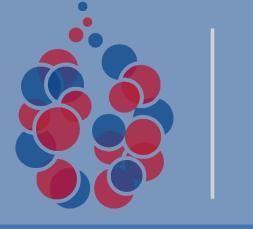
From the Structure of Experience to Concepts of Structure Anna Leshinskaya^{*} & Sharon L. Thompson-Schill University of Pennsylvania



C E N T E R F O R C O G N I T I V E N E U R O S C I E N C E

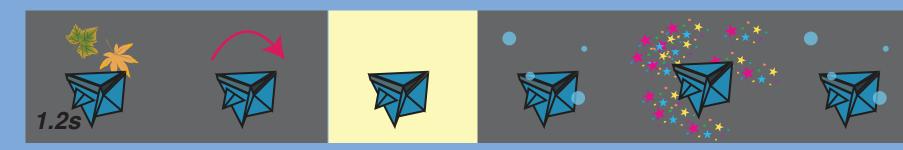
Many object categories (i.e., most artifacts) criticially rely on causal properties – one reason they include members with different surface features. Here we ask:

1. What aspect of experience do causal properties of objects come from? Can they be extracted from predictive information presented in naturalistic event streams?

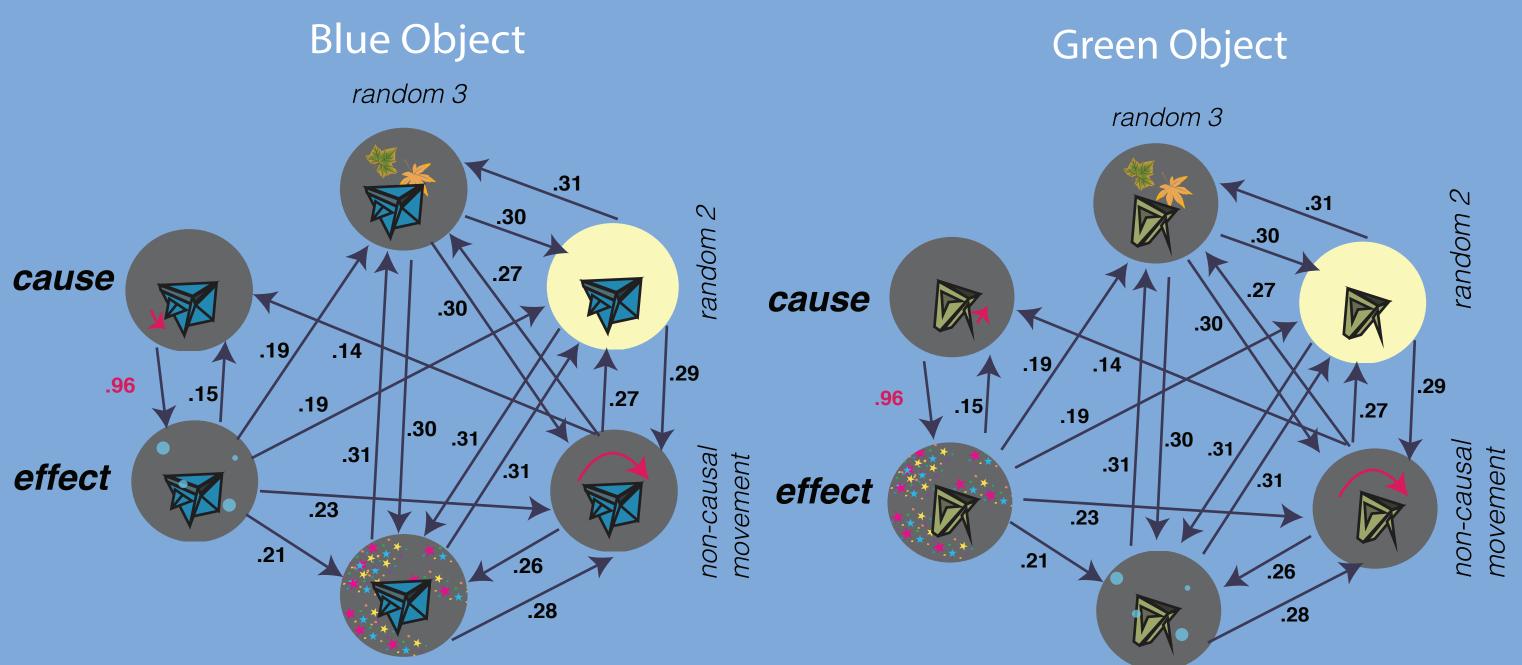
2. How spontaneously and automatically do we form generalizable causal categories?

