline{\alpha})_+}_{f(\underline{\alpha})} + \lambda \underline{\alpha}^T K \underline{\alpha} \quad \text{where } \underline{k}_i = i^{\text{th}} \text{ column of } K$$

$$\begin{aligned} \ell(\underline{w}) &= \sum_{i=1}^n (1 - y_i \underline{x}_i^T \underline{w})_+ \\ \nabla_{\underline{w}} \ell &= \sum_{i=1}^n \mathbb{I}\{y_i \underline{x}_i^T \underline{w} < 1\} (-y_i \underline{x}_i) \end{aligned}$$

$$\Rightarrow \nabla_{\underline{\alpha}} S = \sum_i \mathbb{I}\{y_i \underline{k}_i^T \underline{\alpha} < 1\} (-y_i \underline{k}_i) + 2\lambda K \underline{\alpha}$$

can solve for $\underline{\alpha}$ using gradient descent:

$\eta > 0$ = step size

$\underline{\alpha}^{(0)}$ = initial guess

for $i=1, 2, \dots$

$$\begin{aligned} \underline{\alpha}^{(i)} &= \underline{\alpha}^{(i-1)} - \eta \nabla_{\underline{\alpha}} f \Big|_{\underline{\alpha}^{(i-1)}} \\ &= \underline{\alpha}^{(i-1)} - \eta \left[\sum_{i=1}^n \mathbb{I}\{y_i \underline{k}_i^T \underline{\alpha}^{(i-1)} < 1\} (-y_i \underline{k}_i) + 2\lambda K \underline{\alpha}^{(i-1)} \right] \end{aligned}$$

if $\|\underline{\alpha}^{(i)} - \underline{\alpha}^{(i-1)}\| < \varepsilon$ then STOP

Stochastic Gradient Descent

Recall gradient descent:

$$\underline{w}^* = \underset{\underline{w}}{\operatorname{arg\,min}} f(\underline{w})$$

$$\underline{w}^{(k+1)} = \underline{w}^{(k)} - \tau \nabla f(\underline{w}^{(k)})$$

Imagine $f(\underline{w}) = \frac{1}{n} \sum_{i=1}^n f_i(\underline{w})$

e.g. if $f(\underline{w}) = \frac{1}{n} \|y - X\underline{w}\|_2^2$

$$= \frac{1}{n} \sum_{i=1}^n (y_i - \langle \underline{x}_i, \underline{w} \rangle)^2$$
$$\Rightarrow f_i(\underline{w}) = (y_i - \langle \underline{x}_i, \underline{w} \rangle)^2$$

Then Gradient Descent =

$$\underline{w}^{(t+1)} = \underline{w}^{(t)} - \tau \sum_{i=1}^n \nabla f_i(\underline{w}^{(t)})$$

Now:

@ iteration t . choose $i \in \{1, 2, \dots, n\}$

$$\underline{w}^{(t+1)} = \underline{w}^{(t)} - \tau \nabla f_i(\underline{w}^{(t)})$$

- each iteration easier/faster to compute
- need more iterations

How to choose i_t ?

A. cyclical ("Incremental Gradient Descent")

$$i_t = t \bmod n$$

e.g. $n=3$: i_t 's = 1, 2, 3, 1, 2, 3, 1, 2, ...

B. random permutations (common in practice)

every n rounds, reshuffle

e.g. $n=3$: i_t 's = 1, 3, 2, 3, 1, 2, 2, 1, 3, ...

epoch 1 epoch 2 epoch 3

C. choose i_t uniformly at random

"stochastic gradient descent" (easier to analyze than random perturbations)

$i_t \sim \text{unif}(1, \dots, n)$

e.g. $n=3$: i_t 's = 1, 3, 3, 2, 3, 1, 2, 2, 2, ...

note: expected value $\mathbb{E}[\nabla f_{i_t}(\underline{w})] = \nabla f(\underline{w})$

$$\text{Ex: } f(\underline{w}) = \frac{1}{n} \sum_{i=1}^n (y_i - \langle \underline{x}_i, \underline{w} \rangle)^2 + \lambda \|\underline{w}\|_2^2$$

$$f_i(\underline{w}) = (y_i - \langle \underline{x}_i, \underline{w} \rangle)^2 + \lambda \|\underline{w}\|_2^2$$

$$\text{check: } \frac{1}{n} \sum_{i=1}^n f_i(\underline{w}) = f(\underline{w})$$

$$\nabla f_i(\underline{w}) = -2(y_i - \langle \underline{x}_i, \underline{w} \rangle) \underline{x}_i + 2\lambda \underline{w}$$

$$\text{SGD: } \underline{w}^{(t+1)} = \underline{w}^{(t)} + 2\tau (y_{i_t} - \langle \underline{x}_{i_t}, \underline{w}^{(t)} \rangle) \underline{x}_{i_t} - 2\tau \lambda \underline{w}^{(t)}$$

Mini-batch SGD:

1. randomly divide n samples into K batches

eg., $n=12, k=3$

$$\mathcal{B}_1 = \{1, 4, 6, 10\}$$

$$\mathcal{B}_2 = \{3, 5, 9, 12\}$$

$$\mathcal{B}_3 = \{2, 7, 8, 11\}$$

2. for $k=1, 2, \dots, K$

$$\text{let } f_k(\underline{w}) = \frac{K}{n} \sum_{i \in \mathcal{B}_k} f_i(\underline{w})$$

compute batch gradient $\nabla_{\underline{w}} f_k$

$$\text{update } \hat{\underline{w}}^{(t+1)} = \hat{\underline{w}}^{(t)} - \tau \nabla_{\underline{w}} f_k(\hat{\underline{w}}^{(t)})$$

$t = t+1$

3. if $\|\hat{\underline{w}}^{(t)} - \hat{\underline{w}}^{(t-K)}\|_2^2 < \epsilon$, BREAK. otherwise, go to step 1.

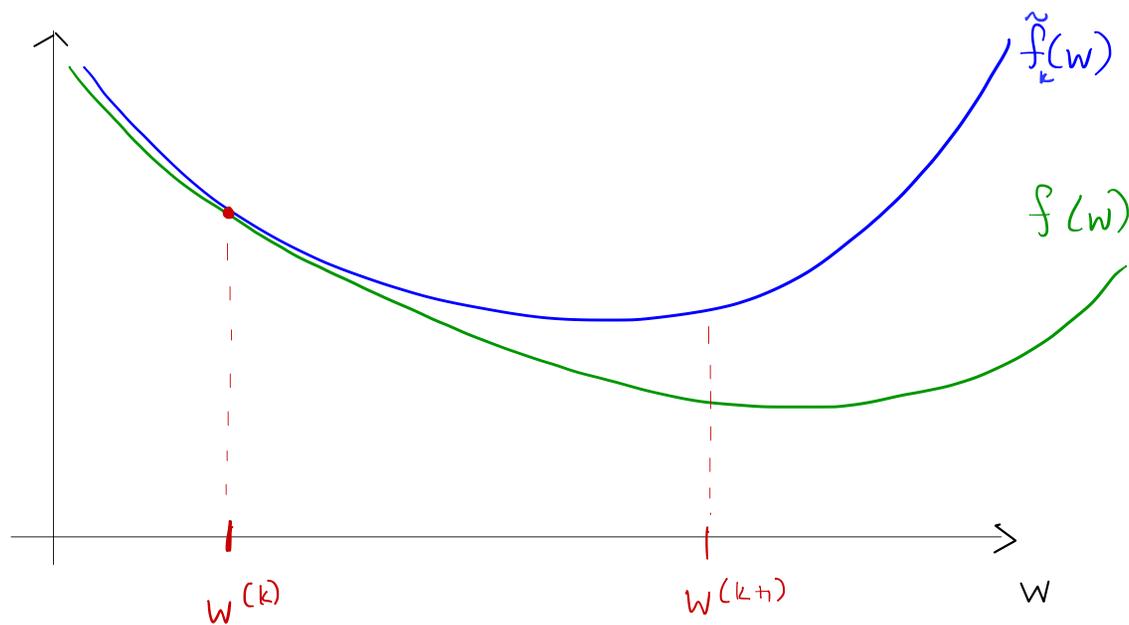
Optional
Notes

Where do gradient descent updates come from?

$$\begin{aligned}
 \text{Consider } f(w) &= \|y - Xw\|_2^2 = \|y - Xw^{(k)} + Xw^{(k)} - Xw\|_2^2 \\
 &= \|y - Xw^{(k)}\|_2^2 + 2(y - Xw^{(k)})^T X(w^{(k)} - w) + \|Xw^{(k)} - Xw\|_2^2 \\
 &\leq \underbrace{\|y - Xw^{(k)}\|_2^2}_{\text{same value regardless of } w} + 2(y - Xw^{(k)})^T X(w^{(k)} - w) + \underbrace{\|X\|_{op}^2}_{\text{maximum singular value of } X \text{ squared}} \|w^{(k)} - w\|_2^2
 \end{aligned}$$