Experiment 1: How do we assign causal properties to objects in naturalistic event streams?

Task: determine what each object causes.



Stimuli: sequence of 250 animated visual events order governed by markov chain.



other-object effect

Each object appeared with all ambient events, but only one of those events also depended on its movements.

Sentence Acceptability Measure

1. Causality: Effect Event "The green object seemed to cause the multi-colored stars to appear" 2. Causality: Other-Object Effect Event

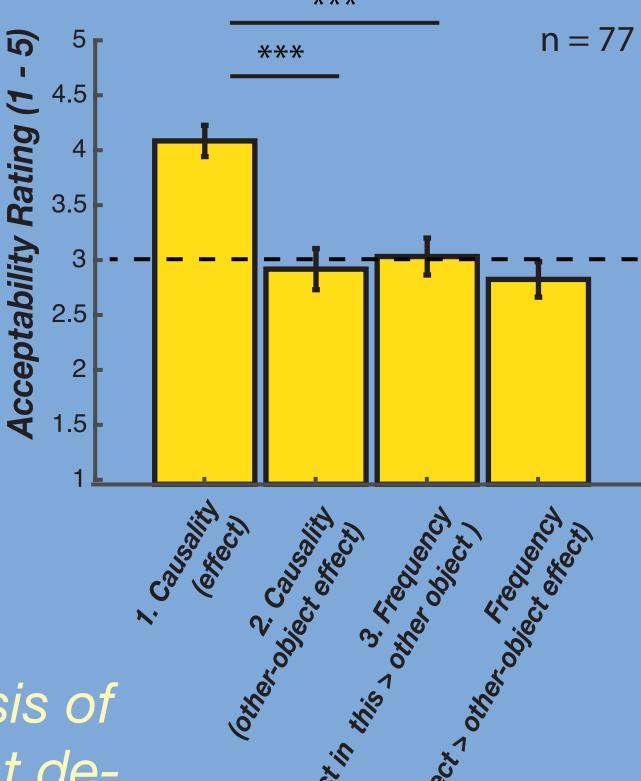
"The green object seemed to cause the bubbles to appear"

3. Frequency: Effect vs. Other-Object Effect Event

"When the green object was present, multi-colored stars appearing happened more often than when the blue object was present"

aennitely laise unsure aennitely true

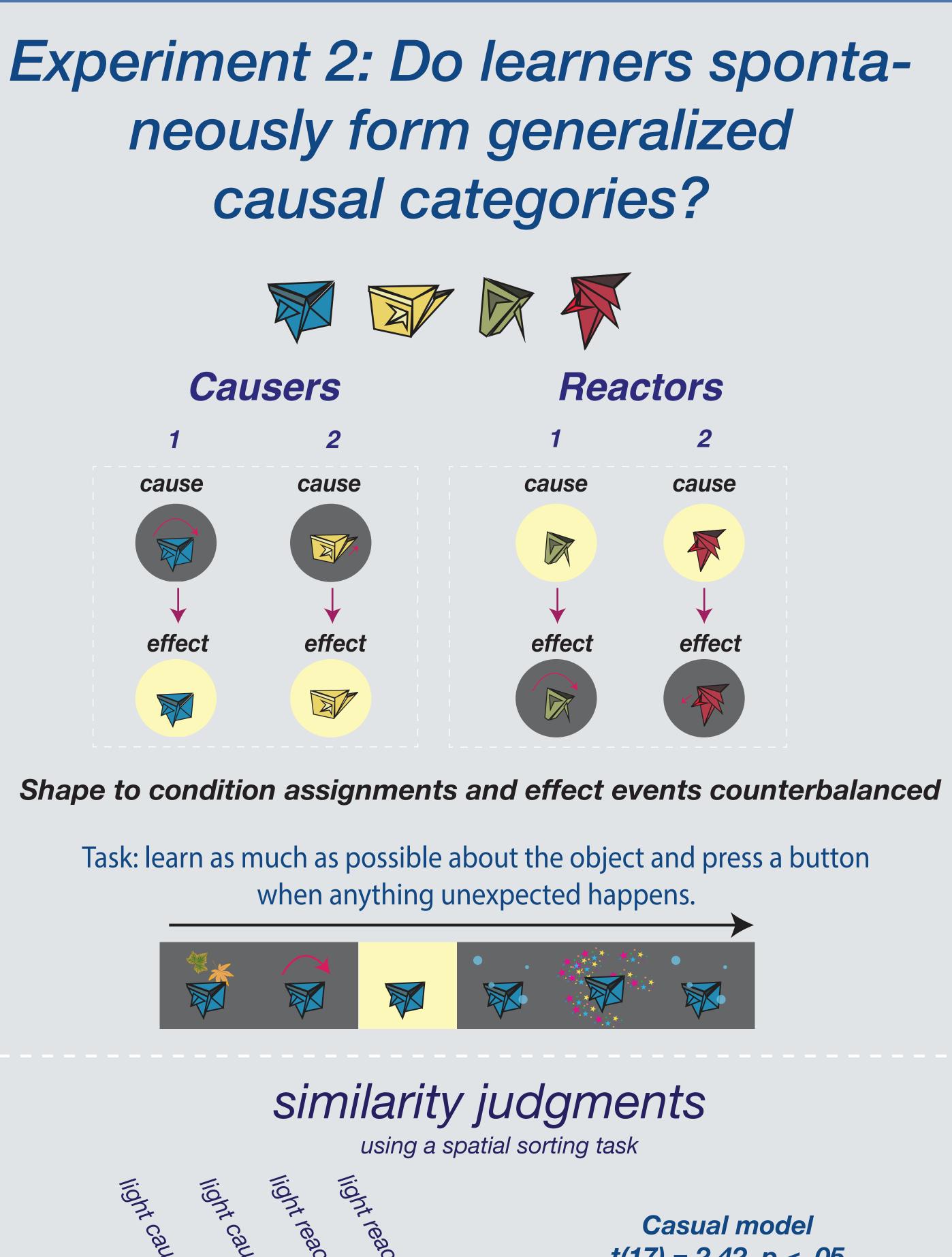
Causality can be assigned on the basis of higher-order event structure: an event dependency that depends on the object's presence.