Let τ be a step size, assume $\tau < \frac{1}{2\|X\|_{op}^2}$

$$\Rightarrow f(w) \leq C + 2(y - Xw^{(k)})^T X(w^{(k)} - w) + \frac{1}{2\tau} \|w^{(k)} - w\|_2^2 =: \tilde{f}_k(w)$$



$$f(w^{(k)}) = \tilde{f}_k(w^{(k)})$$

$$f(w) \leq \tilde{f}_k(w)$$

Choose $w^{(k+1)}$ to minimize \tilde{f}_k

aside: $\|Xw\|_2^2 \leq \|X\|_{op}^2 \|w\|_2^2$
 where $\|X\|_{op}$ - max singular value of X .
 because $\|Xw\|_2^2 = \|U\Sigma V^T w\|_2^2$
 $= \|\Sigma V^T w\|_2^2$
 $= \sum_i \sigma_i^2 (V^T w)_i^2$
 $\leq \sigma_{\max}^2 \sum_i (V^T w)_i^2$
 $= \sigma_{\max}^2 \|V^T w\|_2^2$
 $= \sigma_{\max}^2 \|w\|_2^2$

$$\hat{w}_{KH} = \underset{w}{\operatorname{argmin}} \quad 2(y - Xw^{(k)})^T X(w^{(k)} - w) + \frac{1}{2\tau} \|w^{(k)} - w\|_2^2$$

$$= \underset{w}{\operatorname{argmin}} \quad \underbrace{2\tau(y - Xw^{(k)})^T X(w^{(k)} - w)}_{=: v^T} + \|w^{(k)} - w\|_2^2$$

$$\text{let } v := 2\tau X^T(y - Xw^{(k)})$$

— independent of w !

$$= \underset{w}{\operatorname{argmin}} \quad 2v^T(w^{(k)} - w) + \|w^{(k)} - w\|_2^2$$

$$= \underset{w}{\operatorname{argmin}} \quad \|v + w^{(k)} - w\|_2^2 - \|v\|_2^2$$

$$\begin{aligned} = \underset{w}{\operatorname{argmin}} \quad \|v + w^{(k)} - w\|_2^2 &= w^{(k)} + v = w^{(k)} + 2\tau X^T(y - Xw^{(k)}) = \text{Gradient Descent Step !!!!!} \\ &= w^{(k)} - 2\tau X^T(Xw^{(k)} - y) \end{aligned}$$

Does this work?

Convergence for $f(\underline{w}) = \|X\underline{w} - y\|_2^2$

$$\text{want } \|X w^{(k+1)} - y\|_2^2 < \|X w^{(k)} - y\|_2^2$$

$$\text{recall } w^{(k+1)} = w^{(k)} - 2\tau X^T (X w^{(k)} - y)$$

$$\Rightarrow \|X w^{(k+1)} - y\|_2^2 = \|X (w^{(k)} - 2\tau X^T (X w^{(k)} - y)) - y\|_2^2$$

$$= \|X w^{(k)} - y - 2\tau X X^T (X w^{(k)} - y)\|_2^2$$

$$= \|X w^{(k)} - y\|_2^2 - 4\tau \underbrace{(X w^{(k)} - y)^T (X X^T (X w^{(k)} - y))}_{= \|X^T (X w^{(k)} - y)\|_2^2} + 4\tau^2 \underbrace{\|X X^T (X w^{(k)} - y)\|_2^2}_{\leq \|X\|_{\text{op}}^2 \|X^T (X w^{(k)} - y)\|_2^2}$$

$$\|X w^{(k+1)} - y\|_2^2 \leq \|X w^{(k)} - y\|_2^2 + 4\tau \left(\tau \|X\|_{\text{op}}^2 \|X^T (X w^{(k)} - y)\|_2^2 - \|X^T (X w^{(k)} - y)\|_2^2 \right)$$

$$= \|X w^{(k)} - y\|_2^2 + 4\tau \|X^T (X w^{(k)} - y)\|_2^2 (\tau \|X\|_{\text{op}}^2 - 1)$$

\Rightarrow if $\tau \|X\|_{\text{op}}^2 - 1 < 0$ ($\tau < \frac{1}{\|X\|_{\text{op}}^2}$), then $\|X w^{(k+1)} - y\|_2^2 < \|X w^{(k)} - y\|_2^2$

if $\underline{w}^{(1)} = 0$ and $\tau < \frac{1}{\|X\|_{\text{op}}^2}$, then

$$\underline{w}^{(k)} \longrightarrow (X^T X)^{-1} X^T y \text{ as } k \rightarrow \infty$$

$$(a-b)^2 = a^2 - 2ab + b^2$$
$$\|a-b\|^2 = \|a\|^2 - 2a^T b + \|b\|^2$$

$$a = X w^{(k)} - y$$
$$b = 2\tau X X^T (X w^{(k)} - y)$$

know: $\|X a\|_2 \leq \|X\|_{\text{op}} \|a\|_2$



a

$$\leq \|X\|_{\text{op}}^2 \|X^T (X w^{(k)} - y)\|_2^2$$

a