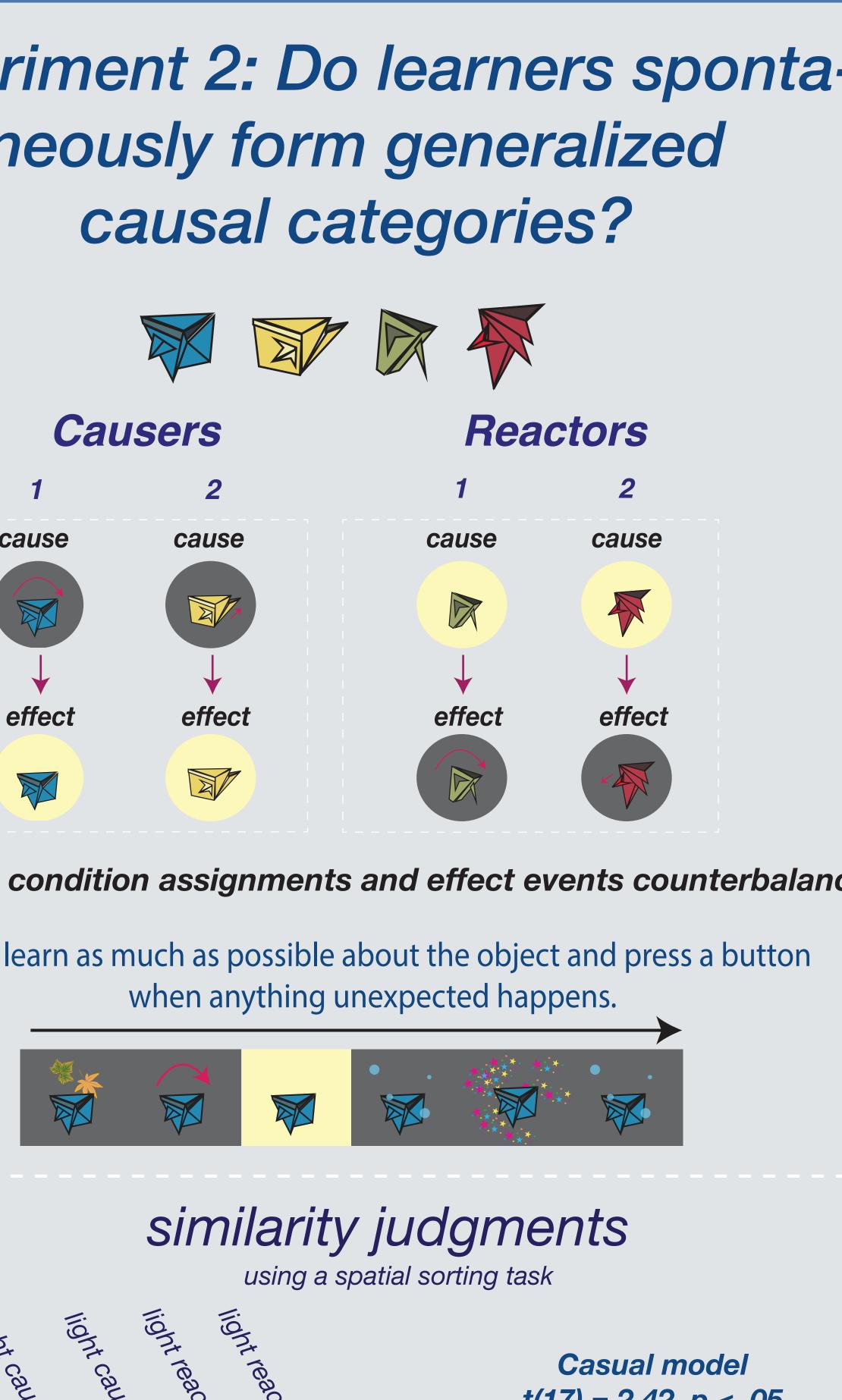


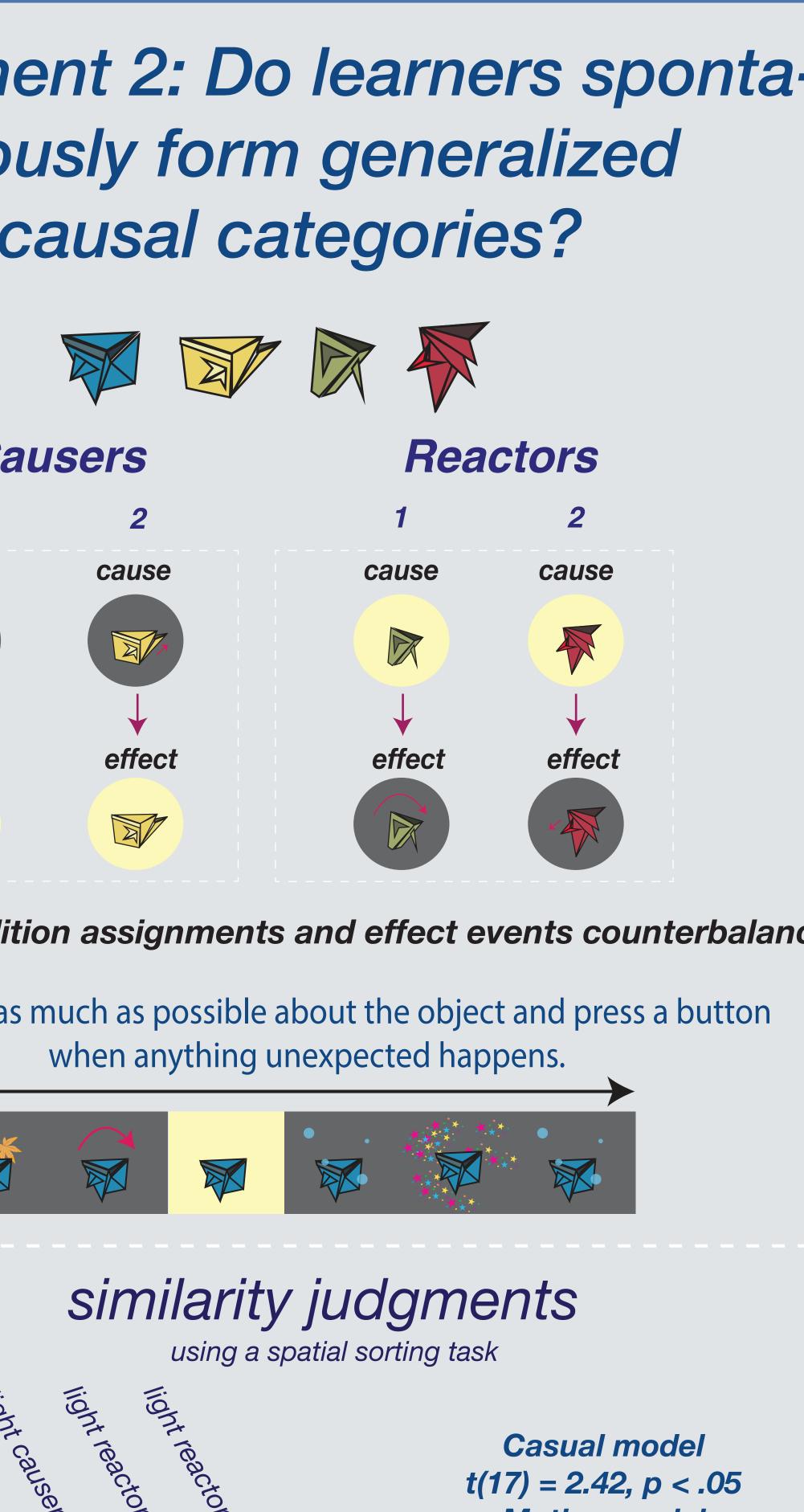
*alesh@sas.upenn.edu

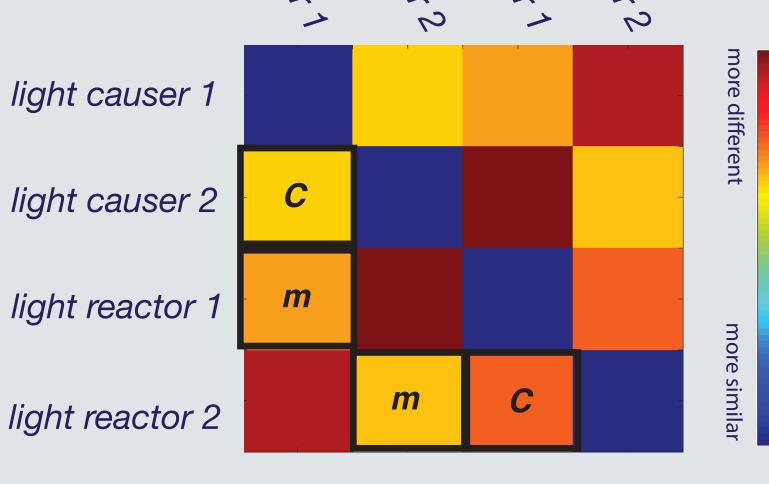
other-object effect





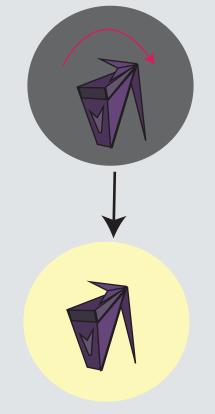






generalization test

which objects is this most similar to?



same motion & same causality different motion & same causality same motion & different causality different motion & different causality

> *Motion match F*(1,17) = 15.36, *p* < .001 Causal match F(1,17) = 5.52, p < .05

Participants used a combination of motion and causality/predictive structure to group objects.





Why is this important?

Predictive structure is a pervasive part of experience that can be extracted using straightforward learning mechanisms. But it can also be leveraged to gain abstraction, as predictive relations can be generalized across participating events and sensory features. Together, this could account for bottom-up abstraction of sensory experience and the $\frac{1}{2}$ formation of novel kinds generalizing across sensory features.

Motion model *t*(17) = 2.39, *p* <.05 Mixture model *t*(17) = 3.53, *p* < .01

Linear regression with motion model : c cells = 0, others = ; causal model : m cells = 0, others = 1, fit on individual data, betas subjected to t-test.

Linear regression with a single factor: mixture model: c cells = .5 and m cells = .5. others = 1

